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### DOE/NASA CONTRACTOR **REPORT**

DOE/NASA CR-161589

SOLAR HEATING AND COOLING SYSTEM INSTALLED AT COLUMBUS, OHIO -- FINAL REPORT

Prepared from documents furnished by

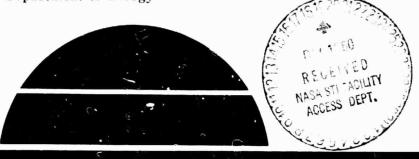
Columbus Technical Institute 550 E. Spring Street Columbus, Ohio 43216

Under DOE Contract EG-77-A-01-4090

Monitored by

National Aeronautics and Space Administration George C. Marshall Space Flight Center, Alabama 35812

For the ''. S. Department of Energy



(NASA-CR-161589) SOLAR HEATING AND COOLING SYSTEM INSTALLED AT COLUMBUS, OHIO Report (Dayton Univ., Ohio.) HC A DO/HF AU1 CUCL TOA N81-12544

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## U.S. Department of Energy



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### COLUMBUS TECHNICAL INSTITUTE SOLAR HEATING/COOLING DEMONSTRATION PROJECT

Final Report

Richard G. Coy R. Paul Braden

September 1980

University of Dayton Research Institute 300 College Park Ave. Dayton, Ohio 45469

Prepared for the

U. S. Department of Energy
National Solar Heating and Cooling Demonstration Program
Washington, DC 20545

National Aeronautics and Space Administration George C. Marshall Space Flight Center Marshall Space Flight Center, Alabama 35812

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#### PREFACE

The efforts reported herein were conducted by a project team assembled by the Columbus Technical Institute under the Department of Energy, Solar Heating and Cooling Demonstration Project for Nonresidential Buildings, Cooperative Agreement No. EG-77A 014090. This work, sponsored by the Department of Energy (DOE), was managed by the National Aeronautics and Space Administration (NASA), Marshall Space Flight Center, Huntsville, Alabama. The NASA manager is Mr. Douglas W. Westrope. This report covers work conducted during the period July 1976 through May 1980.

The authors, Mssrs. Richard G. Coy and R. Paul Braden,
University of Dayton Research Institute, would like to acknowledge
whe cooperation and contributions of all of the project team whose
members are: Columbus Technical Institute, Project Director,
Mr. Russell Jordan; McDonald, Cassell & Bassett, architects,
Mr. William R. McDonald; Lantz & Jones, structural consultants,
Mr. James Nebraska; Heapy & Associates, Mr. Richard Pearson;
University of Dayton Research Institute, solar system design
consultants, Dr. J. E. Minardi, Mr. R. K. Newman, Mr. D. H. Whitford,
and Mr. G. J. Roth; Owens-Illinois, Inc., solar collector
manufacturers, Mr. V. R. Daiga and Mr. R. E. Ford; and Elford,
Inc., general contractors, Mr. Tom Fitzpatrick.

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## SECTION 1 INTRODUCTION AND SUMMARY

In May 1977 the Columbus Technical Institute (CTI), 550
East Spring Street, Columbus, Ohio 43216, was selected as a recipient of a nonresidential solar energy demonstration contract awarded by the Department of Energy (DOE), in response to Program Opportunity Notice DSE-76-2. CTI proposed to include a solar energy heating/cooling system in its new classroom/administration building, designated as the "Phase V Building", which was approved for construction in 1976 by the Ohio General Assembly.

The Phase V Building (Franklin Hall) was built in the northeast quadrant of the CTI campus on land owned by the college, five blocks east of the Ohio State capital building. It has approximately 47,000 square feet of floor space on three levels. The solar heating and cooling system designed for the building utilizes about 4,096 square feet of advanced, evacuated, tubular collectors located on the roof. The collectors were built by the Owens-Illinois Company.

The overall program was managed by the National Aeronautics and Space Administration (NASA), Marshall Space Flight Center, Huntsville, Alabama, for DOE. The efforts discussed in this report were conducted by a project team, whose members are:

Mr. Russell Jordan, Administrative Assistant to the CTI President;

McDonald, Cassell & Bassett, architects; Lantz & Jones, structural consultants; Heapy and Associates, mechanical engineering consultants; University of Dayton Research Institute (UDRI), solar system design consultants; Owens-Illinois, solar collector manufacturer; Elford, Inc., general contractor; and Duckworth Plumbing Co., mechanical contractor. Major subcontractors include: Honeywell, Inc. - control subsystem; and Remtech Inc. - data acquisition subsystem.

An overview of the campus and pictures of the completed building are shown as Figures 1-1, 1-2, and 1-3. The system was acceptance tested and became operational in June 1979. Performance

data is being collected by the Solar Data Acquisition and Reduction (SDAR) System provided by CTI.

PICINAL PAGE 18

### COLUMBUS

### **TECHNICAL**

### INSTITUTE

A - Eibling Hall

B - Administration Building

C - Rhodes Hall

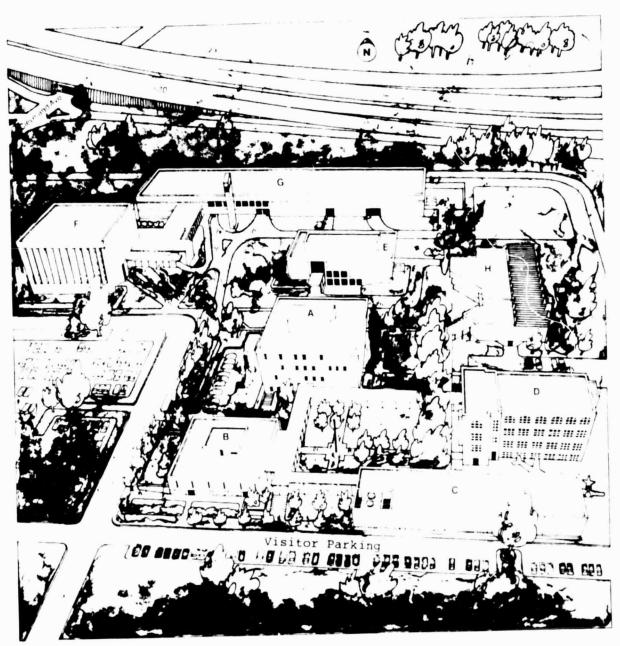
D - Acquinas Hall

E - Educational Resource Center

F - Health and Academic Facility

G - Business and Automotive Facility

H - Franklin Hall



Spring St.

Figure 1-1. Columbus Technical Institute. (Courtesy CTI)

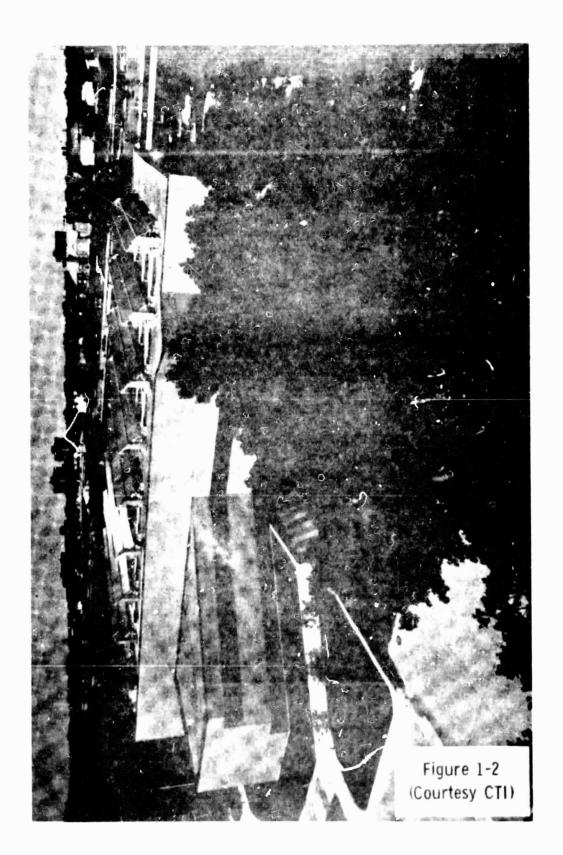


Figure 1 2. Aerial View of Franklin Hall.

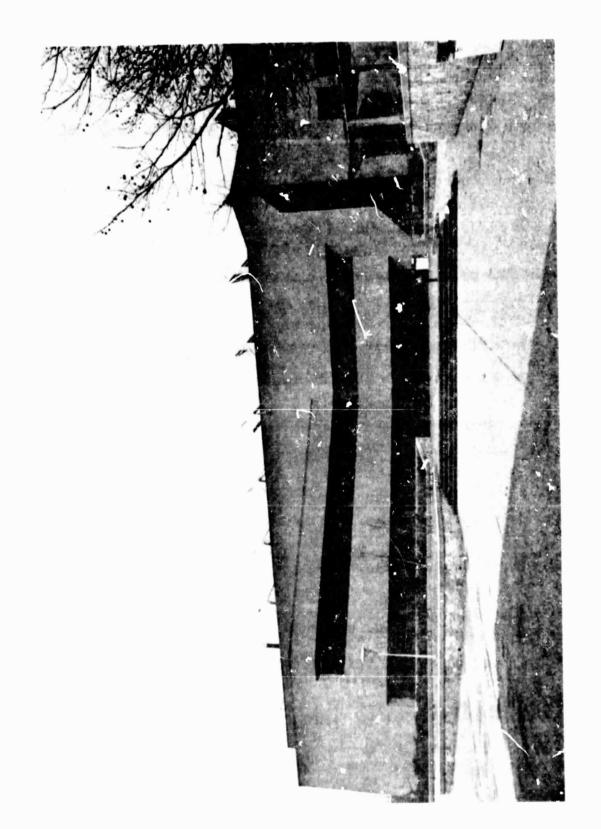


Figure 1-3. Ground View of Franklin Hall. (Courtesy CTI)

## SECTION 2 SITE AND SYSTEM DESCRIPTION

Franklin Hall of the Columbus Technical Institute is located in downtown Columbus, Ohio, at 40° North Latitude and 83° West Longitude (See Figure 2-1). The collectors, which face due South, are mounted at an angle of 45° measured from the horizontal.

The maximum number of solar collectors that could be mounted on the roof were used in the solar heating system. They should provide 79 percent of the total annual heating requirements of the building and 27 percent of the annual cooling (through absorption chilling). Each collector is 4 ft wide and 8 ft high. The collectors are arranged in 8 rows, 16 collectors per row. All pipe connections to the collectors are made through vertical chutes "or roof curbs" which penetrate the poured asphalt roof.

The collectors are identical to those installed in the Troy, Ohio Library earlier (reference DOE report UDR-TR-80-14, February 1980). They are normally nondrainable, but can be manually drained by partial disassembly if an emergency occurs, such as a catastrophic circulation pump failure during the periods of extremely low temperature and minimum sunlight. They are not drained in summer; hot water is circulated between the collectors and an insulated 5,000 gallon holding tank, passing through a water/lithium bromide absorption chiller to cool the building. If the solar collector temperature coes above 220°F, solar heat is dissipated through heat exchangers into the cooling tower which services the chiller system. In event of a building power failure, a manual valve allows city water to be used for emergency collector cooling.

The CTI solar heat/cooling system includes multiple modes of operation:

#### 1. HEATING ONLY

a. Solar collectors provide sufficient heat to meet the demand (See Figure 2-2).

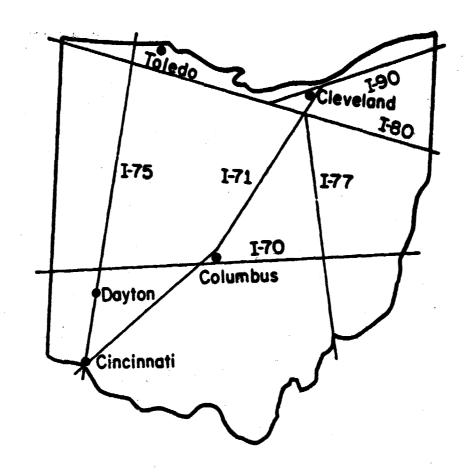


Figure 2-1. Location of Columbus, Ohio.

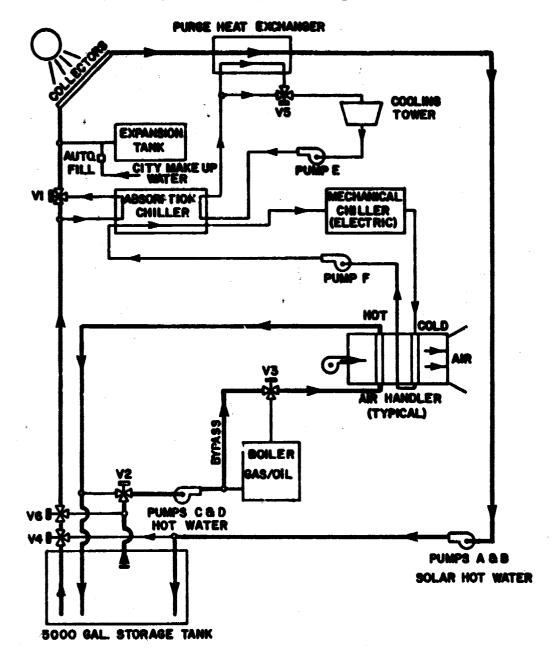


Figure 2-2. Schematic, Heating Mode. (Courtesy Heapy & Associates)

b. Supplementary heating is necessary (see Figure 2-3). To keep the boiler from supplying heat to the storage tank, valve V2 activates to allow the return water from the air handlers to return directly to the boiler, by-passing the storage tank. (Only the solar collectors put heat into the storage tank.) As soon as the solar collectors heat the storage tank to a temperature greater than the air handler return water temperature, valve V2 allows tank water to enter the boiler.

#### 2. COOLING ONLY

- a. So long as the storage tank water temperature remains between 170 and 220°F, Figure 2-4 applies. If the temperature drops below 170°F, the absorption chiller cannot operate. It goes off line and valve Vl opens to bypass the chiller. All chilling is accomplished by reciprocating chillers in series with the absorption machine. (This mode is not shown on a separate figure.)
- b. When the solar collector water temperature rises above 220°F, the excess heat is dumped into the Purge Heat Exchanger and Cooling Tower, as shown on Figure 2-5.

#### 3. MIXED MODES

Individual air handlers have the capability of calling for heating or cooling individually, so mixed modes are possible.

#### 4. OVERHEAT AND FREEZE PROTECTION MODES

The control logic for the solar heating/cooling system has built-in protection against overheat or freezing of the solar collectors, independent of the demand for heat or cold by the air handlers (see Appendix C, Honeywell Control System Drawings, sheet 5 of 10). They include:

• Collector overtemperature—If the collector discharge temperature exceeds 220 to 230°F, the cooling tower loop (pump E, purge heat exchanger and cooling tower, Figure 2-5) activates to reduce the discharge temperature below 220°F.

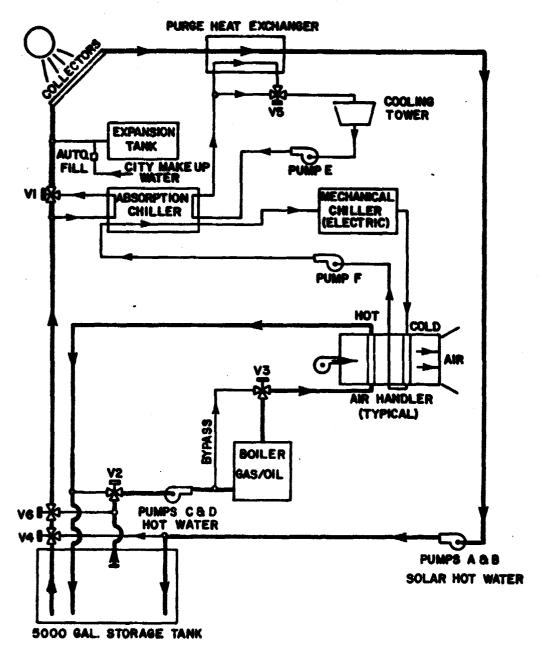
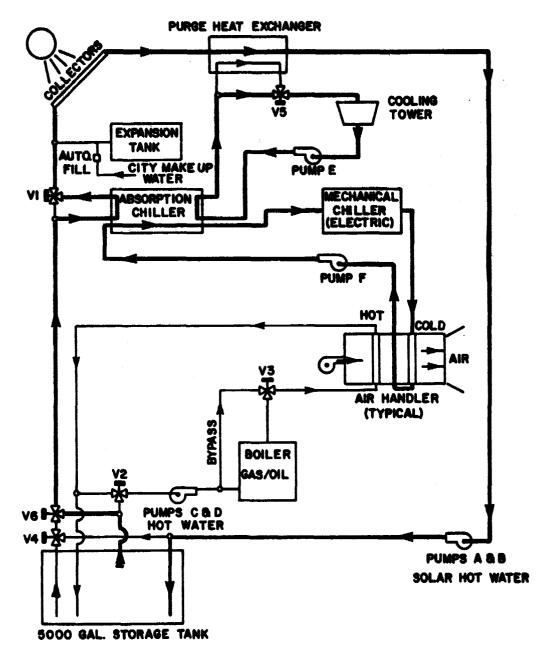
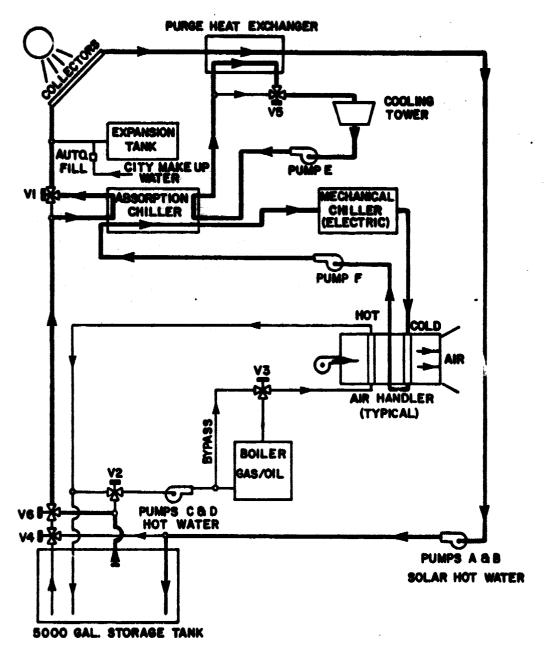


Figure 2-3. Schematic, Heating Mode, Extreme Cold. (Courtesy Heapy & Associates).



(SOLAR COLLECTOR WATER TEMPERATURE BETWEEN 170° AND 220° F)
Figure 2-4. Schematic, Cooling Mode, Low Collector Temperature.
(Courtesy Heapy & Associates)



#### (SOLAR COLLECTOR WATER TEMPERATURE EXCEEDS 220°F)

Figure 2-5. Schematic, Cooling Mode, High Collector Temperature. (Courtesy Heapy & Associates)

• Collector freeze protection--If the outside air temperature drops below 40°F, pumps A and B cycle on for one-half hour every four hours. If the collector discharge temperature drops below 40°F, valve V4 is positioned such that pumps A and B (Figure 2-3) pump water continuously through the collectors from the storage tank until the discharge temperature reaches 60°F. Since the control system does not permit the boiler to provide heat to the storage tank, the heat necessary to raise the collector temperature must come from the storage tank and its surroundings. If the collector discharge temperature continues to drop (to 38°F or less) a remote bell in Aquinas Hall rings until the condition is corrected. Maintenance personnel must open valves to introduce city water into the collector water loop to raise its temperature above 40°F.

#### 5. EMERGENCY MODES

If water circulation through the solar collectors is interrupted for periods greater than 30 minutes or so when solar insolation is high, overheat will occur; the water trapped in the collectors will turn to steam, and escape from pressure relief valves at the outlet of each collector row (see Figure 3-1, page 28, and Section 3.2, page 29). To control the rate of steam release and decrease the collector temperature, it is necessary to cover the collectors with black Visqueen, and keep them covered until the water circulation problem is corrected. This emergency condition has already occurred in the Franklin Hall System, and was handled well by maintenance personnel.

If water circulation stops and there is no solar insolation (heavy cloud conditions and arctic-type cold), the collectors must be manually drained, per Section 3.2, page 29.

#### 2.1 SOLAR COLLECTOR SUBSYSTEM

One-hundred-twenty-eight SUNPAK<sup>TM</sup> solar collector modules with shaped reflectors are installed on this project. These collectors are advanced, high performance, evacuated, tubular collectors manufactured by Owens-Illinois, Inc. Each module

consists of 24 individual collector tubes with an integral manifold as shown in Figure 2-6 through 2-10 and occupies approximately 32 square feet in the assembled configuration. The effective area of the standard SUNPAK<sup>TM</sup> module is 27.4 square feet, which is used as the basis for describing collector performance. The effective collector area available on this project with 128 modules is 3507 square feet. A complete description of the Owens-Illinois, Inc. collector is presented in Appendix B, SUNPAK<sup>TM</sup> Solar Collector Installation Service and Operating Manual.

#### 2.2 STORAGE SUBSYSTEM

The capability of storing excess solar energy is provided by an insulated 5,000 gallon steel tank. The tank is installed below ground, adjacent to the northwest corner of the building. Construction and installation details of the tank are shown in Appendix A.

#### 2.3 DISTRIBUTION AND CONTROL SUBSYSTEM

This subsystem includes all piping, pumping, and heat transfer components as well as the required control logic for the efficient operation of the entire system. The system schematic presented in Figure 2-11 shows all major components of the distribution subsystem as well as the control valves and sensors. All piping in the distribution system is installed within the building.

The pneumatic control subsystem was designed and built by Honeywell, Inc. It meets the demand for heat in a given sector of the building by first using the energy in the storage tank and collector system, then calling for back-up heat from the natural gas/oil boiler. Details of the control subsystem are shown in Appendix C.

Six three-way pneumatic valves control the flow of water within the solar system. They are shown on Figure 2-11 as Vl

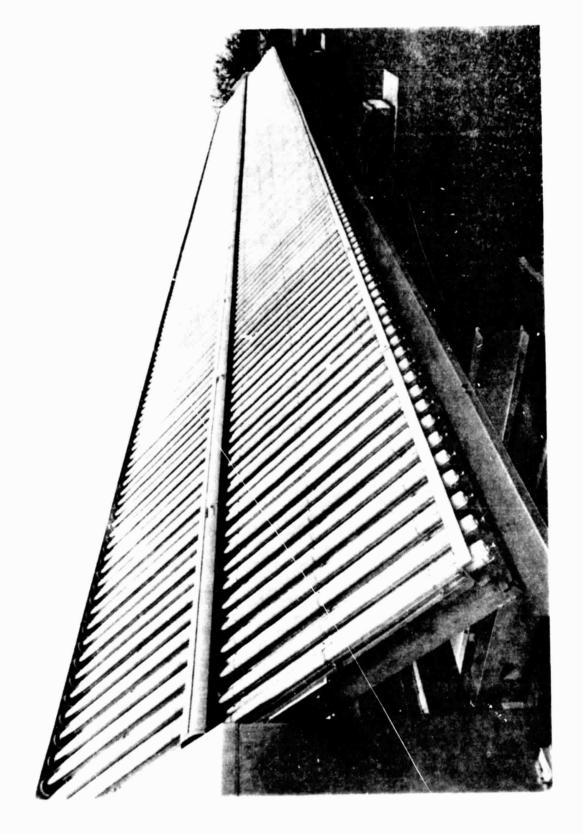


Figure 2-6. CTI Collectors on Roof. (Courtesy CTI)

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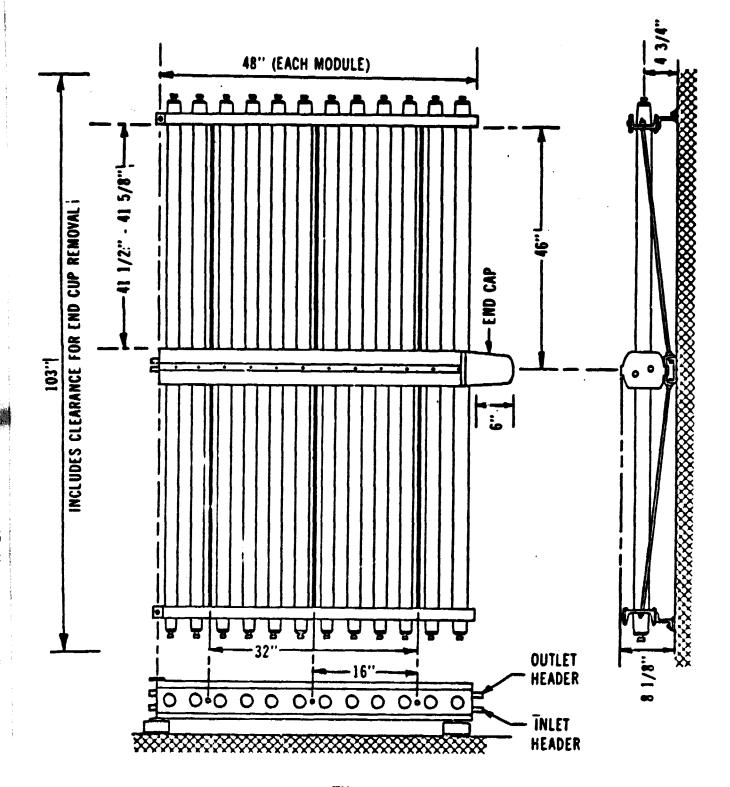
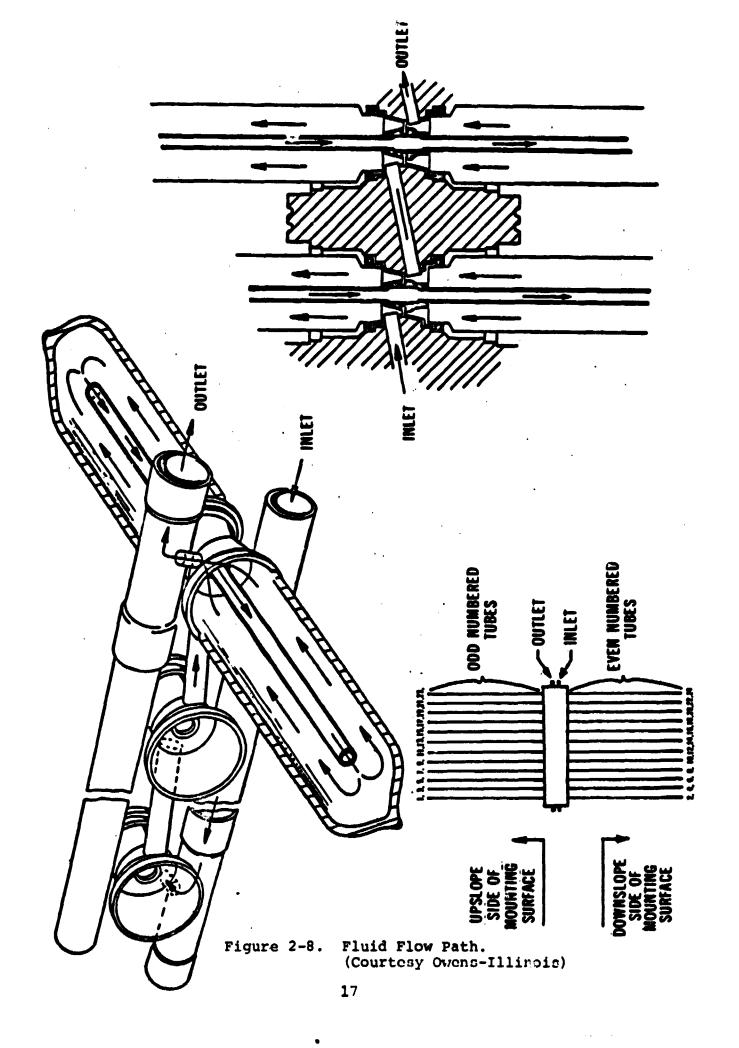


Figure 2-7. SUNPAK TM COLLECTOR PICTORIAL. (Courtesy Owens-Illinois)



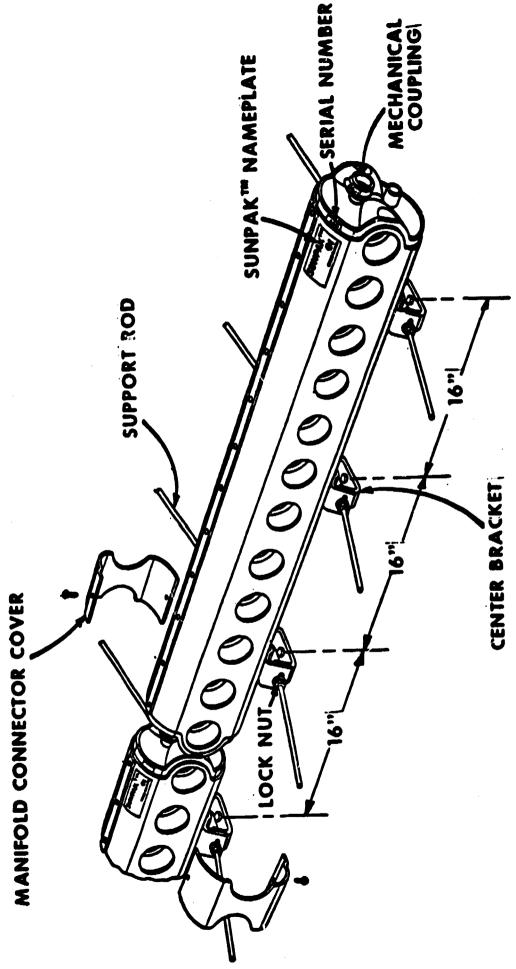


Figure 2-9. Manifold Assembly. (Courtesy Owens-Illinois)

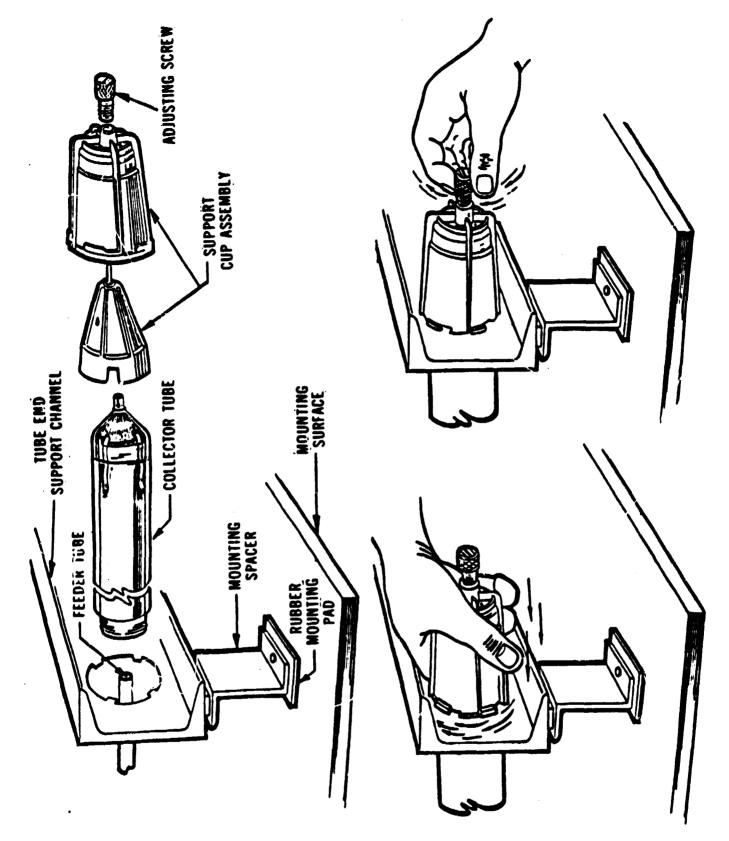


Figure 2-10. Collector Tube Installation. (Courtesy Owens-Illinois)

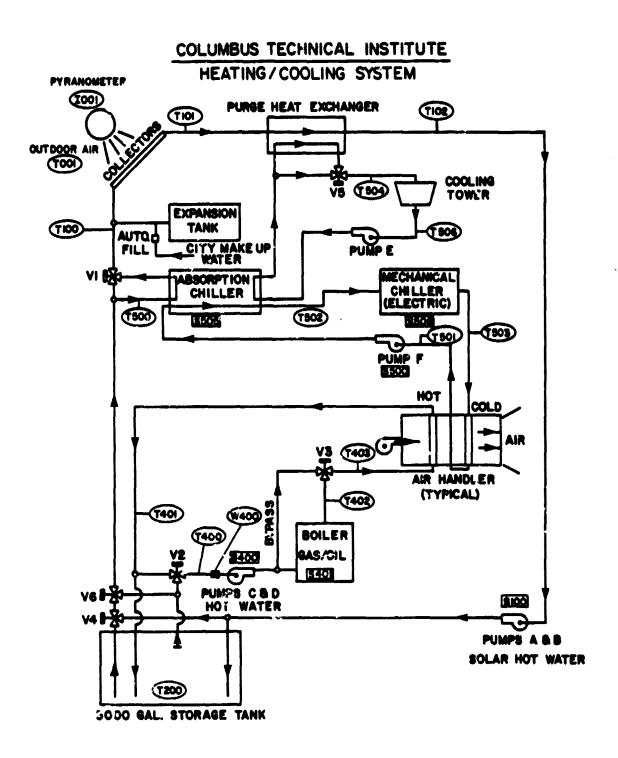


Figure 2-11. Major System Parameters & Control Valves. (Courtesy Heapy & Associates)

through V6. Their functions are:

- 1. V1 Bypass the absorption chiller when no cooling is required.
- 2. V2 Bypass the storage tank if the return water temperature from the air handlers is greater than the storage tank temperature.
- 3. V3 Bypass boiler unless air handler hot water loop temperature is too low to heat the building.
- 4. V4 Bypass storage tank if tank temperature is greater than water temperature in the solar collectors.
- 5. V5 Bypass the purge heat exchanger because water temperature is below 220°F. (The cooling tower is a component of the building cooling system, and is used by the solar system only when the solar hot water temperature is excessive).
- 6. V6 Allow hot water to be drawn from the top of the storage tank when in the cooling mode.

#### 2.4 DATA COLLECTION AND LOBBY DISPLAY INSTRUMENTATION

The Franklin Hall solar heating system is equipped with minimum instrumentation to assess the overall performance of the system. This instrumentation was purchased by CTI under private contract in 1977.

The Solar Data Acquisition and Reduction (SDAR) system was built by Remtech, Inc., of Huntsville, Alabama, for the CTI installation, with the cooperation of Heapy and Associates. The system is built around a Digital Equipment Corporation LSI \$11/2 general-purpose 16-bit microcomputer processor module. The system will interrogate up to 32 analog inputs, convert them to engineering units, calculate heat flows through the system, display the results on a video monitor (mounted in the lobby and provided on-demand), and record the system parameters on a cassette tape.

The data is also retrievable remotely via telephone modem. The inputs to the system are shown as Figure 2-12, the required solar system constants as Figure 2-13, and the system performance calculations as Figure 2-14.

A sample lobby terminal display is shown as Figure 2-15. Details on SDAR are shown in Appendix D.

Channel	Sensor	Variable	Function
1	n	1001	Incident solar energy
2	T15	T001	Outdoor air temperature
3	T6	T100	Collector inlet/Absorbtion chiller outlet
4	Tì	T101	Collector outlet/Purge inlet
5	T12	T102	Purge outlet
6	R1	\$100	Collector pump status
7	T2	T200	Storage tank temperature
8	T7	T400	Storage outlet/Boiler inlet
9	T3	T401	Heating loop return
10	T8 <sub>.</sub>	1402	Boiler outlet
11	T4	T403	Heating loop supply
12	R2	\$400	Heating loop pump status
13	R3	S401	Boiler status
14	FM1	W400	Heating loop flow rate
15	TII	T500	Absorbtion chiller inlet
16	T14	T501	Cooling loop return/Absorbtion chiller load inlet
17	Т9	T502	Absorbtion chiller load outlet/Electric chiller inlet
18	T10	T503	Cooling loop supply/Electric chiller load outlet
19	T13	T504	Cooling tower inlet
20	T5	T506	Cooling tower outlet
21	R4	\$500	Cooling loop pump status
22	R5	S505	Absorbtion chiller status
23	R6	S506	Electric chiller status

Figure 2-12. Input Channel Assignments. (September 1979) (Courtesy Remtech)

```
AREA - Collector area -(3507.2 sq. ft.)
W100 - Collector loop flow rate -(60 GPM)
EP101 - Collector pump operating energy -(11.5 KW)
W400 - Flowmeter conversion data -(1 pulse/10 gal 350 max - 100 min)
EP400 - Heating loop pump operating energy -(31 KW)
W500 - Cooling loop flow rate -(300 GPM)
EP500 - Cooling loop pump operating energy -(15.5 KW)
EP504 - Cooling tower operating energy used by absorption chiller -(3.46 KW)
EP505 - Absorption chiller operating energy -(3.8KW)
W505 - Absorption chiller load flow rate -(1606 GMP)
W506 - Electric chiller load flow rate - (3006 GPM)
HTCOST - Cost per Btu of conventional heating-($7.49/1 x 106BTU)
CLCOST - Cost per But of conventional cooling-($2.00/1 x 106BTU)
MININ - Insolation required for useful solar collection -(20 BTU/sq.ft.)
```

\* Data in ( ) are the constants in program supplied on September 1979.

These constants may be changed by the use of Task 4 in the SDAR System Task List.

Figure 2-13. Required Solar System Constants. (Courtesy Remtech)

Solar energy available:	Q001= \int 1001 \cdot AREA \cdot dt
Solar energy collected:	Q100= \int (T101-T100) \cdot \text{W100-S100-dt}
Solar energy purged:	Q101= \int (T101-T102) \cdot \text{W100} \cdot \text{dt}
Solar collector operating energy:	Q102= \int EP101 \cdot \s100 \cdot \dt
Collector efficiency:	N100=(Q100/Q001)
Solar energy to storage:	Q200=Q100-Q101-Q500
Solar energy to heating load:	Q400=Q402-Q401
Auxiliary energy to heating load:	Q401=\int (T402-T400) \cdot \text{W100 \cdot S401 \cdot dt}
Heating load:	Q402=\int (T403-T401) \cdot \wd00 \cdot \square \delta \text{400} \cdot \delta \text{dt}
Solar heating loop operating energy:	Q403=\int EP400 \cdot (S400-S401) \cdot dt
Solar energy to absorption chiller:	Q500= \int (T500-T100) \cdot \text{W100-S505-dt}
Cooling load:	Q502=\(\int(T501-T503)\cdot\) \W500\cdot\
Absorption chiller operating energy:	Q503=\int (EP500+EP504+EP505) \cdot
Absorption chiller load:	Q505= $\int (T501-T502) \cdot W505 \cdot S505 \cdot dt$
Electric chiller load:	Q506=\int (T502-T503) \cdot \w506 \cdot \s506 \cdot \dt
Absorption chiller coefficient of performance:	N500=Q505/(Q503+Q102)
Energy saved:	Q606=Q400+Q500-Q102-Q403-Q503
Dollars saved:	D606= (Q400-Q403-(Q102-Q400)/(Q400+Q500)) • HTCOST+ (Q500-Q503-(Q102-Q500)/(Q400+Q500)) • CLCOST
Hours of useful solar energy:	S001= 0.0 if I001 MININ
	$H001 = \int S001 dt$

Figure 2-14. System Performance Calculations. (Courtesy Remtech)

	\$ 100.00 \$ 1000.00 \$ 1000.00		178.9 F 200.5 F 179.0 F 66.2 F 88.2 Btu/sq Ft Hour
	1.232E+05 Btu 3.002E+06 Btu 9.079E+07 Btu	USEABLE SOLAR ENERGY AVAILABLE 10.2 Hours 261.6 Hours 1257.3 Hours	SYSTEM PARAMETERS 178.9 F 200.5 F 179.0 F 66.2 F 88.2 Btu/sq Ft Hour
26 AUG 79 11:30 A.M.	YESTERDAY LAST 30 DAYS 3.002 LAST 365 DAYS 9.079	***************************************	COLLECTOR INLET TEMPERATURE COLLECTOR OUTLET TEMPERATURE STORAGE TANK TEMPERATURE OUTDOOR AIR TEMPERATURE SOLAR INTENSITY COLLECTOR PUMP ON BOILER OFF ELECTRIC CHILLER OFF ***********************************

Figure 2-15. SDAR Display on Lobby Terminal. (Courtesy Remtech)

### SECTION 3 SYSTEM OPERATION

The solar heating system operational controls have been interfaced with the standard Heating, Ventilating, and Air Conditioning (HVAC) controls. The operation of this combined solar heating-HVAC system is keyed to the solar collector output temperature; the ambient air temperature; temperature within the solar distribution/storage system and standardized air handling units; and the building space thermostats. Operation of the combined system is automatic and should require no action during operation except for adjusting or setting building space thermostats, or emergency conditions such as power or component failures, system leaks, and extreme low temperature. (Ref. Appendix C for detailed operation and drawings.)

#### 3.1 FILLING AND DRAINING PROCEDURES

Make-up water is provided to the solar system by an automatic fill valve at the expansion tank. Make-up of the water in the boiler/air handler loop is accomplished indirectly through the 5000 gallon storage tank. The cooling tower and mechanical chiller loops also have water make-up valves which are components of the conventional HVAC system.

For initial fill, the solar hot water loop is equipped with manual valves at the inlet and outlet to the solar hot water pumps A & B and bleed valves in the roof curbs (see Figure 3-1). Regardless of the position of valves V4 and V6, the 5000 gallon storage tank will fill from city water pressure, and water will enter the collectors regardless of the position of valve V1.

As a safety precaution, the solar collectors were covered with black Visqueen until they were adequately filled with water so the individual collector tubes would not experience high thermal shock as cold city water entered the tubes.

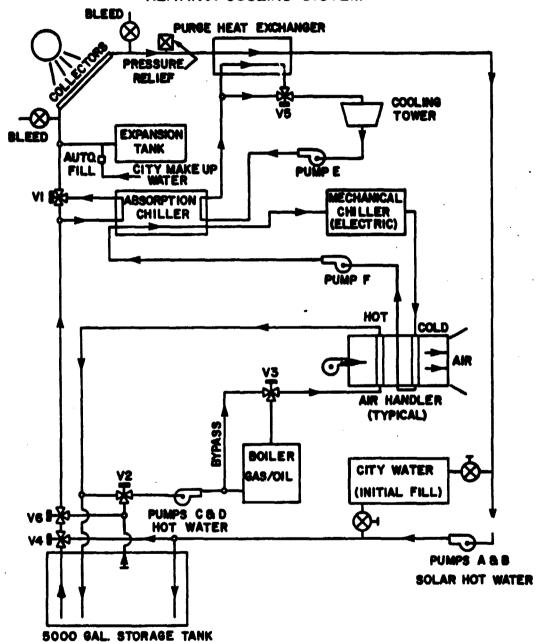


Figure 3-1. Filling and Draining Schematic. (Courtesy Heapy & Associates)

To fill the boiler/air handler loop, valve V2 was opened to permit flow from the storage tank to the pumps C&D inlet.

Pumps C&D filled the remainder of the loop. Valves V1, V3, and V5 were excercised to fill the bypass lines.

#### 3.2 EMERGENCY DRAINING

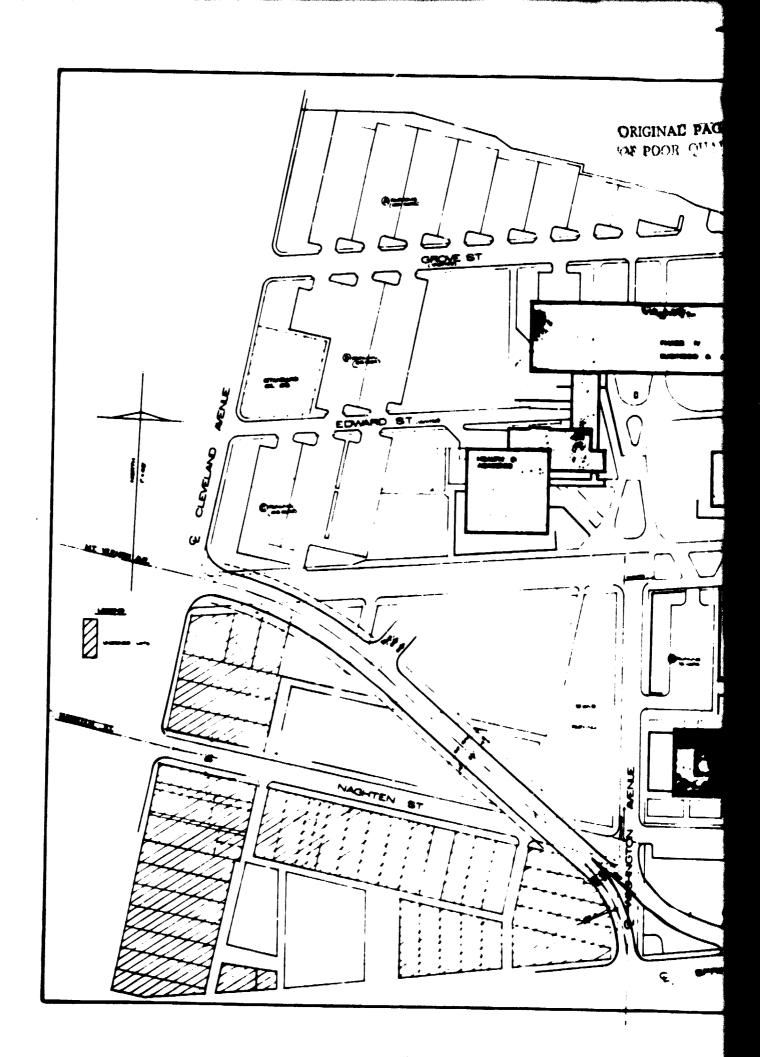
If a collector tube is broken, the resulting leak will be detected by a system which warns the Security Office in an adjoining building. Each of the eight rows of collectors on the roof can be isolated from the system by closing two manual valves in the roof curb because the eight rows are connected in parallel. The defective row must be covered with black Visqueen during hours of bright sunlight to prevent percolation of the collectors until the leak can be repaired.

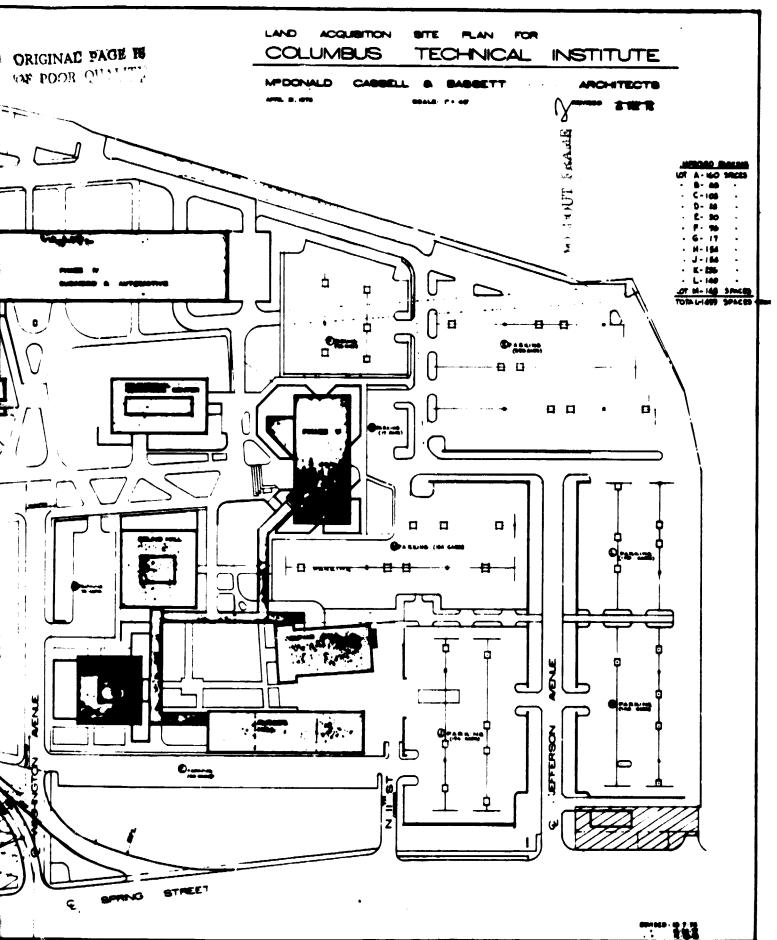
If catastrophic failure of both solar heat pumps A & B occurs, or if the system develops a leak between the solar collectors on the roof and the pump/storage tank complex on the first floor and underground, then the entire solar system must be shut down immediately. All Solar collectors must be covered with black Visqueen until repairs are complete.

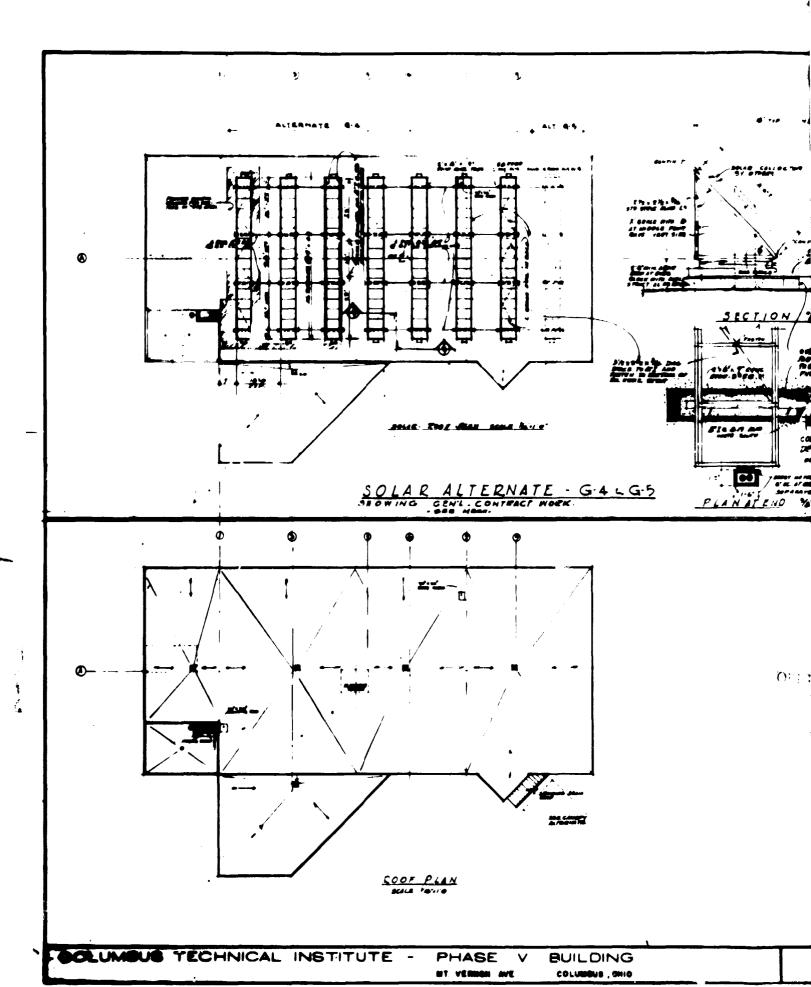
The worst possible combination of events is a catastrophic leak in the piping to or from the collectors and the collector temperature drops below freezing. This could only occur during the night in extreme cold. If the leak could be "contained", city water would be passed through the collectors to prevent freeze-up until the sun emerged. If the leak could not be "contained", each of the 3072 tubes would have to be drained individually before freeze-up, since there is no high-pressure air or other system to force water out of the collectors in an emergency. If hot water pumps C & D fail, or if a leak occurs in the boiler/air handler loop, no heat can be provided to the building. The solar loop can continue to provide hot water to the storage tank, but this water is not accessible to the air handlers.

To assist maintenance personnel on restart of the system, an Acceptance Test Plan is included as Appendix E.

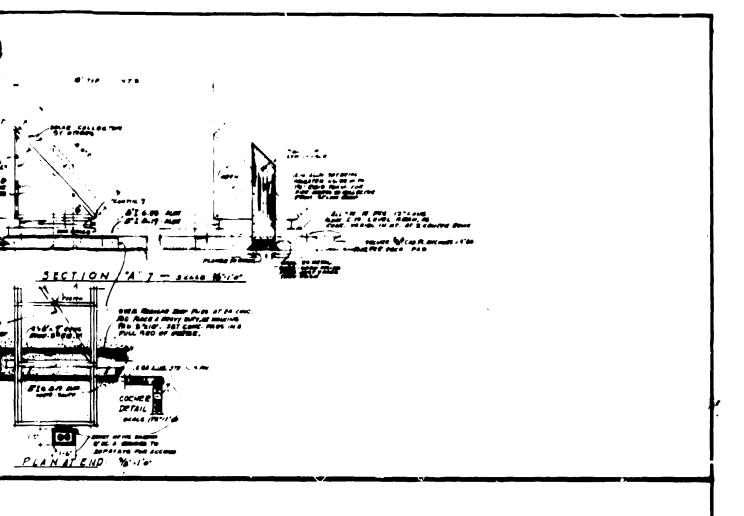
# APPENDIX A AS-BUILT DRAWINGS







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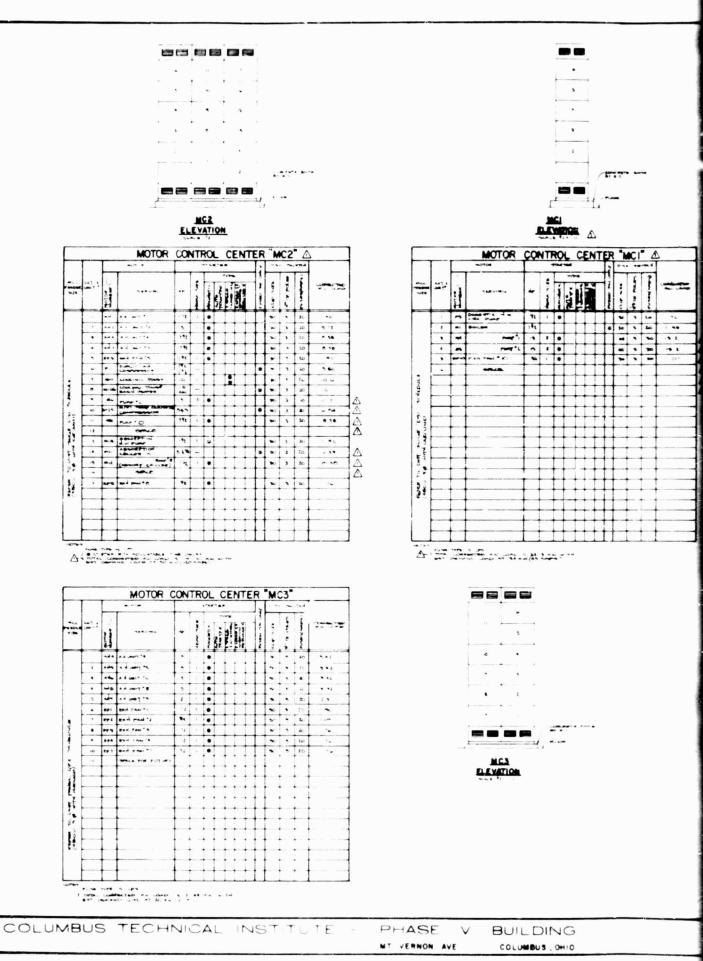
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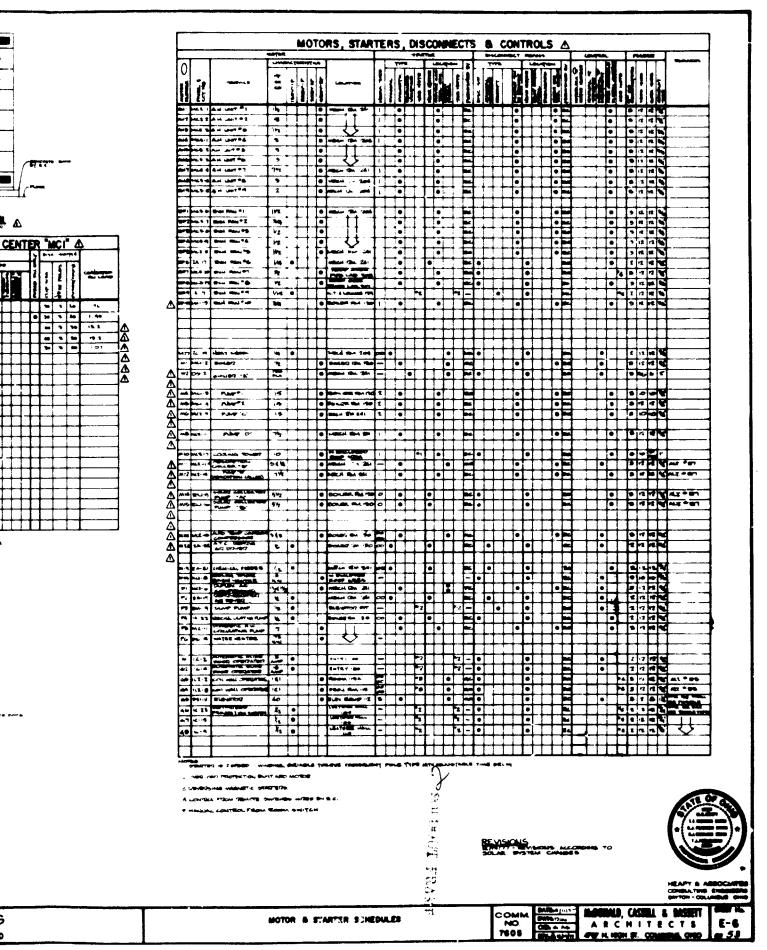
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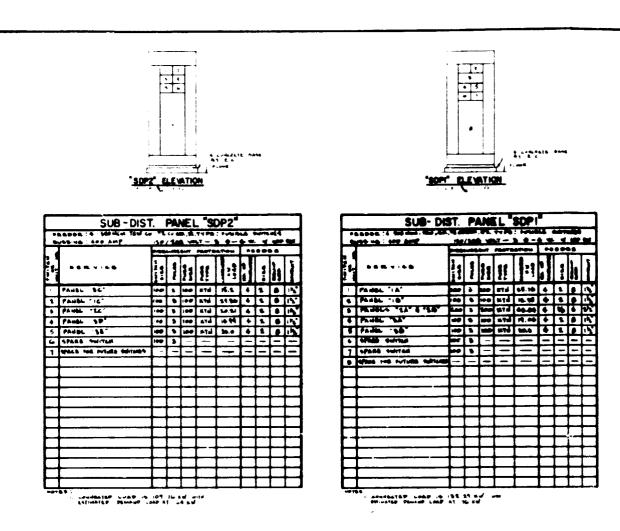
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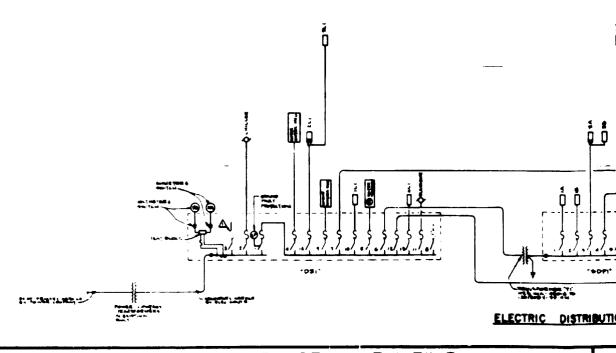
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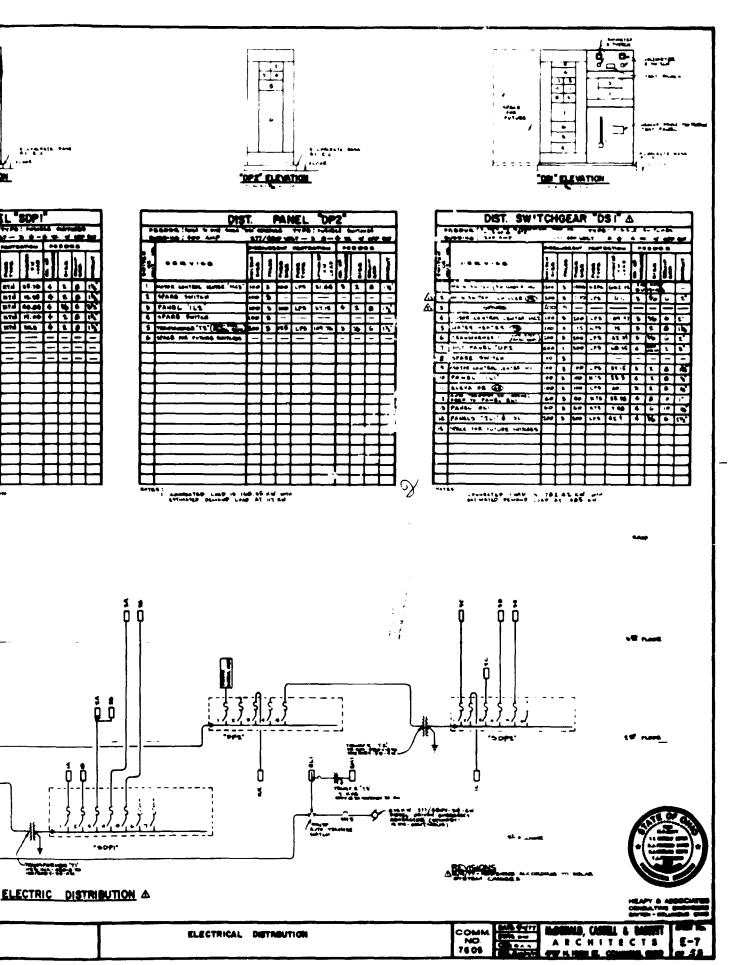


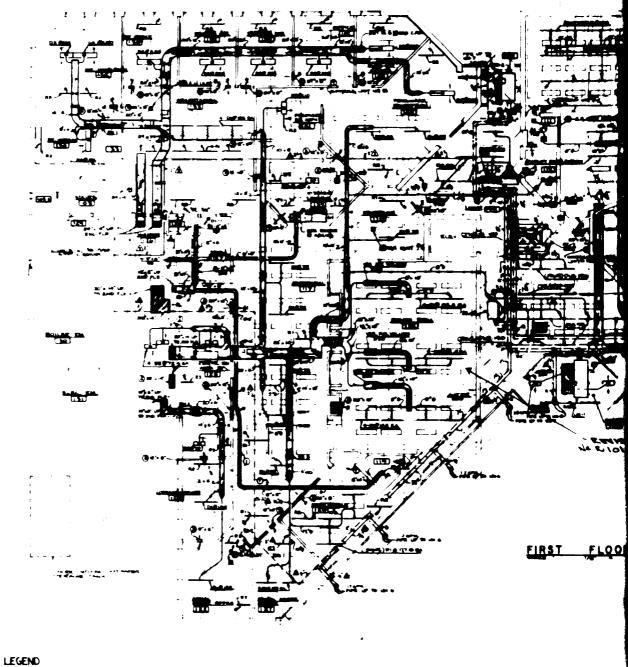






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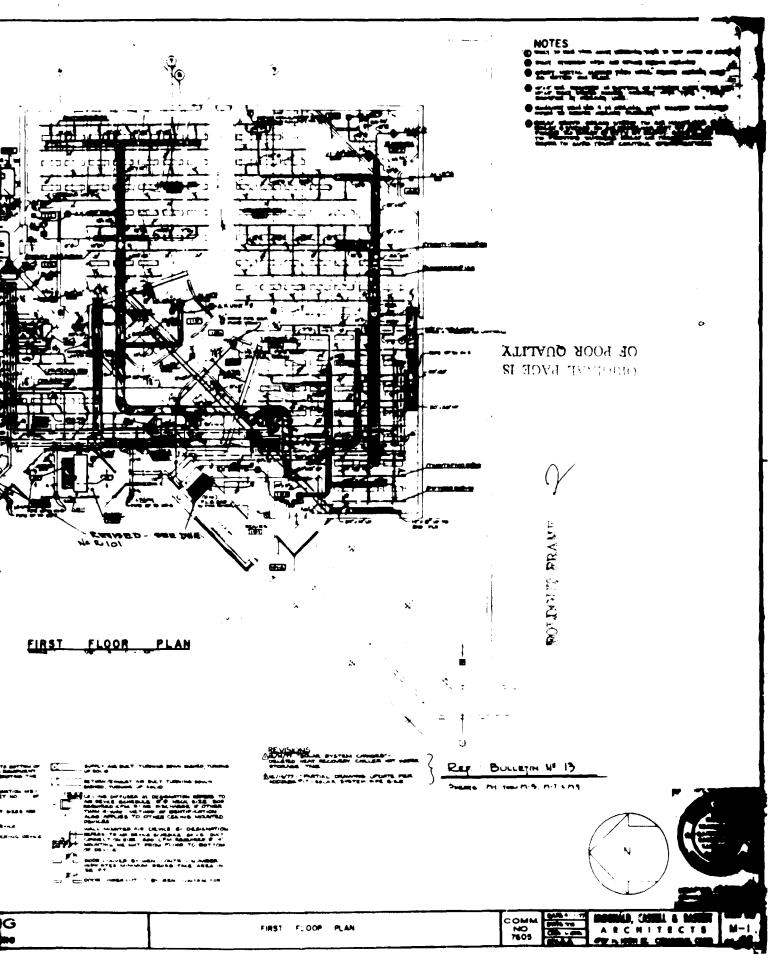


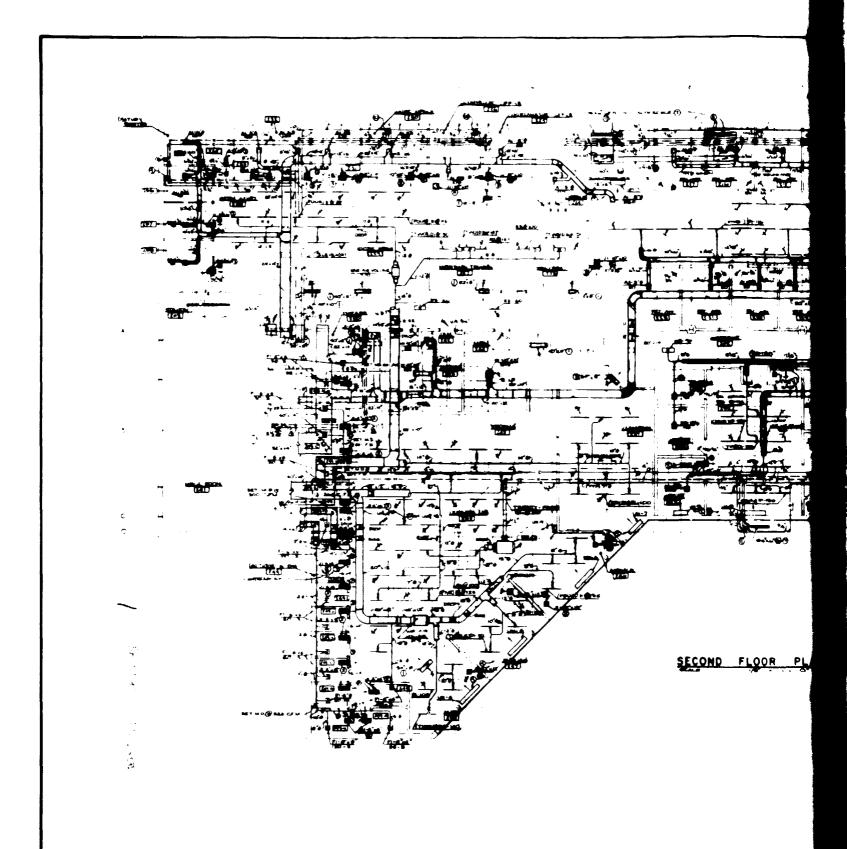
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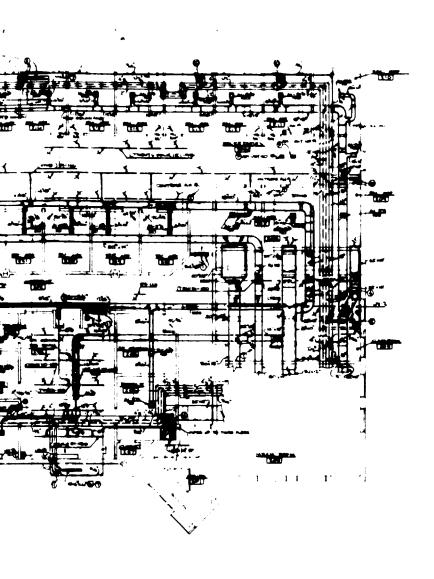
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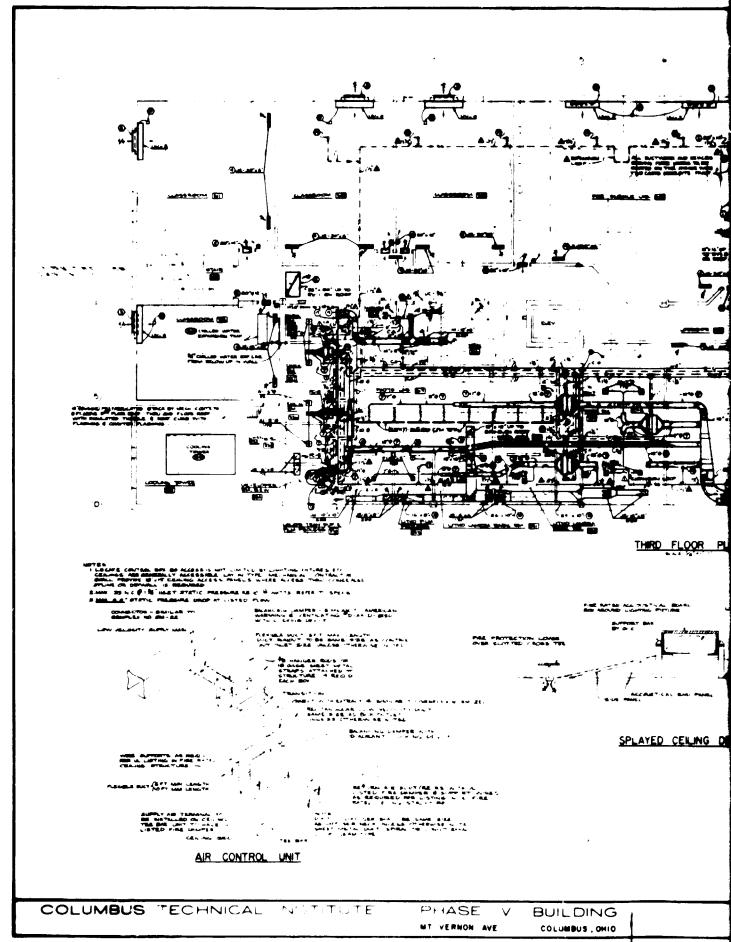
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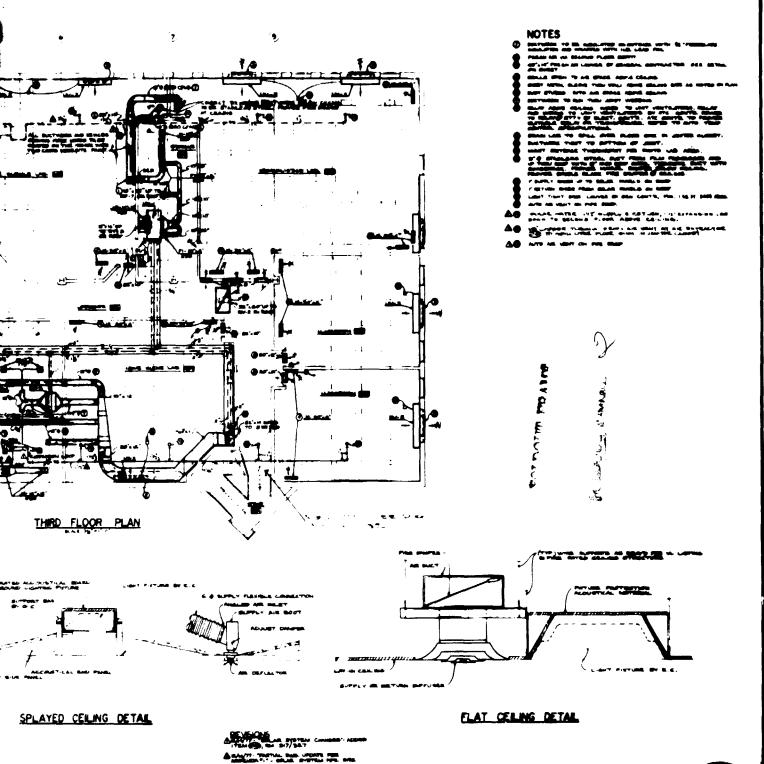


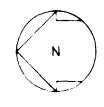


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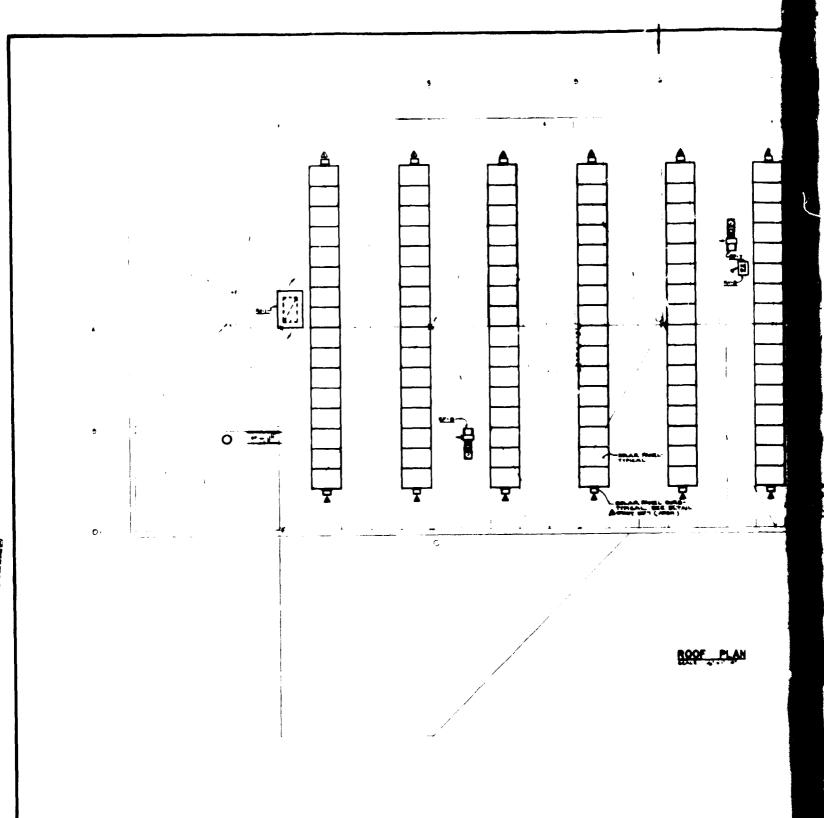


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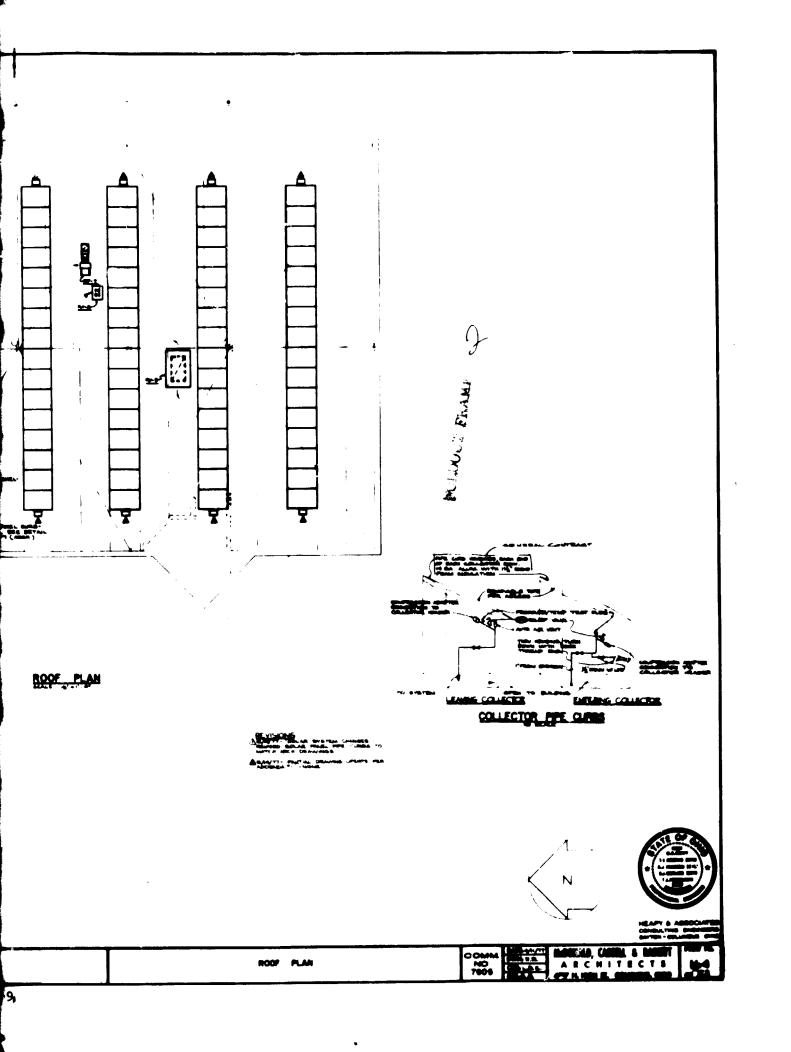
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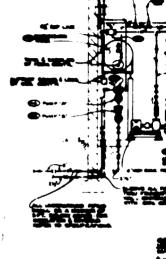
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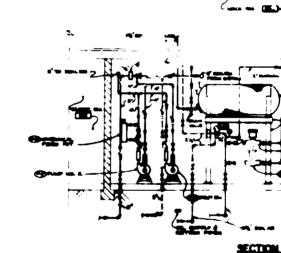


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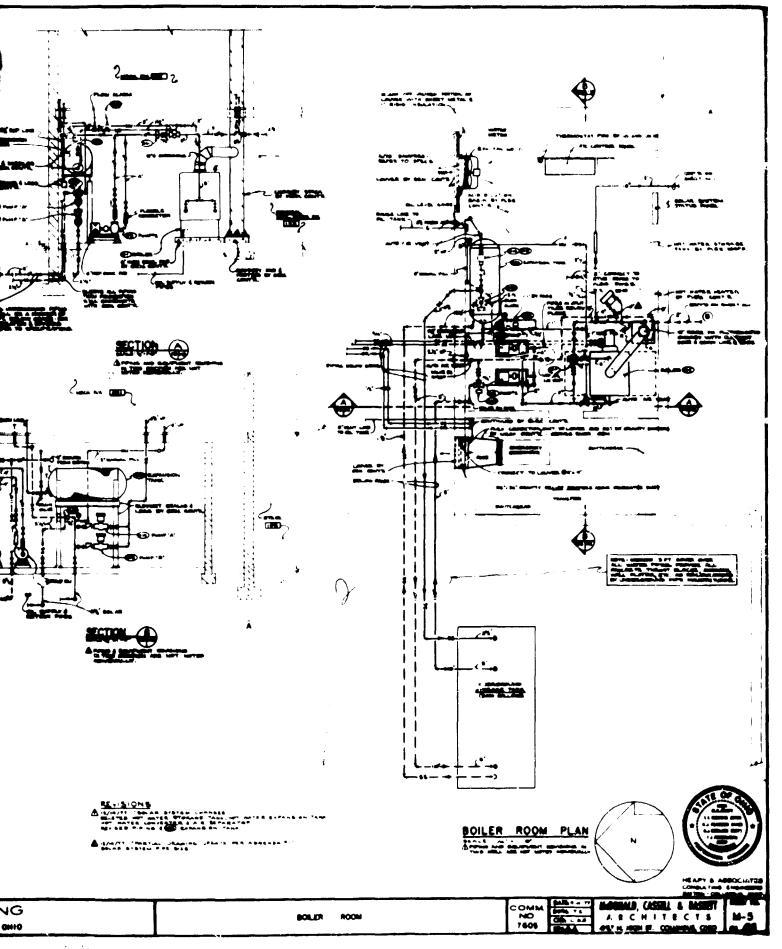


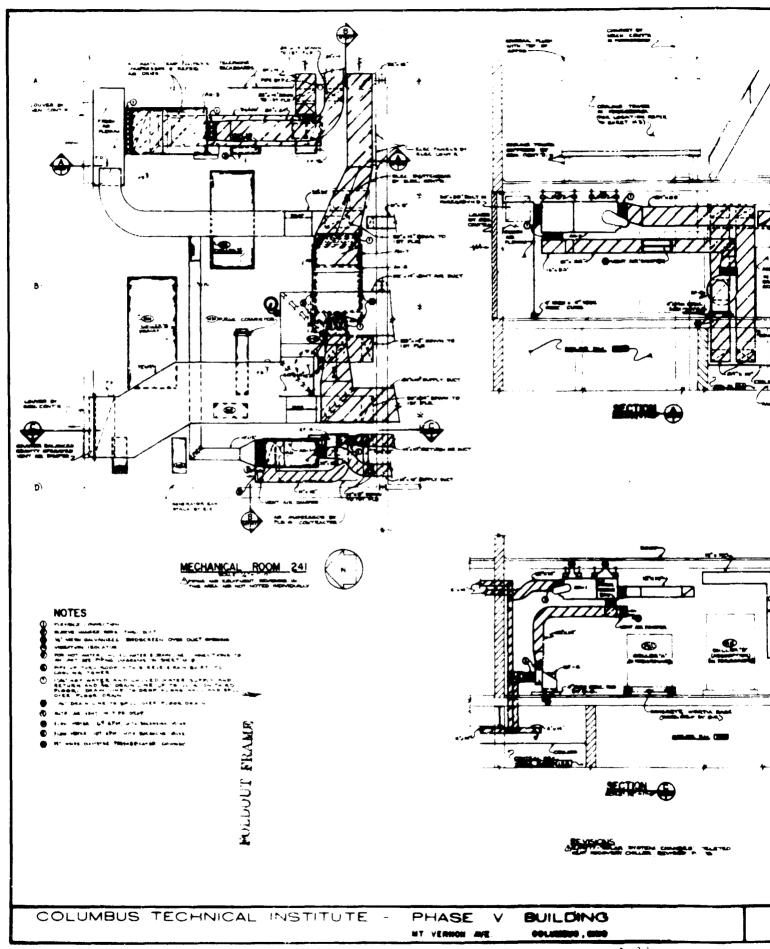
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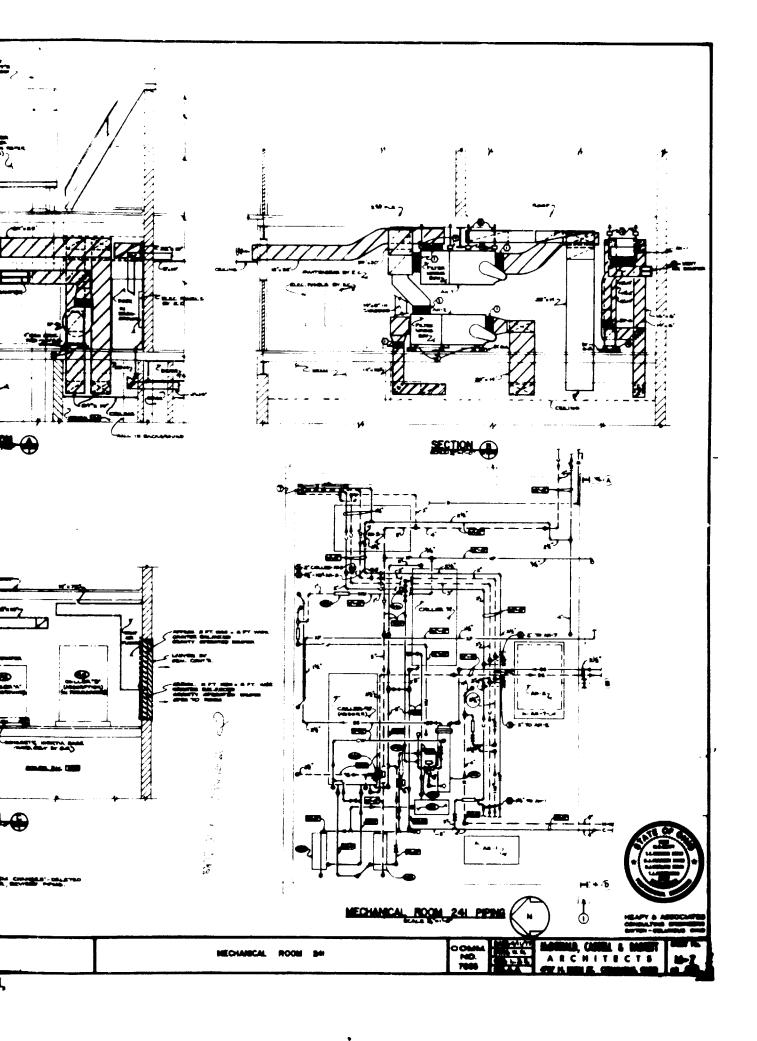
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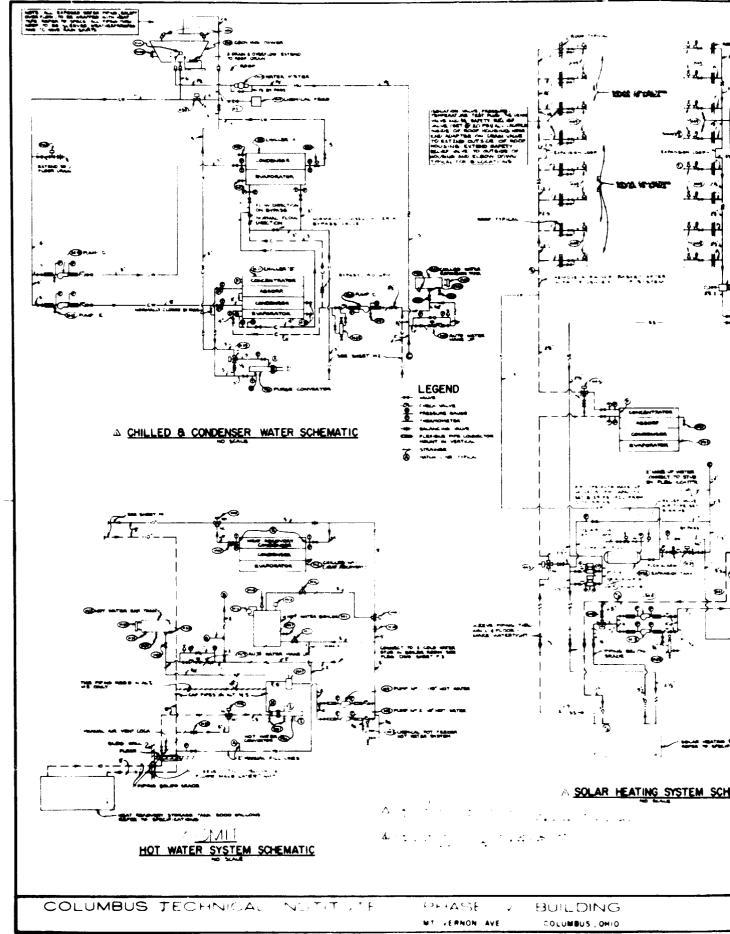
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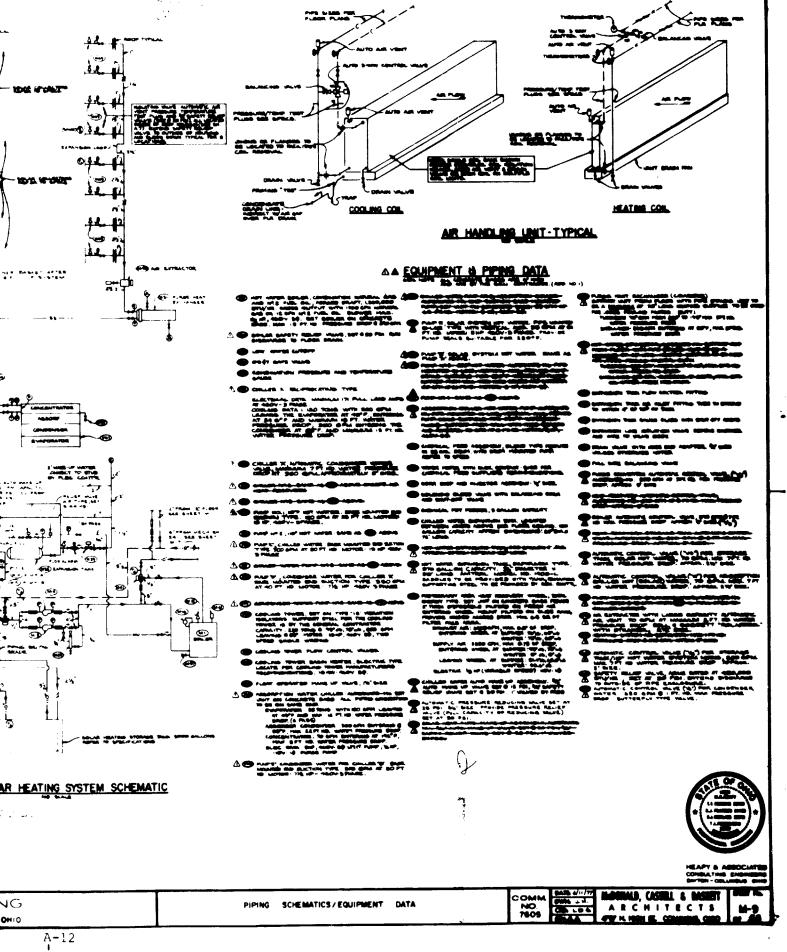








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#### APPENDIX B

SUNPAK TM SOLAR COLLECTOR INSTALLATION, SERVICE, AND OPERATING MANUAL



SUNPAK<sup>TM</sup> SOLAR COLLECTOR

INSTALLATION, SERVICE AND OPERATING MANUAL

### **SOLAR ENERGY PRODUCTS GROUP**

#### **FOREWORD**

This manual is intended to serve both as a guide to installation procedures and as a means of understanding the basis of solar-collector operation and maintenance.

Those persons charged with understanding and operating the collector system should read and understand the entire manual.

Those persons concerned only with installation of hardware will find essentially all the necessary information in <u>Section 2</u>, Installation Procedure, and in the accompanying Figures and Drawings.

Each specific SUNPAK application will be somewhat unique as a result of small differences in circumstances of installation and use. The manual is valid for the majority of these circumstances. The manufacturer should be contacted for recommendations if the customer feels his installation may be atypical in any way.

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#### **IMPORTANT**

Please see pages 7, 12, and 14 for safety information

#### 1.0 General Description

#### 1.1 Physical Dimensions

The standard SUNPAK module consists of 24 individual collector tubes manifolded together as shown in Figure 5.1. A nominal gross area of 4'x 8' is occupied by the assembled module. The effective collection area of the standard SUNPAK module is 27.4 square feet. It is the latter area (27.4 ft<sup>2</sup>) that is used as the basis for describing collector performance and in quoting collector array prices.

A typical module weighs about 110 pounds (dry) and will contain about 9 gallons of fluid (water preferred) when filled. The resulting collector load is approximately 4  $1b/ft^2$  dry and 7  $1b/ft^2$  water filled.

#### 1.2 Materials and Parts

The glass components are made with Owens-Illinois KG-33 (KIMAXR) borosilicate glass to provide strength, optical clarity, and thermal shock resistance. The fluid passageways inside the manifold are copper. All internal copper connections are hard soldered. High temperature silicone rubber "O"-rings and grommets are used for seals. The copper cup assemblies and internal headers are encased in a molded urethane foam which serves as an insulating support structure. The urethane foam is sheathed in a rigid shell of fiberglass reinforced polyester resin. The materials have been chosen to resist damage to the collector by stagnation temperatures which may rise as high as  $650^{\circ}$  F in an unfilled collector exposed to the sun.

A complete parts list appears in Table 1.

#### 1.3 Fluid Flow

#### 1.3.1 Collector Fluid Type

Water is the preferred heat transfer fluid due to its low cost and good thermal performance. The low loss property of the SUNPAK<sup>IM</sup> collector makes use of water practical even in cold climates. The use of other fluids such as glycol solutions is also possible, but rarely necessary. Questions regarding fluid selection should be reviewed with the manufacturer in light of the specific application.

#### 1.3.2 Fluid Flow Path

The SUNPAK<sup>TM</sup> manifold is designed to deliver water in a serpentine series flow pattern to its 24 tubes. This is accomplished with the use of the standard 8 mm 0.D. or optional 11 mm 0.D. feeder tubes which channel water to and from the closed end of each collector tube. Figures 5.2A, 5.2B, and 5.2C illustrate the flow pattern. In a multi-module collector array, the individual modules are interconnected in parallel flow arrangement.

#### 1.3.3 Collector Fill Flow Rates

Fluid flow rate during filling must be above a certain minimum value in order to prevent two phase flow in the feeder tubes and the resulting possibility of air entrapment. For the 8 mm standard feeder tubes, a minimum fill rate of 0.3 gpm/module is recommended with the optimum rate being 0.4-0.5 gpm/module. The 11 mm optional feeder tubes require a minimum fill rate of 0.6 gpm/module with 0.7-0.8 gpm/module being optimum. See Section 3.1 for details.

#### 1.3.4 Collector Operating Flow Rates

Efficiency of energy transfer to the collector fluid will be affected by fluid flow rate. For the 8 mm standard feeder tubes, a minimum operating flow rate of 0.25 gpm/module is recommended and a flow rate of 0.3 gpm/module is considered to be near optimum. The 11 mm optional feeder tubes require a minimum operating flow rate of about 0.5 gpm/module with 0.6 gpm/module being optimum.

#### 1.4 Installation Overview

#### 1.4.1 General Description

The collector has been designed to allow easy installation. Heavy lifting equipment is not necessary as long as there is sufficient access to allow components to be carried to the mounting surface. Each component can be easily lifted by one man. After manifolds and brackets are mounted, collector tubes are simply inserted into their "O"-ring seals at the manifolds. Plastic end caps with adjusting screws are used at the closed ends of the tubes to hold them in place against hydraulic pressure in the operating system (see Figure 5.7). If a tube replacement is necessary, the plastic end cap is removed by loosening the adjusting screw and giving a quick twist. The tube can then be removed from its seal and a new one inserted.

#### 1.4.2 <u>Installation Manpower</u>

The installation procedure is quite simple and requires a minimum of tools (see Table II), Although specific systems differ somewhat, a typical 100 ft<sup>2</sup> array, not including SUNPAK<sup>TM</sup> reflectors (see Section 1.4.6), could be installed with about one man-day of effort. Inclusion of the reflector elements in the installation of a new system would increase the installation time for the 100 ft<sup>2</sup> array to about two man-days of effort. Provision of proper tools, carpenters' aprons for carrying small parts, and efficient layout of the parts inventories to avoid long carrying distances will all serve to minimize installation time. A five-man crew seems to be optimum with three men on the collector hardware installation and two helpers to maintain an uninterrupted flow of parts.

#### 1.4.3 Collector Manifold Arrangement

The manifold is designed with internal nominal 1-inch I.D. copper header pipes. Adjacent manifolds are coupled by a specially designed mechanical coupling included with the factory-supplied hardware. Additional couplings are available for connection of external piping to the manifold inlets and outlets. As many as 15 manifolds can be joined in a single row by interconnecting the internal headers. Longer arrays can be fabricated, but careful attention to flow arrangement and header pressure drops is necessary to assure balanced flow distribution to individual modules. Best flow distribution will result when the inlet and outlet of a given row of modules are at opposite ends of the array. Header pipe thermal expansion is taken up by the mechanical header couplings.

#### 1.4.4 Mounting Surface

The collector is designed to mount on a tilted support surface provided by the customer. This can be a sloping roof or a sawtooth structure on a flat roof. The plane in which manifold and end brackets are mounted should not deviate from flatness by more than 1/4" along any 4' length. More pronounced irregularities, especially along the length of a manifold, will require the use of shims to provide a flat surface to assure proper tube and manifold alignment.

When the collector is mounted on a watertight surface, a commonly employed technique to minimize roof penetrations is the mounting of horizontal members on the roof exterior to which the collector brackets can be attached. The horizontal members may be treated 2" x 6" lumber or galvanized metal channels which are blocked up to allow water drainage. Roof penetrations at the blocking should be flashed or caulked for watertightness.

#### 1.4.5 Diffuse Reflector Surface

Collector modules can be mounted over one of two types of background reflectors; a flat diffuse reflector, or a shaped (cylindrical) non-imaging specular reflector. For best results with the diffuse reflector, the surface should have a non-glossy, reflective nature such as flat white paint. A surface which tends to be self-cleaning with rain water would be most desirable.

Several diffuse reflector materials have been tested for reflectance. Those showing satisfactory reflectance included white vertical aluminum siding, white aluminum shingles, and white roof paint applied over asphalt rolled roofing. White exterior paint over plywood gives satisfactory reflectance for up to a year which might be acceptable for a small test stand, but this approach does not offer a long-life background needed for a permanent installation.

### 1.4.6 SUNPAKTM Shaped Specular Reflector

The SUNPAK<sup>TM</sup> Shaped Specular Reflector (SSR) is shipped ready-for-mounting by the customer using the spring tube clips and interlocking tabs on the reflector elements (see Drawing ED-1). This mounting system assures proper reflector alignment and structural integrity to withstand wind and snow loading.

#### 1.4.7 Mounting Surface Tilt Angle

The angle of tilt of the support surface depends upon several factors which influence the matching of collector output with load requirements over the duration of the operating year. In general, a winter heating load is best satisfied with a south-facing array tilted at an angle of the latitude plus 10-20 degrees. A constant annual load such as domestic hot water would use a tilt approximately equal to the latitude. A load which peaks in the summertime would use a tilt equal to the latitude minus 10-20 degrees. Collector output is not very sensitive to deviations of a few degrees from the optumum tilt angle.

#### 1.4.8 Special Considerations for Low Tilt Angle

Generally, the collector will be mounted at a tilt ranging from 30 to 70 degrees from horizontal. Tilt angles of less than 30 degrees will require special consideration of air clearing during collector filling. Information can be obtained from the manufacturer.

#### 1.4.9 Mounting Surface Structural Integrity

The SUNPAK TM collector module and shaped reflector attachment are designed to withstand wind, snow, and ice loadings normally encountered in service. It is the responsibility of the customer to insure that the mounting surface to which the collector is attached has the required structural integrity to support the filled collector array under normally anticipated conditions. It should be noted that at recommended collector operating pressures of 30 psi or less, hydraulic pressure in the tubes will yield a resultant force at each mounting bracket attached to the surface. Maximum forces on the mounting surface are on the order of 30 lb. (downward) at each end bracket and 40 lb. (upward) at each center bracket. In long collector array designs, careful attention should be paid to the deflection characteristics of the supportstructure under wind loading. Further information can be obtained from the manufacturer.

#### 2.0 Installation Procedure

#### 2.1 Installation Sequence and Layout

#### 2.1.1 Sequence

The general sequence of collector installation is as follows:

- a. chalkline layout of mounting surface reference lines:
- b. layout and mount manifold center brackets;
- c. square and mount manifolds and mechanical header couplings;
- d. square and mount tube end supports;
- e. tighten support tie rods between manifolds and end supports;
- f. install feeder and collector tubes;
- g. connect external piping and leak check;
- h. install manifold connector covers;
- i. secure manifold connector covers and end caps.

The details of each installation will be somewhat different. The manufacturer's field service personnel have accumulated a good deal of experience and can be relied upon to prepare local installation crews and provide time-saving hints. The customer should not hesitate to call upon this experience either in the field or by phone or mail to the manufacturer's office directed to the responsible Project Manager.

#### 2.1.2 Layout (Figures 5.1 and 5.4 and Drawings ED-1 and ED-2)

A single module will occupy a space of 4 feet wide and 8 feet tall. Provision should be made for minimum length runs of external piping at the end of an array of modules and for the manifold end caps which project about six inches beyond the ends of the array. Provision should also be made for removal of tubes during servicing which will require a minimum of 3" of clearance at the ends of the 8' module dimension. If the total array consists of several parallel rows of modules, then access must be provided between rows for servicing any point in the array.

A chalkline is first made to fix the centerline of the manifolds. Two additional chalklines are then laid out parallel to the first and lying 46' +1/8", -0" above and below the manifold centerline. These lines mark the centerlines of the tube end support mounting spacer holes. A perpendicular chalkline is made at the starting end of the array to mark the end of the first module. Additional perpendicular lines may be made at 4' intervals down the row to mark the space occupied by each module. Intervals should be measured along a stationary steel tape to avoid accumulated measurement error.

### 2.2 Manifold Center Brackets, Part SK-2852, Figs. 5.4, 5.5, and Drawing ED-1

Manifolds are mounted with 3 center brackets per module which are fastened to the mounting surface on the manifold centerline chalkline. The first bracket of the first module is located 8" inboard from the first perpendicular reference chalkline marking the end of the first module. Remaining center brackets in the row are secured at 16" intervals. The 16" tolerance is approximately equal to \$\frac{1}{16}\$" and should be done with a stationary steel tape to prevent accumulated measurement error. The center brackets are fastened to the mounting surface with appropriate customer-supplied fasteners.

### 2.3 Squaring and Mounting Manifolds, Part SK-5155, Figs. 5.5, 5.6, and Drawing ED-1

Field experience has shown that careful alignment of the manifolds at this point can result in optimum alignment of all components in the array. It should be noted that manifolds must be positioned on the center brackets with the "T" marking on the bottom mounting brackets facing the upslope side of the mounting surface. The manifold nameplate should be on the downslope side of the surface.

At this point, both the first and last manifold of each row of modules should be lowered onto the center brackets and made hand tight using the threaded end of the support rod (SK-2851) and the locknut/washer assembly. Use of two washers in this assembly may help to avoid deformation of the brackets due to inadvertent over tightening. Both manifolds should be made perfectly square and level in all directions using a steel square, steel scale, and level. Support rods are then tightened to hold manifolds firmly.

Mounting of the intermediate manifolds is made easier by temporarily locating a taut steel wire (use a turnbuckle) about 1" above the two end manifolds and extending the full length of the collector array between these manifolds. After making sure that this wire is perfectly straight and level, all intermediate manifolds should have the same relationship to the wire as the two end manifolds already mounted.

The remaining manifolds can now be lowered into place one at a time being sure to attach the floating mechanical coupling (SK-3047) at each header connection. When manifolds are properly aligned and secured by the support rods, a gap of 1/8" should exist between ends of adjoining header pipes. This gap and the coupling are used to take up thermal expansion of the headers. No soldering is necessary within the array. Mechanical couplings can be tightened at this time.

## 2.4 Tube End Supports, Part SK-2848, Figs. 5.4, 5.5, and Drawings ED-1 and ED-2

The aluminum tube end supports are now mounted using the "Z" shaped mounting spacers (SK-2880). The horizontal chalklines at 46"  $^{+}$ 1/8,  $^{-}$ 0 serve as the centerlines for the mounting holes of the "Z" brackets. The

first pair of brackets will be located opposite one another at a point 2" inboard from the first perpendicular reference chalkline marking the end of the first module. The second pair of brackets will be located 46" inboard from the first pair. Intermediate brackets will be mounted at 48" intervals. Brackets for the last module in a row will again have a 46" separation as did those for the first module. A stationary steel tape should be used to lay out these mounting holes since accumulated measurement error will result in collector tubes not being perpendicular to the manifolds. This could lead to sealing problems.

If not already done, the tube end supports and "Z" mounting spacers should be fastened together. Working at the first module of the row, these assemblies should be placed onto the support rods and held in position at the mounting holes to check the squareness of the support rods to the manifolds and the end supports. If square, the ruber pads (SK-2875) can be placed beneath the feet of the mounting spacers and the spacer/end support assemblies can be mounted for all modules in the row. A spot check of the squareness of the support rods in the row is advisable.

The butt joints between successive tube end support channels are made with a simple clamp arrangement using the clips (SK-2870) and a bolt (SK-5318) and nut (SK-5316). Since no clips are used on the first and last brackets of a row (no butt joints at these locations), a small shim spacer (SK-2989) is provided to maintain constant collector tube height. The shim is inserted between the tube end support and mounting spacer. Larger shims under the feet of the "Z" mounting spacers may be needed if the mounting surface is very irregular. Wherever penetrations are made directly into a roof structure, care should be taken to maintain the integrity of the roof.

The nuts holding the threaded support rods to the tube end support channels may now be made tight enough to adjust the distance between the inner face of the support channel and the flat side of the manifold to equal 41-1/2" - 41-5/8".

Manifold connector covers (SK-5419) should be fastened into place with the special fasteners (SK-5407).

2.5 Feeder Tube (SK-4920) and Collector Tube (SK-3092) Installation, Fig. 5.7 and Drawing ED-1

#### !!SAFETY GLASSES AND GLOVES SHOULD BE WORN!!

The feeder tubes form a continuous fluid channel when the flared ends are snapped into place in the manifold grommets (SK-4921). Installation procedures are identical for the standard 8 mm feeder tubes and the optional 11 mm feeder tubes. Care should be exercised in properly sealing the tubes in the grommets. Do not use any petroleum-based lubricants on the silicone rubber parts. If some lubrication is required during installation, only a common soap solution in water or ethylene glycol should be used. Silicone rubber can become brittle and crack in a short time after contact with petroleum compounds.

Before actually inserting the feeder tubes, a check should be made of every collector tube opening in every manifold in the array to be certain that grommets, end seals, and "O"-rings are in place and passageways are clear. It should also be confirmed that the protective carbon material is present on the non-flared ends of the feeder tubes. This assures that the collector tubes will not be damaged when slipped over the feeder tubes.

Do not walk on installed manifolds or tube end supports at any time. Supporting brackets were not designed to withstand such loading and improper collector tube and manifold alignment may result.

Ideally, sufficient access should exist between rows of modules to allow the feeder tubes and collector tubes to be installed separately as in Figure 5.7. If this is the case, all feeder tubes can be installed at this time. If insufficient access exists to insert the tubes from the ends of the tube end supports, then feeder and collector tubes must be installed together. Basically this involves placing the feeder tube into the collector tube and lowering both into the space between the manifold and tube end supports. The closed end of the collector tube is extended through the tube end support and the feeder tube is withdrawn slightly from the open end of the collector tube to allow seating of the flared end into the grommet.

Proper tube and manifold alignment will be assured if the following sequence of tube insertion is observed. This sequence is valid regardless of which method is used to place the feeder and collector tubes. Tubes 1 and 2 of the first manifold in the row of modules should be inserted and the support cup assemblies (SK-3048) put in place and made finger tight fixing the space between the flat side of the manifold and the end support channels at 41-1/2" - 41-5/8". (See Figure 5.2C for details of tube numbering sequence.) Nuts on the support rod outboard ends may have to be loosened. Tubes number 23 and 24 of the first module should then be installed in the same manner followed by the four tubes at the center of the manifold. By "playing" the adjusting screws of the support cups against the support rod nuts, the proper 41-1/2" - 41-5/8" dimension can be fixed and the nuts on the support rods given a final tightening. At no time should support cup adjusting screws be more than finger tight.

Remaining tubes in the first module can now be installed. Tubes for other modules in the row should be installed in the same sequence. It should be noted here that the optional shaped specular reflector element (SK-2988) should be installed as each tube is installed. Spring clips (SK-2987) and the interlocking reflector tabs are much easier to work with at this point.

#### 2.6 External Piping To and From the Solar Collector

The piping connections to the collector may be made at either end of a bank. The top header, i.e., the pipe located furthest from the mounting surface, is the outlet header. The bottom pipe is the inlet header.

The connecting piping to each row of manifolds should be properly supported to prevent undue stress on the collector system. Expansion of external piping from the collector should be considered in this area. The headers within the collector manifold are compensated for expansion by the mechanical coupling. Support to the manifolds is not designed to cover the stresses that may be introduced by the connecting piping.

External piping may be joined to the manifold header pipes by a soldered connection, but extreme caution should be exercised to prevent damage to any of the soldered connections inside the manifold or the manifold insulation. An electrical resistance soldering tool is recommended, but a torch can be used if heat shields are employed to protect manifold insulation. A solder of 95% tin and 5% antimony is recommended.

A preferred alternative is the connection of external piping using the positive restraint coupling (SK-4253) as shown in Drawing ED-2. This avoids all soldering and can also be used in conjunction with the termination adaptor (SK-5319) for header pipe termination.

Vent valves near the inlet and outlet connections are recommended for several purposes. These parts can be used as air vents when the system is filled or drained. These valves may be manual or automatic depending on desired operation conditions. In an emergency no flow condition, the steam may be vented through these valves to protect the system from undue thermal and pressure conditions.

The maximum recommended operating pressure of the solar collector row is 30 psig. The recommended design is to provide for a pressure relief valve of 30 psig or less in the outlet header line to vent the collector in an emergency condition. It is absolutely essential that no type of shutoff valve be located between the collector and the relief valve. Such a valve could be accidentally closed and eliminate overpressure protection. The inlet of the collector should be maintained below 30 psig and can be accomplished with a pressure regulator in the system. Each pressure relief valve should be vented properly to insure that steam and water are diverted safely. A pressure relief valve should be provided to each row of manifolds. For multi-manifolded rows, each row which can be isolated from the system must have a safety relief valve.

### 2.7 Leak Detection

The collector row should be checked for leaks at the coupling between modules and at the connecting piping. Next, the "O"-ring seal area should be checked for leakage. Leak testing can be with either air or water. Water is the preferred method and can be used by pressurization of the system not to exceed 30 psig. In some systems or situations, it may be desirable to use air to check for leaks. In these cases, pressurization with low pressure air (~5 psi) and a soap solution is a convenient way to find leaks before a system is water filled. The collector should not be pressurized over 10 psi with air due to the potential hazard of flying glass if a tube would be broken. Note that air testing is not recommended during a bright, clear day. Evenings or nights are suggested to reduce pressure-volume changes of air as it is heated in a closed system.

### 2.8 End Cap Attachment, Part SK-5153, Drawing ED-2

After leak testing, the insulating end caps can be cut as necessary to make provision for the connecting piping. The caps should fit as closely as possible to the piping to minimize heat losses. The caps are held in place by the special fasteners (SK-5407) which permit access to this location for system servicing.

### 2.9 SUNPAKTM Test Module Package - Special Note

Purchasers of the two-module test array package will also receive this Installation and Operation Manual, and should become thoroughly familiar with all information presented even though the test array is of small size. All installation procedures and modes of operation are identical for large arrays and the small test array. Some time might be saved, however, by taking note of the following facts about the test array:

- a. Depending on the nature of the mounting surface and physical access, the entire array could be assembled in the shop and carried to the final location.
- b. Wherever assembly is done, use of reference chalklines is still recommended, but the use of a taut steel wire is not necessary in aligning the two manifolds (see Section 2.3).
- c. Since both manifolds are the "ends" of a row, the spacing between the mounting holes of the "Z" shaped mounting spacers will be 46" for both modules (see Section 2.4).
- d. If more convenient, external piping connections for the inlet and outlet header pipes may be at the same end of the two module array. Any flow muldistribution should be negligible for such a short array (see Section 1.4.3).
- e. The mounting surface need not necessarily be constructed for long term durability. Exterior grade plywood with a suitable finish is acceptable (see Section 1.4.5).
- f. Since many test modules may be run without energy storage facilities and without sophisticated control logic, it may be advisable to make special provisions to drain the solar loop when necessary due to severely cold weather. This must be accomplished manually in the test module array by removing the first inlet tube of each module (tube #1) and all the even numbered tubes in the module (see Figure 5.2C for tube numbering sequence).
- g. During periods of high insolation and no collector fluid flow, the possibility of collector boilout can be easily avoided by temporarily shading the test module with a suitable opaque cover. The collector modules need not be drained if this step is taken.
- h. The structural integrity of the mounting surface is equally important for test modules and large sized arrays. Even though the test installation may be temporary, the mounting surface must be sound (see Sections 1.4.4-1.4.9).

### 3.0 Recommended Operating Procedures

### 3.' Filling

The internal parts of the SUNPAK TM solar collector will approach temperatures in excess of 600°F while standing in bright sunlight. While the SUNPAK TM collector has been constructed with low expansion glass, filling the collector during midday portions of a bright day are not recommended. Filling a collector in a bright sun could cause damage due to thermal shock. Introduction of a fluid into a hot tube could also result in the initial slug of fluid leaving the collector to be a mixture of hot water and steam. The outlet from the collector on initial fill should be properly vented. The recommended procedure to avoid steam generation and potential thermal shock of the equipment is to fill in the early morning so that a high stagnation temperature is not reached. Filling should not be attempted after 9:00 A.M., and is best carried out less than one hour after sunrise.

The invidivual modules of a collector array are connected in a parallel fluid flow pattern. The fluid flow rate during filling must be sufficient to cause all modules in the array to fill uniformly and to prevent two-phase flow in the feeder tubes which could lead to air entrapment. Air entrapment can cause one or more modules to cease flowing if the back pressure of the air lock is greater than the pressure drop offered by neighboring modules. Air locks may also be encountered when a partially filled array is refilled or whenever air is introduced into a filled array such as when the piping is drained for repairs. The piping system should be designed to minimize the introduction of air into the array during normal operation.

Air entrapment during collector filling can be avoided through the use of the following flow rate guidelines. For the standard 8 mm feeder tubes, a minimum fill rate of 0.3 gpm/module is recommended with optimum fill rates lying in the 0.4-0.5 gpm/module range. For the optional 11 mm feeder tubes, a minimum fill rate of 0.6 gpm/module should be used with 0.7-0.8 gpm/module being optimum.

### IMPORTANT

The boiling out of a collector as a means of emptying the collector for shut-down is <u>not</u> recommended. Under extreme insolation conditions, the collector could be damaged by thermal shock.

### 3.2 Operating Flow Rates

The operating flow rates recommended for the SUNPAK TM collector module are a compromise between desired fluid temperature gain, energy requirements of the load, adequate flow distribution in the collector array, and fluid pumping costs. For most applications, the standard 8 mm 0.D. feeder tubes provide adequate energy delivery with good fluid distribution and acceptable pressure drops across the array. Some load requirements, however, have demanded higher fluid flow rates. Larger feeder tubes of 11 mm 0.D. have been added as an option to give higher flow rates at pressure drops across the array which are comparable to the smaller, standard feeder tubes at lower flow rates.

Figure 5.3 shows the pressure drop across a module as a function of fluid flow rate for both 8 mm and 11 mm feeder tubes. The flow characteristics of the collector are such that a pressure drop of 5 psi or more across the array will assure that distribution of flow to all modules in the array is uniform. As flow rates rise above the minimum needed for good fluid distribution, collector residence time is shortened and fluid temperature gain is reduced. It has been found that the optimum compromise flow rates for the SUNPAK<sup>TM</sup> collector are 0.3 gpm/module for 8 mm feeder tubes and 0.6 gpm/module for 11 mm feeder tubes.

### 3.3 Freeze Protection

The very low loss coefficient of the SUNPAK TM collector affords it excellent freeze protection. The collector will gain enough energy on even the cloudiest days to prevent freezing of the collector modules during daylight hours or through a below freezing night. Piping to and from the collector modules is, however, more vulnerable to freezing, especially under no-flow conditions. The length of such external piping runs should be minimized. It is recommended that all piping systems external to the collector be properly insulated to avoid the problem of freezing a line to the collector resulting in isolation of that element.

Temperature monitoring of the collector fluid is suggested and heat may be added at night to keep the solar loop from freezing. Where below freezing temperatures are particularly severe or prolonged, exposed piping to and from the array should be electrically traced and insulated. Under conditions of no fluid flow, it may be advisable to charge a sustained pulse of fluid to the array at about 4-hour intervals. This pulse can be drawn from storage and should be of sufficient duration to totally displace all fluid contained in the tubes, manifolds, and system piping (each module contains about 9 gallons of fluid).

The collector's tubular design tends to shed snow easily. Experience in Toledo has shown that even a nine-inch snow storm did not cover the array. However, if an array should become completely snow-covered such that no insolation could reach the collector, there could be a danger of freezing the array. To prevent this, the entire volume of water in the exposed solar loop should be exchanged with warm water at least once a day.

### **IMPORTANT**

### 3.4 Maintenance and Safety

Extreme caution should be exercised when performing maintenance on the collector. Accidental breakage of a tube in a system operating under pressure at temperatures above 140° F could result in serious burns to personnel. Tubes should not be removed from an array during periods of bright sunlight if there is a possibility that the module being serviced could be air locked. This could lead to the release of pressurized steam, even though the inlet and outlet headers may be at atmospheric pressure.

Care should be exercised in handling partially filled tubes which may have reached elevated stagnation temperatures in the unfilled portion of the tube. Pouring water from the tube could cause flashing of the water as it contacts the high temperature region of the tube and in some cases this may result in breakage of the tube.

Personnel handling the evacuated collector tubes should wear gloves and safety glasses. This is standard procedure for any routine glass handling work. Failure of a tube due to rough handling results in an implosion and does not generate a serious problem due to flying glass.

The collector support st. ucture should be designed to prevent harm to people or property from falling glass or hot heat transfer fluid in the event of failure of a glass tube or other collector part. If corrosive or toxic heat transfer fluids are used, provision should be made to conduct these fluids to a safe area in the event of collector failure. Safety relief valves protecting the collector against pressures greater than 30 psig should be vented to a safe area.

The collector tubes tend to be self cleaning in normal rainfall. However, if extended dry periods or other abnormal conditions cause an excessive covering of dirt on the collector, occasional hosing off is recommended. If performance is being measured with the aid of a pyranometer, the cover of the pyranometer should be kept clean at all times.

Under conditions of no fluid flow, high levels of insolation on a filled collector can rapidly lead to a boilout condition in the collector. The system should not be shut down for maintenance during bright sunlight hours unless absolutely necessary. If such a daylight shutdown is unavoidable, that portion of the system requiring service should be isolated from the remainder of the system and shut down. That portion of the system must then be drained down or adequately shaded from insolation. It is better to schedule no-flow types of maintenance for night hours or periods of low insolation when no draining or shading is needed.

Recommended spare parts should include 2% extra collector and feeder tubes. Required quantities of other expendable parts (gaskets, seals, etc.) will vary with the installation and can be recommended once the system characteristics are defined.

### 3.5 Monitoring Performance

Performance of the SUNPAK collector can be monitored by comparing the useful energy being gained by the collector to the insolation entering the plane of the collector. Consideration must be given to the residence time of the collector when determining heat gained. For example, a module operating with a 0.3 gpm flow rate will have a 30 minute residence time. To calculate the heat being gained, one would determine a  $\Delta T$  by subtracting an inlet temperature from the outlet temperature which occurs 30 minutes later. This residence time would, of course, be different for other flow rates. Residence time can be estimated assuming plug flow and a 9 gal/module fluid capacity.

### 3.6 Technical Assistance

If additional information is desired, please contact the responsible manufacturer's Project Manager at the following address:

OWENS-ILLINOIS, INC. Solar Energy Products Group SUNPAK<sup>TM</sup> Program P. O. Box 1035 Toledo, OH 43666

### 4.1 <u>TABLE I</u> SUNPAK<sup>TM</sup> PARTS LIST

Number Required <u>Per Module</u>	Part Number	Part Identification
1	SK-5155-2	Standard Manifold (8 mm Feeder Tubes)
1	SK-5155-1	Optional Manifold (11 mm Feeder Tubes)
12	SK-4921-2	Standard Grommets (8 mm Feeder Tubes)
12	SK-4921-1	Optional Grommets (11 mm Feeder Tubes)
24	SK-4920-2	Standard Feeder Tubes (8 mm)
24	SK-4920-1	Optional Feeder Tubes (11 mm)
6	SK-2851	Support Rods
3	SK-2852	Manifold Center Brackets
2	SK-2848	Tube End Supports
4	SK-2870	Clips
2-4	SK-2875	Mounting Pads
2-4	SK-2880	Mounting Spacers
· )-2	SK-2989	Shim Spacers
24	SK-3048	Support Cup Assemblies
24	SK-3092	Collector Tube Assemblies
2	SK-3047	Floating Tube Couplers
As Required	SK-4253	Positive Restraint Tube Couplers
As Required	SK-5319	Termination Adaptors
2 Per Junction	SK-5419	Manifold Connector Covers
4 Per Junction	SK-5407	Manifold Connector Cover Fasteners
1 Per End	SK-5153	End Caps
2 Per End	SK-5407	End Cap Fasteners
24	SK-2988	Optional Shaped Specular Reflectors

### 4.2 TABLE II

### SUGGESTED INSTALLATION TOOL LIST

- 1. "Holster"-type tool pouch
- 2. Carpenter's apron for small parts
- 3. 1/4" ratchet socket drive
- 4. 1/4" x 6" drive extension
- 5. 5/16" deep well socket (1/4" drive)
- 6. 5/16" nut driver

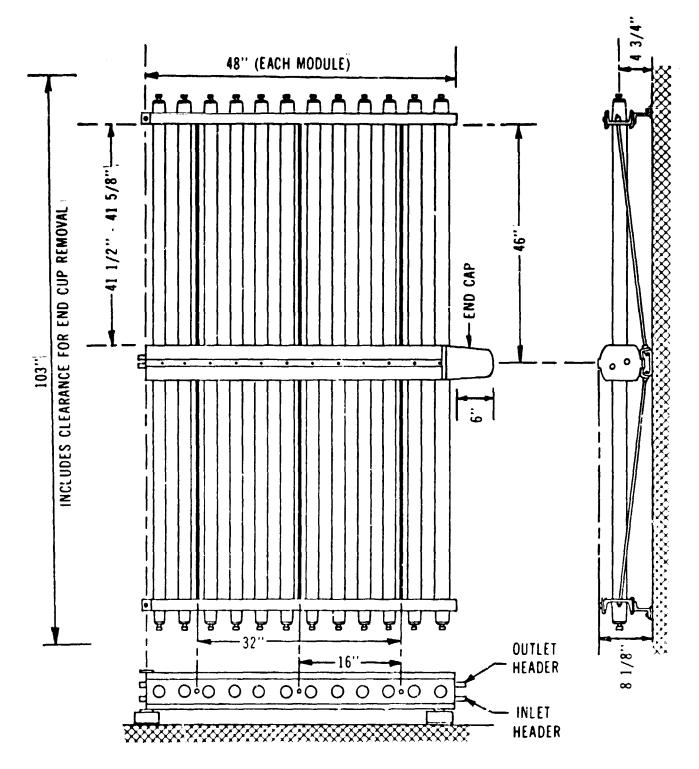
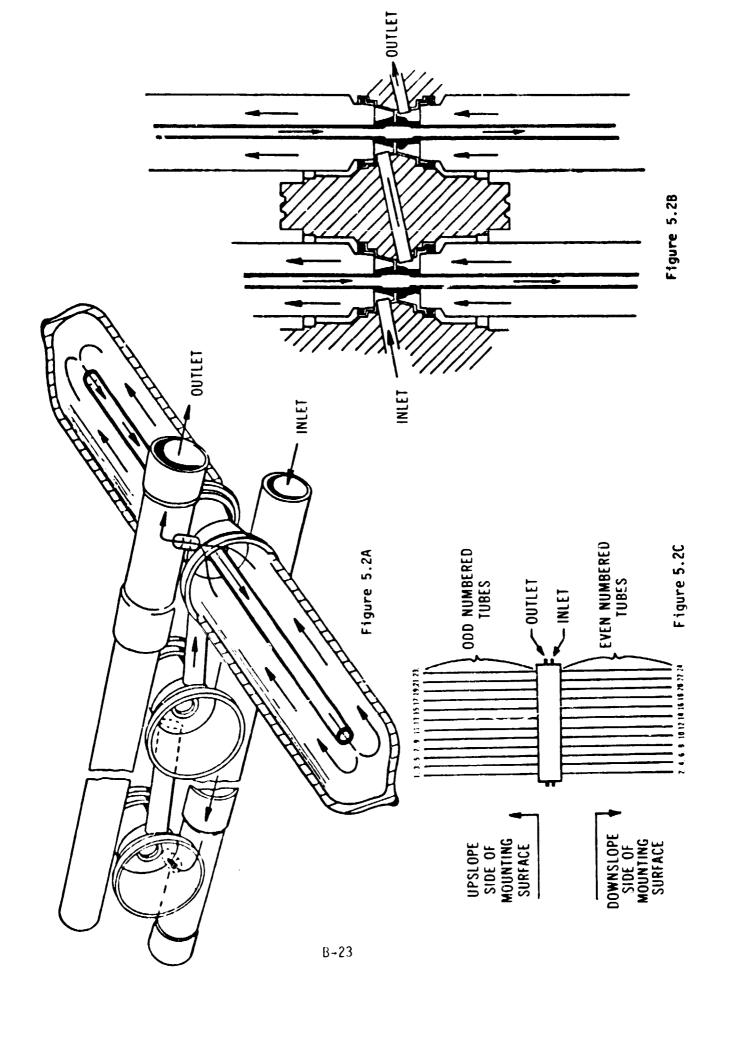


Figure 5.1



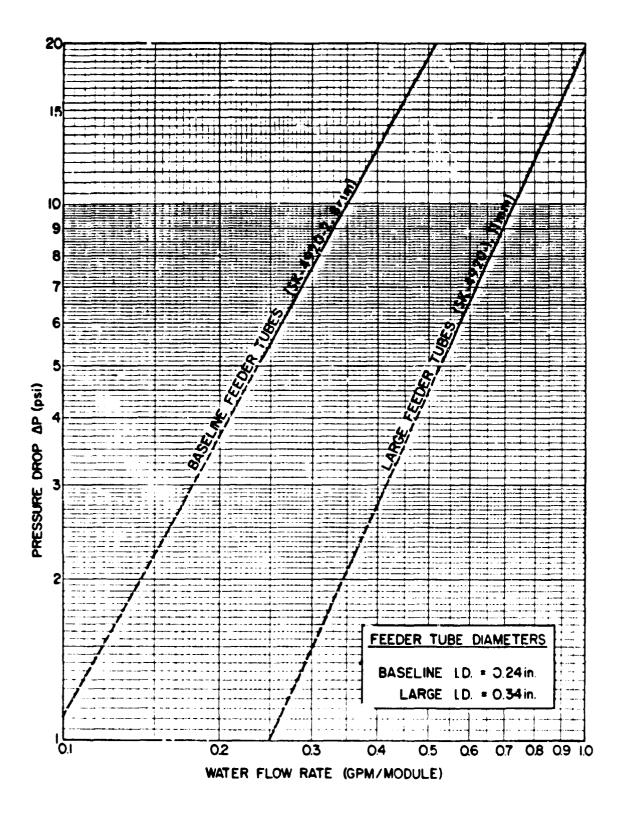
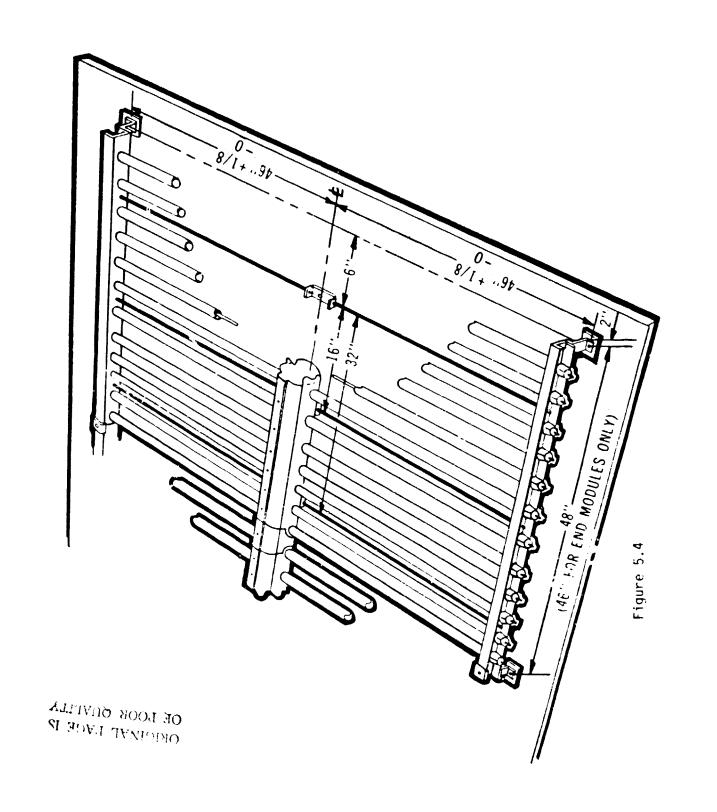
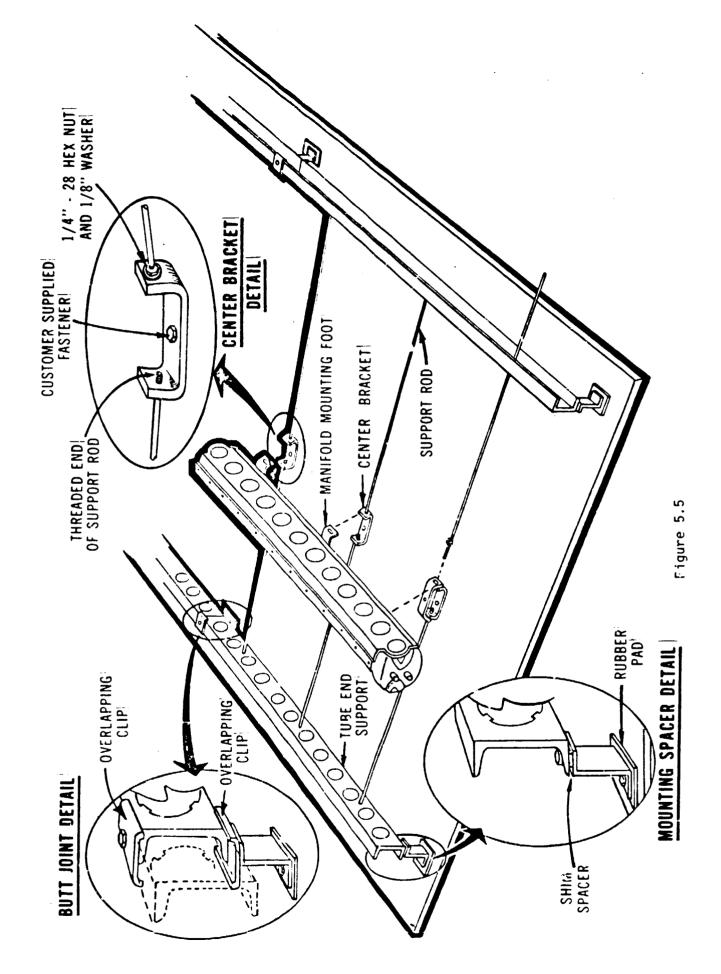
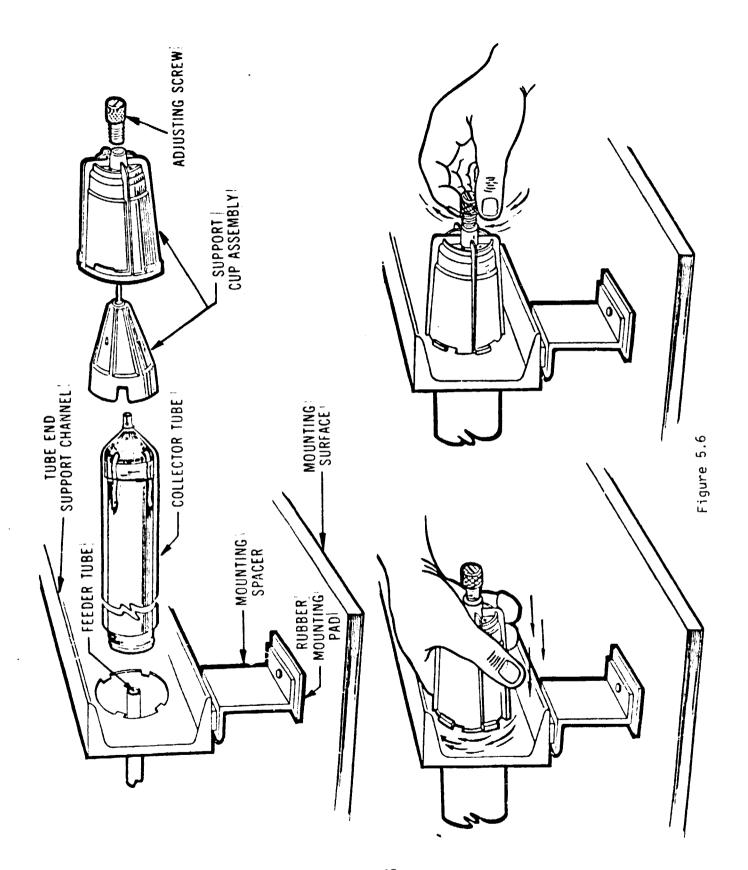


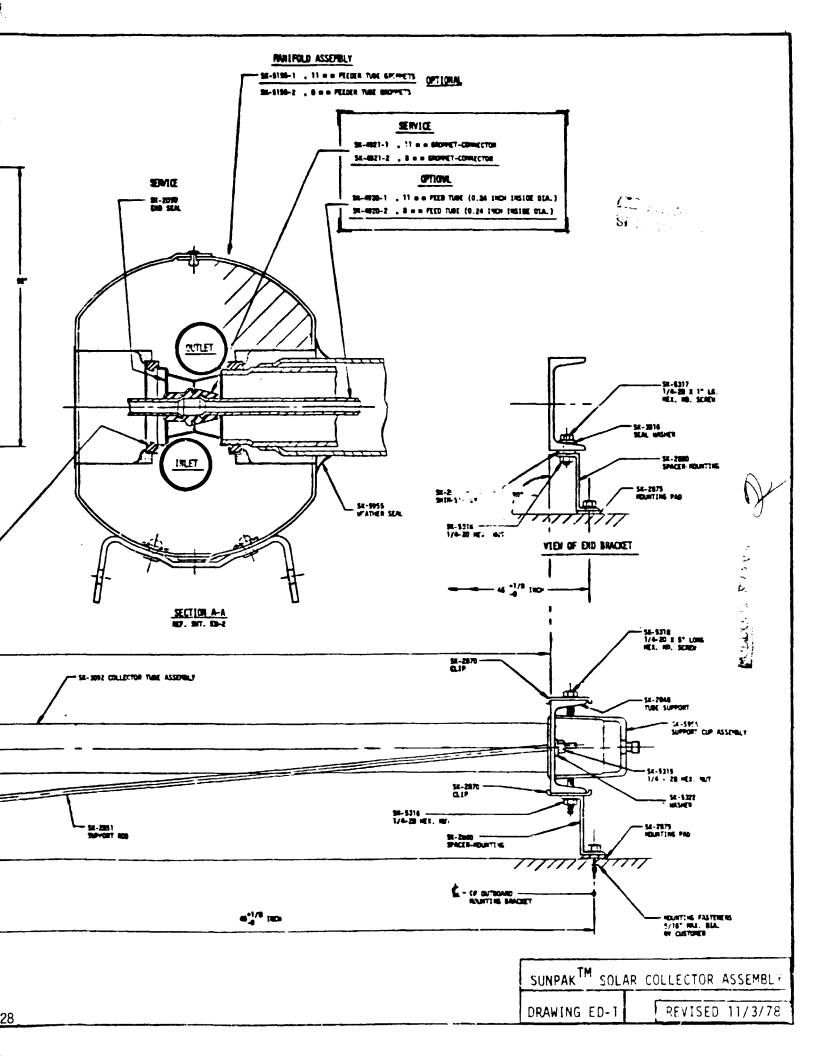
Figure 5.3

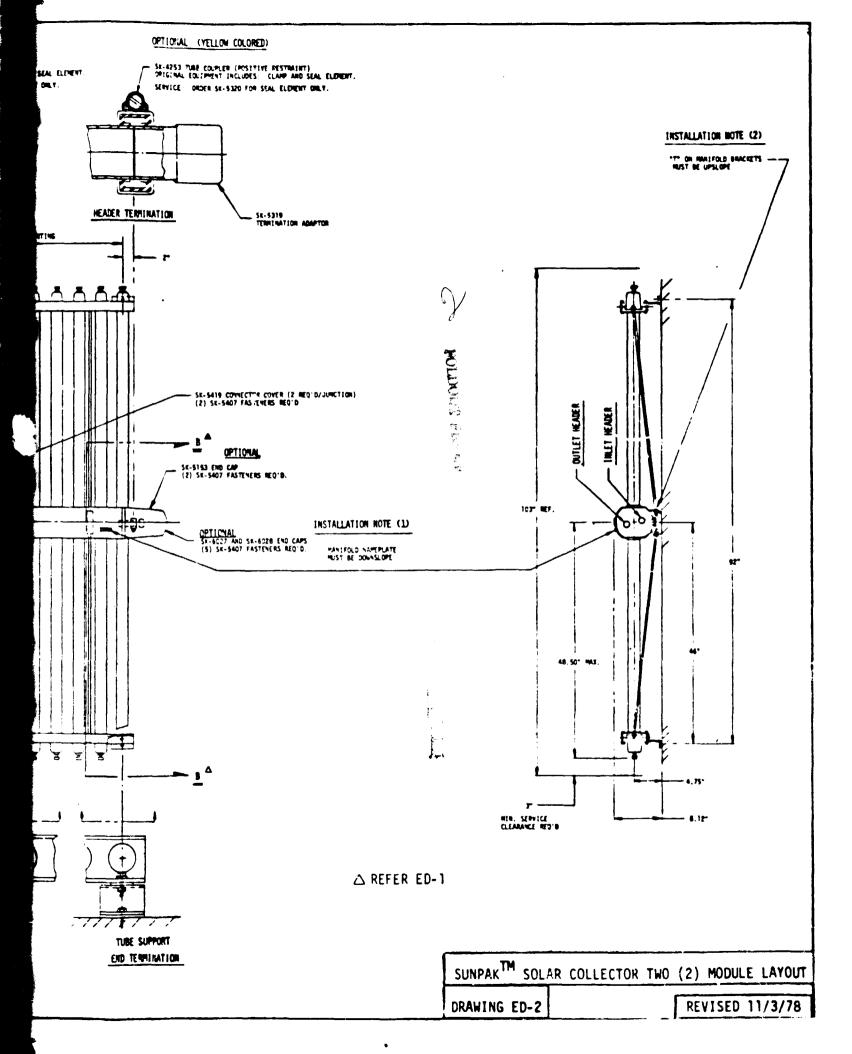
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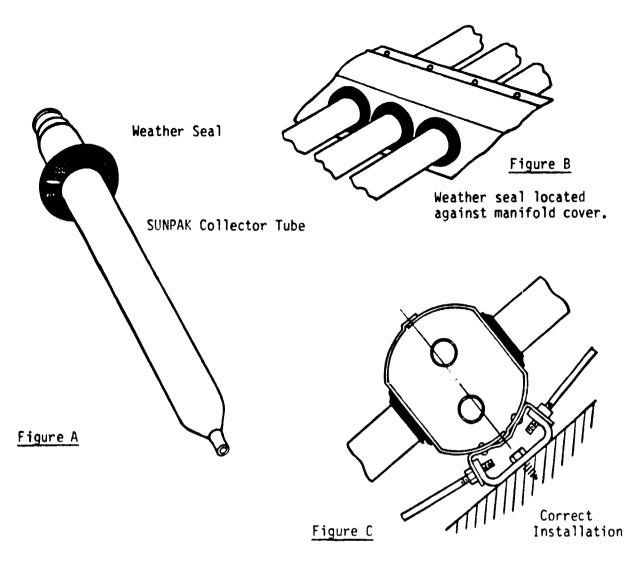








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### 1.0 Description

Figure A illustrates the weather seal (SK-5955) inserted over a SUNPAK collector tube. The eather seal is a black rubber gasket 3-1/2" in diameter with an opening of 2" that fits over the collector tube. When installed it reduces the heat loss from the collector tube manifold connection.

### 1.1 Installation

The installation of the weather seal should be together with the feeder tube (SK-4920) and the collector tube (SK-3092) installation described in Section 2.5 of the SUNPAKTM Solar Collector Installation, Service, and Operating Manual.

The weather seal is placed over the collector tube about 3-6" from the neck end prior to installing the tube into the manifold. After insertion of the collector tube into the manifold and adjustment of the support cup assembly (SK-3048), the weather seal may be located against the manifold cover. The rubber weather seal should be brought into contact with the manifold cover so that it lies snugly on the cover (Figure C). The seal is not to be forced into the manifold opening between the glass and manifold wall. Proper installation of the rubber weather seal will prevent most rain and snow from entering the manifold cup hole.

## APPENDIX C CONTROL SYSTEM DRAWINGS, HONEYWELL

# TEMPERATURE CONTROL FOR

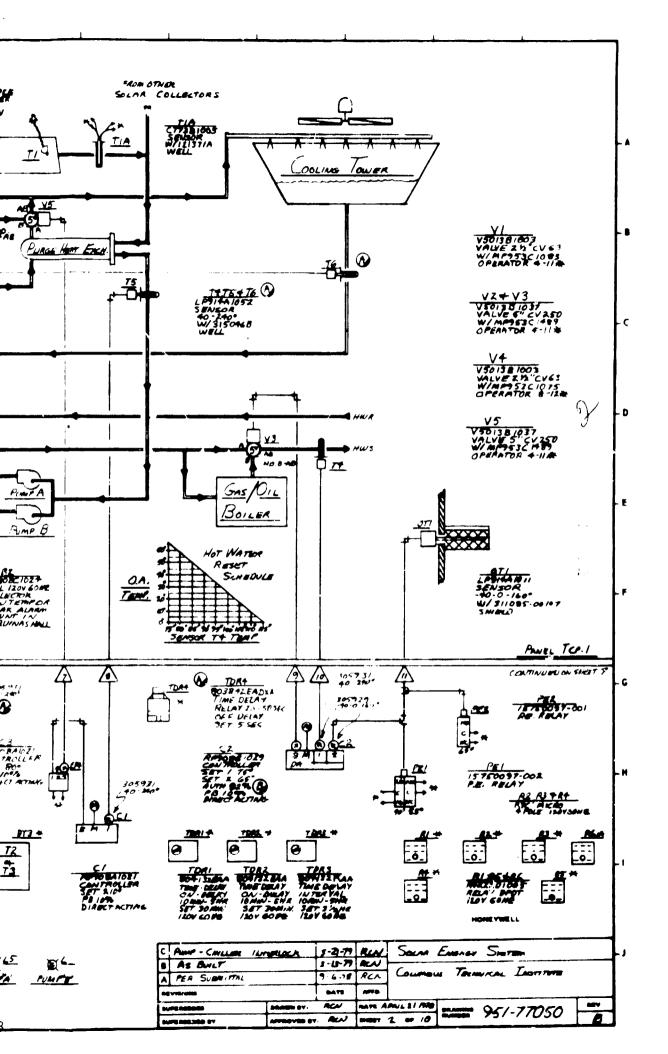
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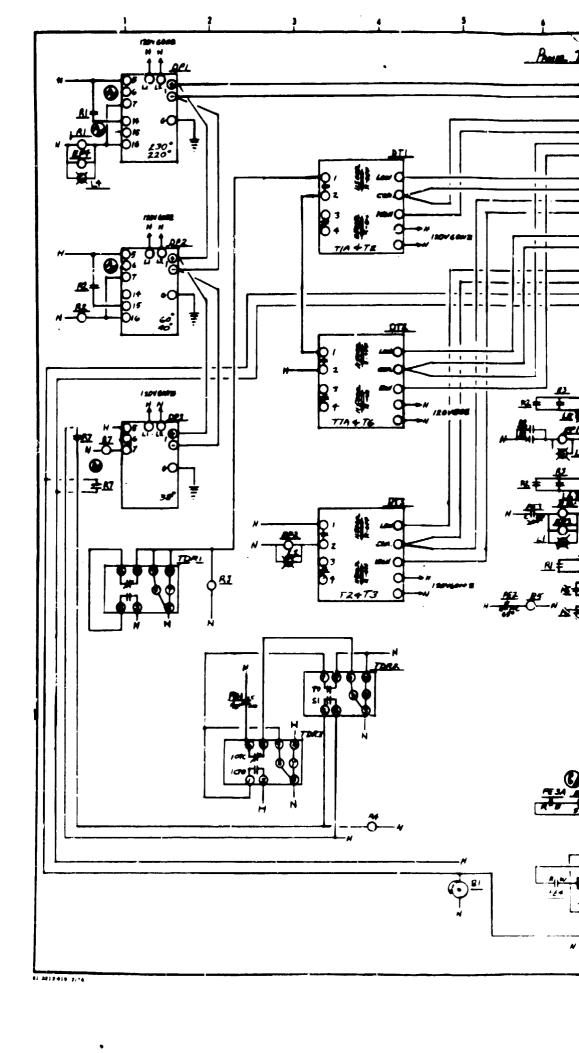
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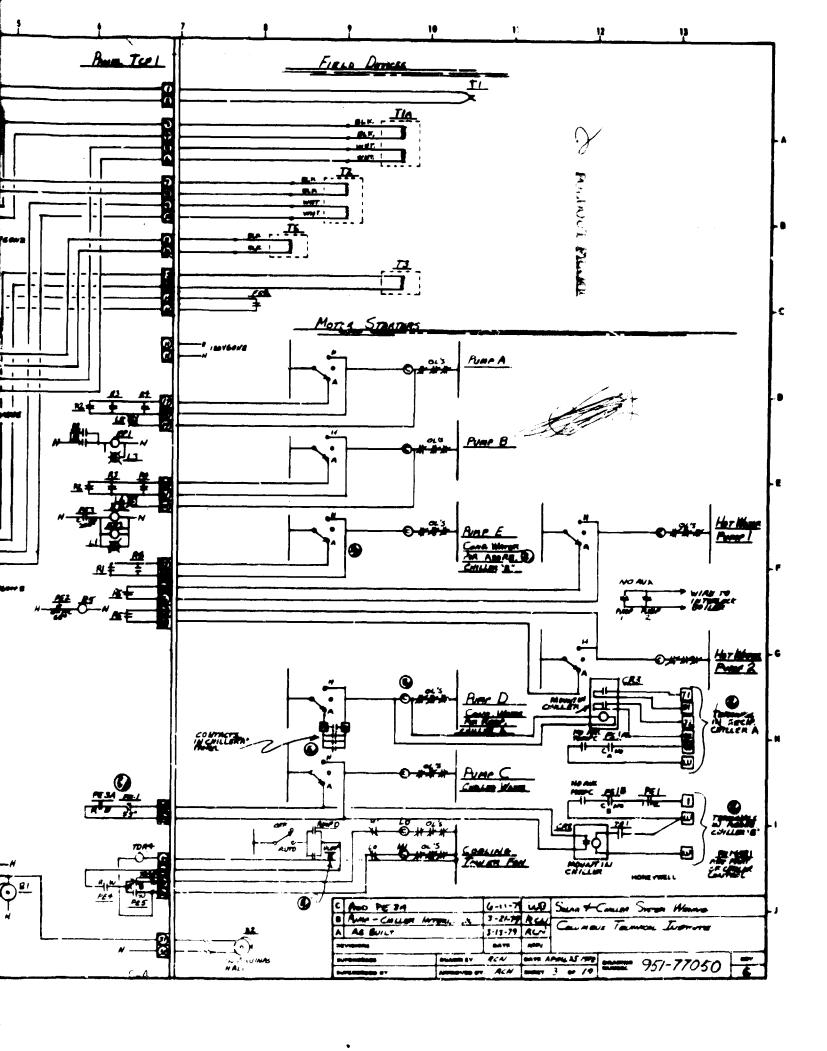


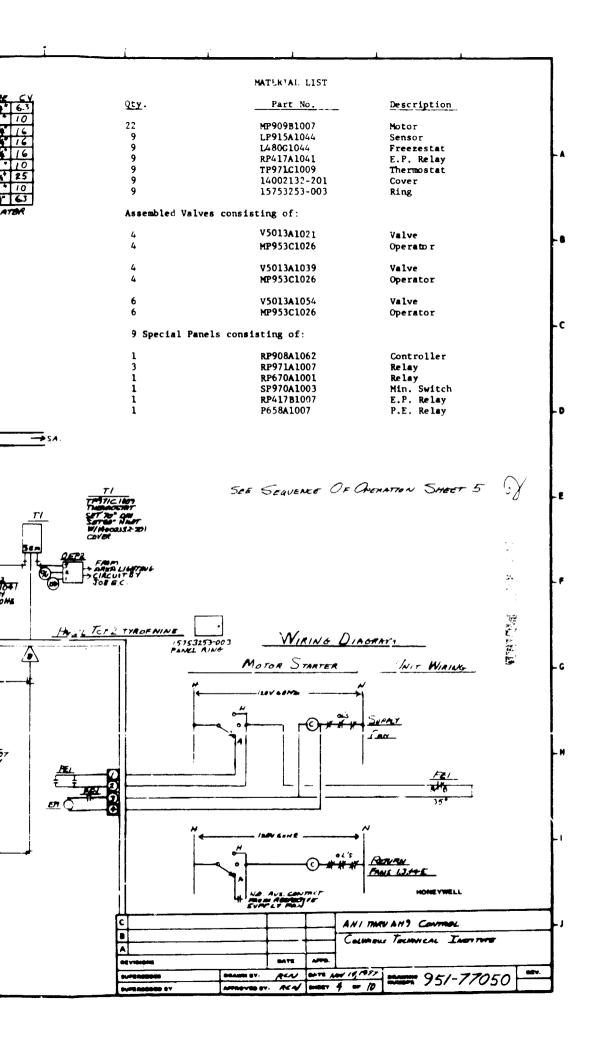
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### Solar Energy Control System

When the solar collector discharge temperature is higher than the storage tank, solar hot values "A" & "B" run for a minimum of \$\frac{1}{2}\$ hour and continue to run as long as the collector in than the tank. Pumps "A" and "B" also run continuously if sensor T1 in the collector discharge. If the outside air temperature drops below 40°, pumps "A" and "B" cycle on for \$\frac{1}{2}\$ he every four hours. Anytime the collector discharge temperature drops to 40°, pumps "A" and run until the discharge reaches 60°. When pumps "A" and "B" run, valve V4 positions for fit to the storage tank.

If the collector discharge temperature exceeds 230°, pump "E" and the cooling tower fans me and valve V5 is put under control of sensor T5 to maintain 210° until the collector discharge temperature drops to 220°. When pump "E" is off, valve V5 bypasses the purge converter.

If the collector discharge temperature drops below 38°, or sensor Tl fails or the leak detector senses flow in the make-up line, a bell in the panel and a remote bell in Aquinas Hall rings until the condition is corrected.

Boiler Operation When outside air temperature is below 65°, hot water pumps 1 & 2 run. Valve V2 positions to bypass the storage tank anytime sensor T3 is warmer than the storage tank. Valve V3 is positioned according to the reset schedule shown.

Chilled Water Sy:tem During the occupied cycle when the outside temperature is above 550 pump "C" runs. When the storage tank water temperature exceeds 200°, the absorption machine and condenser pump "E" and the cooling tower fan runs and valve V1 is allowed to modulate under control of the internal controller of the absorption machine until the tank AH1- thru 9 (Sheet 4) drops below/70°.

The supply fan runs continuously during the "occupied" mode and cycles to maintain the lower night setting of the thermostat in the "unoccupied" mode. When the

specified lighting circuit for the unit is energized, the unit is automatically put in the "occupied" operation.

The space thermostat modulates the mixing dampers, the heating coil valve, and the

cooling coil valve in sequence to maintain its setting. The mixing dampers can be overridden by the mixed air low limit. The Central Economiser signal closes the outside damper to minimum position when the outside temperature exceeds 68°.

If the freezestat renses heating coil discharge temperature of  $35^{\circ}$  or less, the fan stops and the outside damper closes. The freezestat must be manually reset.

### Sequence of Operation - Heat Wheel - PhotoLab Area (Sheet 6)

The photo area unit supply & exhaust fans run during the "occupied" cycle to supply the duct coils.

During "unoccupied" cycle the fans are off and the outside damper closes. If the space temperature falls below the setpoint of the night thermostat, the fans run with the outside damper closed and the bypass damper open. If the designated lighting circuit is energized, the system is put in "occupied" operation.

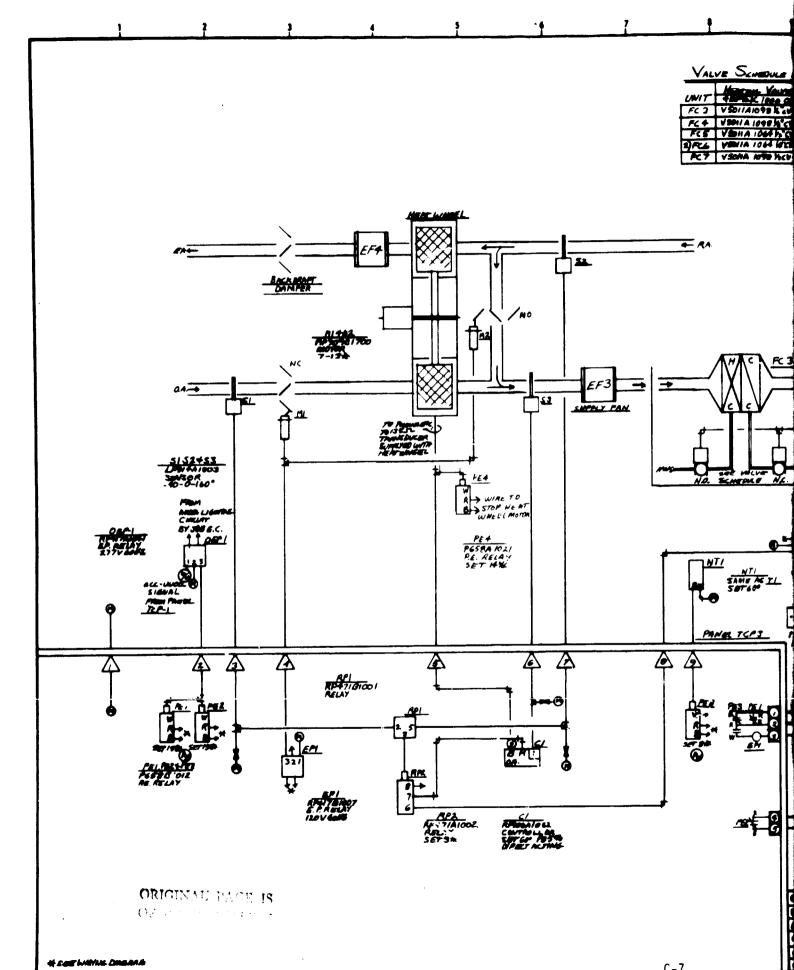
#### Cooling Tower Control

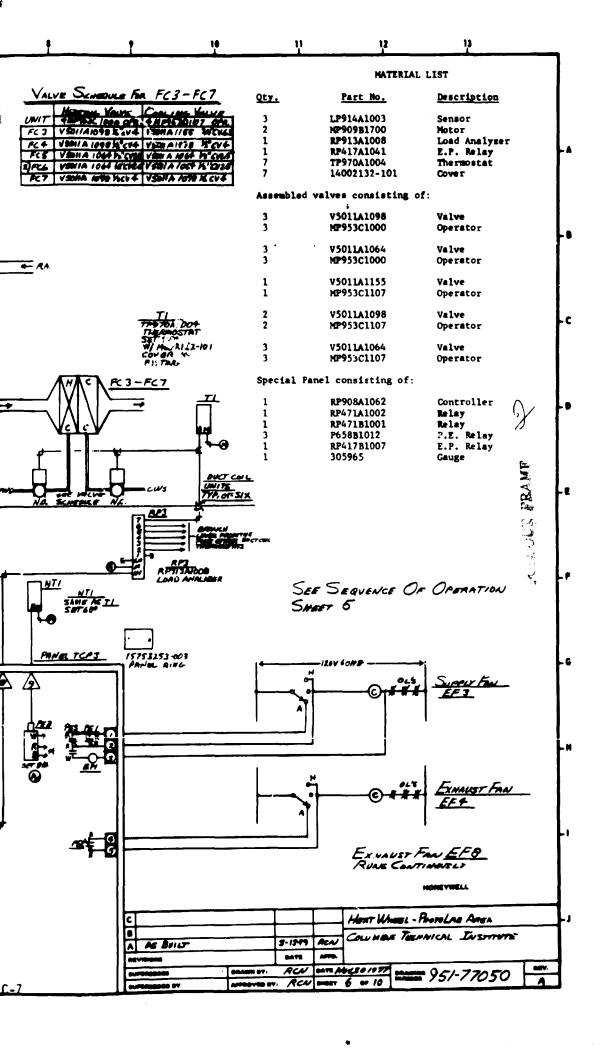
The tower fan is interlocked with the condensor water pumps, and runs in low speed when the condensor water temperature rises above 75° and goes to high speed any time the condensor water temperature reaches 80°.

ARCHITECT: ENGINEER: CONTRACTOR

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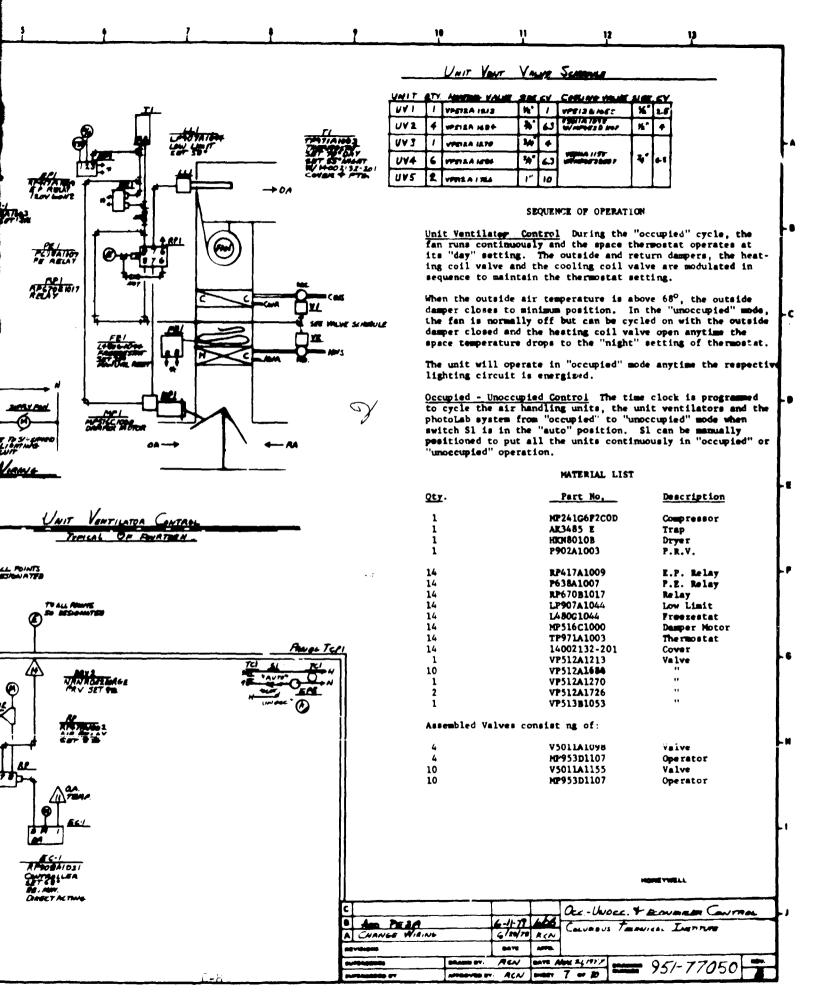


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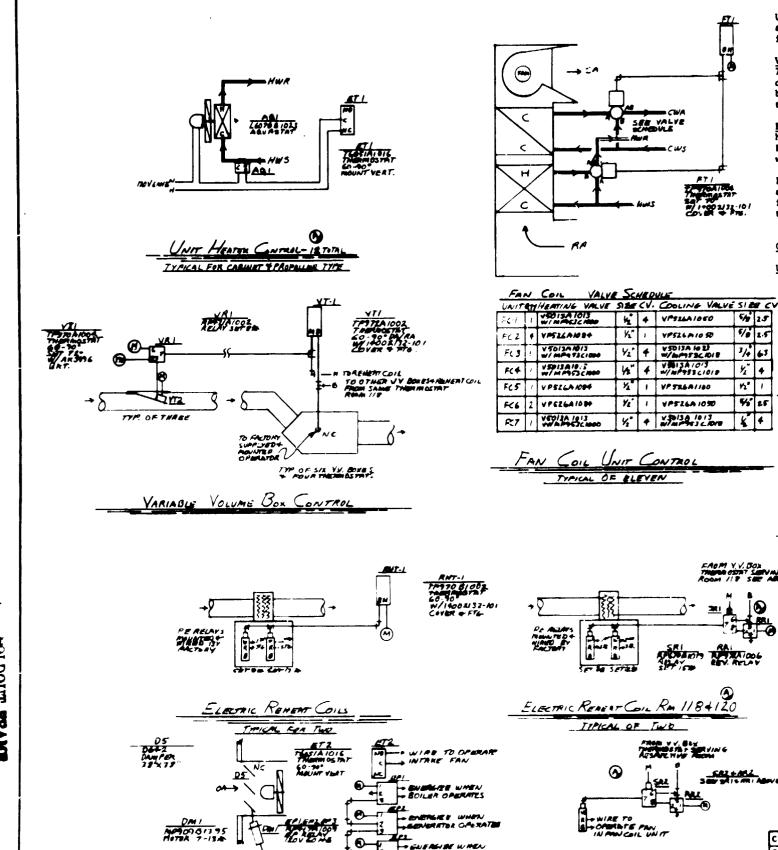
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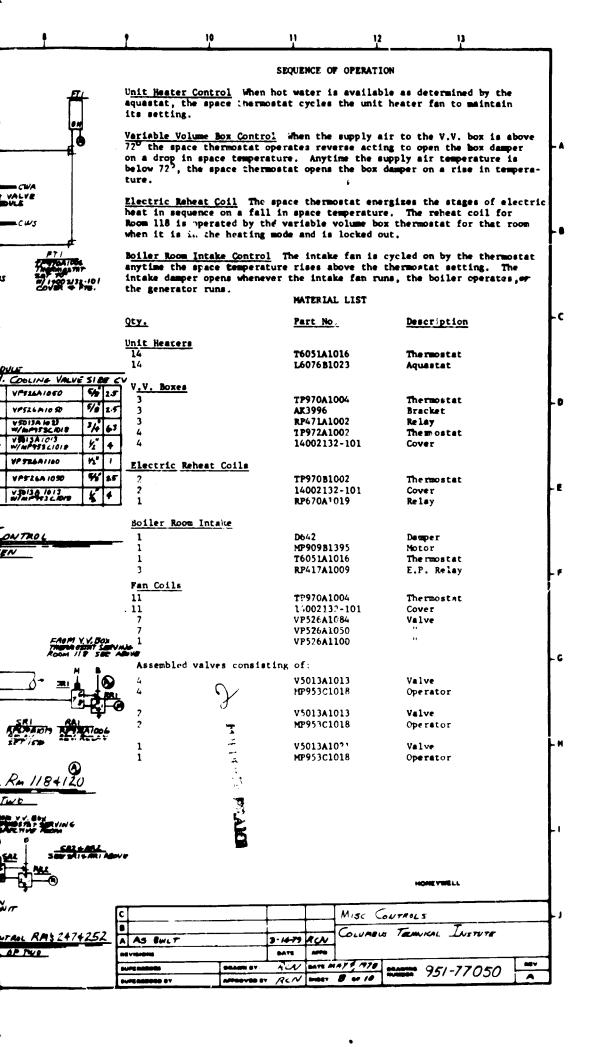
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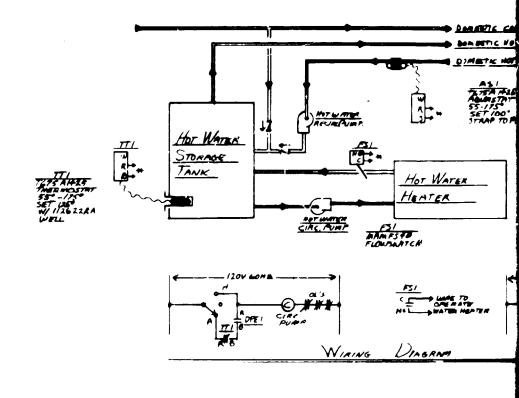


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C-9

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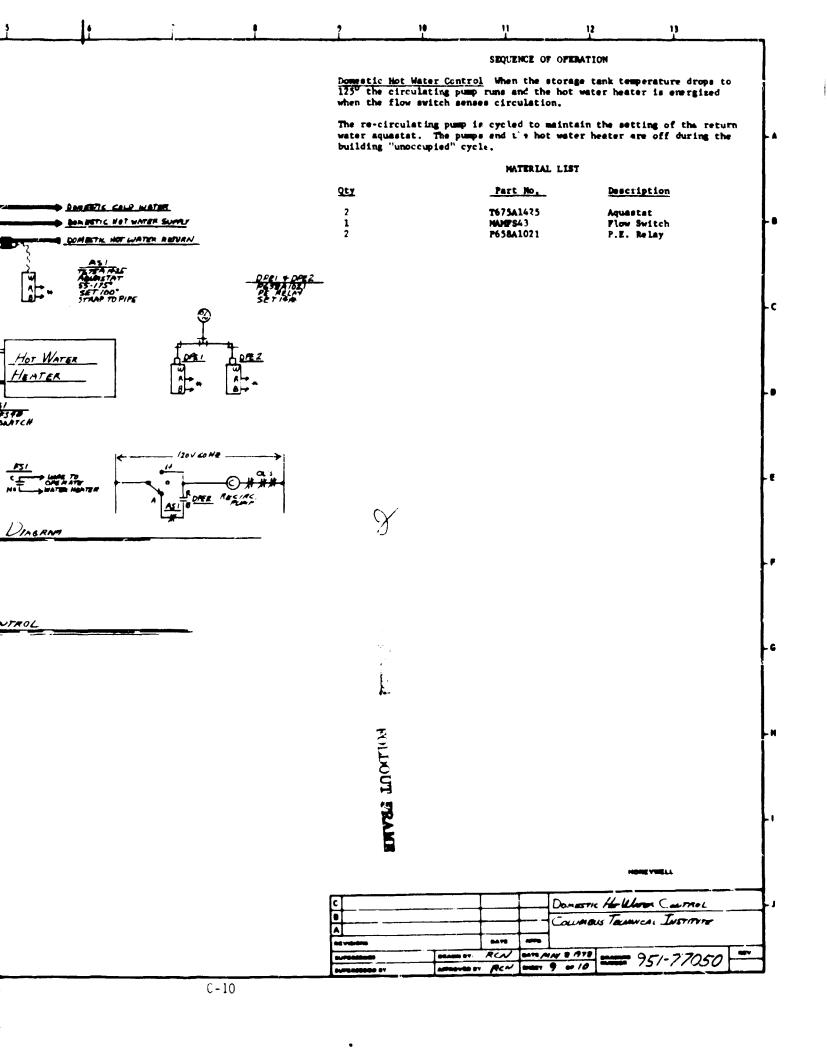




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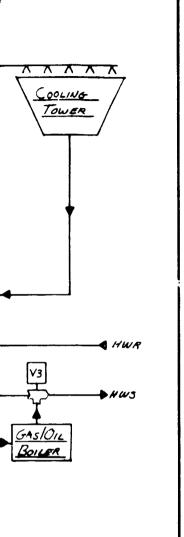
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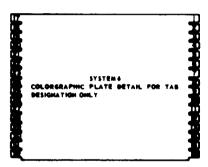


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FOR TEMPORARY & PERMANENT FILM STRIP & SLIDES. USE AREA WITHIN DOTTED LINES ONLY



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APPENDIX D

SOLAR DATA ACQUISITION & REDUCTION SYSTEM, REMTECH

# OPERATIONAL MANUAL AND USER'S GUIDE FOR SOLAR DATA ACQUISITION AND REDUCTION (SDAR) SYSTEM

September, 1979

REMTECH, Inc. 2603 Artic Street, Suite 21 Huntsville, Alabama 35805 (205) 536-8581

#### FOREWORD

This manual provides information for the operation of a computer based data acquisition and reduction system. This system was developed under contract to Columbus Technical Institute, Columbus, Ohio, 43215. The cognizant administrative and procurement contact at Columbus Technical Institute was Mr. Russell W. Jordan, Administrative Assistant to the President. Technical direction for this system was provided by Mr. Dick Pearson and Mr. Rick Pavlak of Heapy and Associates, Dayton, Ohio, 45402. Development and assembly of the system at REMTECH was under the direction of Mr. Jim Levie and Mr. Gene Fuller.

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#### Section 1.0

#### INTRODUCTION

This document provides all the information needed to understand and interface with the microprocessor based data acquisition and reduction system. The system is referred to as the SDAR which stands for Solar Data Acquisition and Reduction. This name is descriptive of both the application and the function of the system.

A schematic of the system arrangement is shown in Fig. 1. The system is built around a Digital Equipment Corp. (DEC) LSI#11/2 general purpose 16 bit microcomputer processor module. With the use of this CPU, the system requires no operator intervention or programming on power up. The added computational power and speed which results from the extended instruction set found in 16 bit machines allow 32 bit floating point single precision calculations and English language commands for system manipulations. The system will interrogate up to 32 signal ended analog inputs at programmed intervals, convert the voltage measured to engineering units, calculate heat flows through the system, display the results on a video monitor, and log system parameters on a cassette tape. The system has been installed and programmed to provide performance data on the solar system installed on the administrative building at Columbus Technical Institute. The solar system consists of 4,000 ft² of evacuated tube collectors designed to provide 70% of the building's heating and 35% of the building's cooling (absorption in series with electric chiller).

The SDAR will provide continuous unattended operation and performance of its programmed tasks. Access to the system is available either by the display lobby terminal or by terminal access via telephone line modem.

# INPUT DATA CHANNELS 32 SINGLE ENDED OR 16 DIFFERENTIAL INPUTS

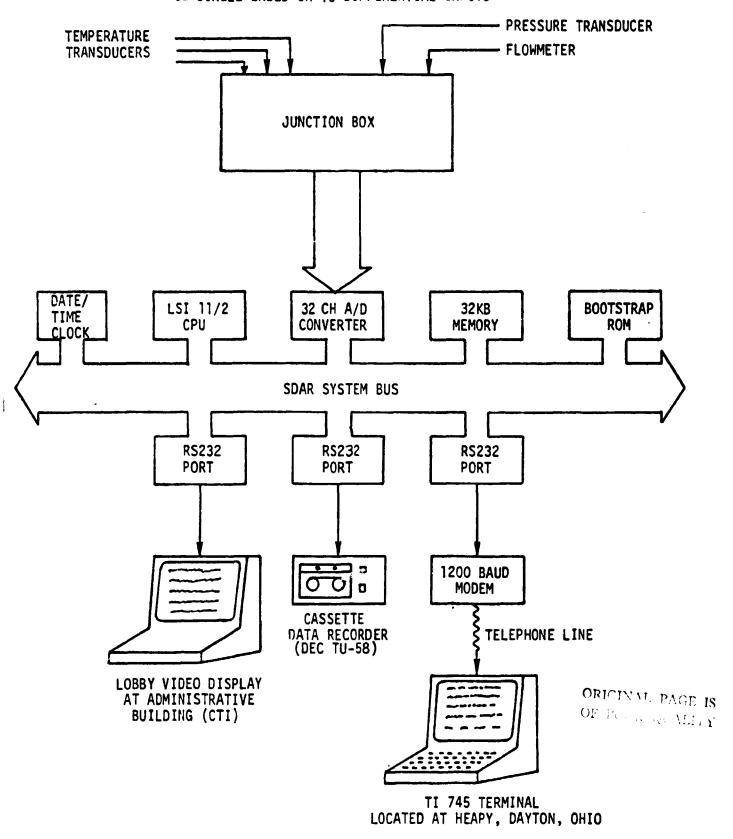


Fig. 1 Schematic of Site Data Acquisition and Reduction (SDAR) System for Columbus Technical Institute (CTI)

The remaining sections provide more detailed descriptions of the hardware and software, along with specific step-by-step instructions for data retrieval and other allowable system operational inquiries and changes.

#### Section 2.0

#### SCOPE OF WORK

The SDAR system was designed, constructed, and programmed to provide Columbus Technical Institute with an instrumentation package for solar energy heating and cooling that performs the following functions:

- 1. System allows for at least 32 analog inputs to measure temperature and flow rates as shown in Heapy and Associates drawing SM-1 and 2 for the Solar Monitoring System for Columbus Technical Institute.
- 2. System uses information collected to calculate and return energy data in engineering units (BTU, °F, etc.).
- 3. System records information on a magnetic tape recorder.
- 4. System is accessible by remote telecommunication device (Hard Printer Terminal) thru a telephone modem.
- 5. System has an information display that changes to display the last recording periods' information.
- 6. System provides as a minimum the following information:
  - (a) BTU's available
  - (b) BUT's used for cooling
  - (c) BUT's of cooling by each chiller
  - (d) BTU's used for heating
  - (e) BTU's of heating by boiler
  - (f) BTU's put in storage
  - (g) Total BTU's used or stored

In addition, other information is provided as may be derived from the points monitored.

# Section 3.0

#### HARDWARE CONFIGURATION

The SDAR consists of (See Fig. 1)

DEC LSI 11/2 16 bit processor

32KBytes of semiconductor read/write memory

32KBytes of semiconductor read only memory

32 differential analog inputs

RS232 port for video monitor, cassette logger and modem control

Non-volatile system clock

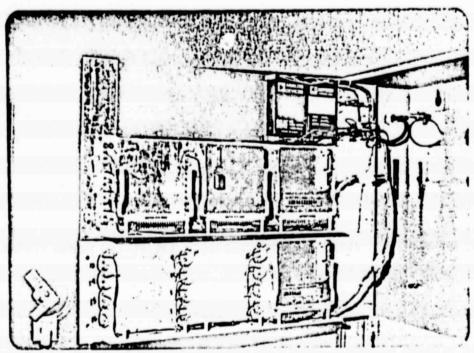
Lobby display terminal

Signal conditioning and junction enclosure

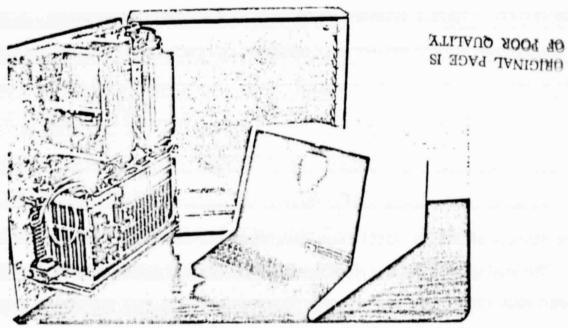
The SDAR is mounted within a NEMA 1 enclosure and requires normal 110 VAC power. A companion NEMA 1 enclosure junction box is used to terminate all input channels and to provide transducer power and signal conditioning for turbine flow meters. Figure 2 provides photographs of the completed hardware.

The video display monitor is a standard 24 line by 80 column CRT. It allows system parameters to be displayed, and if desired, may be used to interact with the SDAR in the same manner as a remote terminal. A 300 baud modem with remote dial-up capability is provided to allow access to the SDAR from a remote terminal. This modem does not require special telephone lines. Also provided is a cassette data storage medium (Digital Equipment Corp. TU-58) allowing off-line storage of 145,000 ASCII characters or 29,000 data records.

The analog to digital system used in the SDAR can accommodate up to  $\pm$  30V of common mode noise. The system clock is nonvolatile and will run on its internal rechargable battery for a minimum of 30 days before loosing its data. No battery back up is required for the SDAR in this installation. If power failure



Interior of Terminal/Signal Conditioning Enclosure



Interior of Computer Enclosure and Lobby Display Terminal

Fig. 2 Physical Appearances of SDAR Enclosures and Terminal.

should occur, the SDAR will automatically reboot and reload, and continue its programmed tasks when power is restored. This is accomplished without operator intervention.

#### Section 4.0

#### SYSTEM SOFTWARE

Descriptions are provided here of the general software arrangement and the specific software which provides access to the system operation. Step by step descriptions are provided to allow an operator the ability to easily and successfully interface with the system.

# 4.1 General Descriptions

All application software is contained on a 15K word PROM/BOOTSTRAP board. The software was developed on REMTECH's PDP11V03 minicomputer using high level languages (FORTRAN, MACRO-11) and loaded into PROM (Programable Read Only Memory). This allows the applications software to be tailored to the user's needs in a cost effective manner and allows a wide range of SDAR options to be implemented initially or at a later data. Some of the optional functions available include:

Dual Disc Drive with RT11 Operating System

Additional Analog Inputs

Digital or Analog Control Signals

Control Alarms and System Status Indicators

**Graphics Display Systems** 

Hardcopy Plots

Hardcopy Printouts

Standard 9 Track Tape for Data Storage

These options are not included in the configuration provided since the specifications did not require these options.

Since the software is contained in ROM (Read Only Memory) the system will, following power up, automatically conduct processor and memory diagnostics, load, and begin execution of the program. When the program is loaded, a set of default values are also loaded which specify the channels and constants to be used for calculation of system heat flows and temperatures, the data channels to be monitored and the sampling frequency (normally 1 minute). These defaults can be changed by an operator at any time through the modem interface or the lobby terminal.

An operator can, via a remote terminal or the lobby terminal, call the SDAR and perform certain program manipulations. When called, the SDAR acknowledges the call and requests a password. When the correct password has been received, a menu of tasks is presented. By choosing tasks from the menu the operator can make changes in the SDAR's operations, such as; changing the constants used in heat flow calculations, resetting the date and time kept by the system clock, changing the recording interval, or dumping the data from the data cassette to the remote or lobby terminal. By implementing these programming tasks under SDAR control as a menu, the necessity for highly trained operators is eliminated and the possibility of operator induced malfunction is eliminated. This is unlike other systems which must be programmed before use and are thereby subject to time consuming and costly program development and debugging procedures with possible operator induced program failure. Since all dialog between the operator and the SDAR is in an English language form, the possibilities for error are further reduced. In addition, the SDAR software conducts extensive checks to determine the validity of the operator commands and to insure that any numerical input data is within a reasonable range.

# 4.2 Specific Software and System Operation

As presently configured, the SDAR will scan and convert to engineering units the 23 channels of data listed in Table 1. Using this data, along with the input system constants of Table 2, calculations of the system performance parameters listed in Table 3 are also performed. These scanning and calculating functions are performed at one minute intervals. The selected information shown in Fig. 3 is updated each minute with the new scan calculations and displayed to the lobby terminal, in order to inform the public on a real-time basis of the solar system's operational status and energy and monetary savings. As far as possible, the performance calculations and system nomenclature in Tables 1 - 3 have been made in accordance with the standards used by the National Solar Data Network as defined by the National Bureau of Standards Report, 76-1137, "Thermal Performance Evaluation Procedures for the National Solar Heating and Cooling Demonstration Program." This allows for easier data comparisons with other systems.

A user selected recording interval of from 1 to 59 minutes, instructs the SDAR to record to tape a date/time group, each of the 23 channel calculations, and the 19 system performance calculations at the selected recording interval. At the end of each 24 hour period a record summarizing the system's performance for that period is written to the system tape for use by the lobby display module.

Periodically, the SDAR will poll both the lobby display terminal and the remote terminal connection to determine if access is required to the system. When an active terminal is detected the SDAR will issue a password request. The lobby display CRT is considered active when the "ONLINE/OFF LINE" switch is

Table 1
INPUT CHANNEL ASSIGNMENTS
(September 1979)

Channel	Sensor	Variable	Function	
1	ΙΊ	1001	Incident solar energy	
2	T15	T001	Outdoor air temperature	
3	Т6	T100	Collector inlet/Absorbtion chiller outlet	
4	TI	T101	Collector outlet/Purge inlet	
5	T12	T102	Purge outlet	
6	F1	\$100	Collector pump status	
7	T2	T200	Storage tank temperature	
8	T7	T400	Storage outlet/Boiler inlet	
9	T3	T401	Heating loop return	
10	T8	1402	Boiler outlet	
11	T4	T403	Heating loop supply	
12	R2	5400	Heating loop pump status	
13	R3	\$401	Boiler status	
14	FM1	W400	Heating loop flow rate	
15	TII	T500	Absorbtion chiller inlet	
16	T14	T501	Cooling loop return/Absorbtion chiller load inlet	
17	T9	T502	Absorbtion chiller load outlet/Electric chiller inlet	
18	T10	T503	Cooling loop supply/Electric chiller load outlet	
19	T13	T504	Cooling tower inlet	
20	Т5	T506	Cooling tower outlet	
21	R4	\$500	Cooling loop pump status	
22	R5	\$505	Absorbtion chiller status	
23	R6	\$506	Electric chiller status	

Table 2
REQUIRED SOLAR SYSTEM CONSTANTS\*

```
AREA - Collector area -(3507.2 sq. ft.)
W100 - Collector loop flow rate -(60 GPM)
EP101 - Collector pump operating energy -(11.5 KW)
W400 - Flowmeter conversion data -(1 pulse/10 gal 350 max - 100 min)
EP400 - Heating loop pump operating energy -(31 KW)
W500 - Cooling loop flow rate -(300 GPM)
EP500 - Cooling loop pump operating energy -(15.5 KW)
EP504 - Cooling tower operating energy used by absorption chiller -(3.46 KW)
EP505 - Absorption chiller operating energy -(3.8KW)
W505 - Absorption chiller load flow rate -(1606 GMP)
W506 - Electric chiller load flow rate - (3006 GPM)
HTCOST - Cost per Btu of conventional heating-($7.49/1 x 106BTU)
CLCOST - Cost per But of conventional cooling-($2.00/1 x 106BTU)
MININ - Insolation required for useful solar collection -(20 BTU/sq.ft.)
```

\* Data in ( ) are the constants in program supplied on September 1979.

These constants may be changed by the use of Task 4 in the SDAR System Task List.

Table 3
SYSTEM PERFORMANCE CALCULATIONS

Solar energy available:	$Q001 = \int I001 \cdot AREA \cdot dt$		
Solar energy collected:	Q100=\( (T101-T100) \cdot \text{W100 \cdot S100 \cdt}		
Solar energy purged:	Q101=\int (T101-T102). W100.dt		
Solar collector operating energy:	Q102= \int EP101 \cdot S100 \cdot dt		
Collector efficiency:	N100=(Q100/Q001)		
Solar energy to storage:	Q200=Q100- <b>Q</b> 101-Q500		
Solar energy to heating load:	Q400=Q402-Q401		
Auxiliary energy to heating load:	Q401=\int (T402-T400) \cdot \text{W100 \cdot S401 \cdot dt}		
Heating load:	Q402=\int (T403-T401) \cdot \wdov-S400 \cdot \dt		
Solar heating loop operating energy:	Q403=\int EP400 \cdot (S400-S401) \cdot dt		
Solar energy to absorption chiller:	Q500=\int (T500-T100) \cdot \text{W100} \cdot \text{S505} \cdot \text{dt}		
Cooling loac:	Q502=\int (T501-T503)\cdot \wxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxx		
Absorption chiller operating energy:	Q503= $\int$ (EP500+EP504+EP505)·S505·dt		
Absorption chiller load:	$0505 = \int (T501 - T502) \cdot W505 \cdot S505 \cdot dt$		
Electric chiller load:	$0506 = \int (T502 - T503) \cdot W506 \cdot S506 \cdot dt$		
Absorption chiller coefficient of performance:	N500=Q505/(Q503+Q102)		
Energy saved:	Q606=Q400+Q500-Q102-Q403-Q50 <b>3</b>		
Dollars saved:	D606= (Q400-Q403-(Q102·Q400)/(Q400+Q500)) • HTCOST+ (Q500-Q503-(Q102·Q500)/(Q400+Q500)) • CLCOST		
Hours of useful solar energy:	S001= 0.0 if I001 MININ		
	H001=∫S001 dt		

26 AUG 79 11:30 A.M. YESTERDAY 1.235 LAST 30 DAYS 3.005 ***********************************
---

ig. 3 SDAR Display on Lobby Terminal

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in the "ON LINE" position. The modem and telephone line interface becomes active if the modem has been called. The call will prompt the modem to indicate to the SDAR that the remote terminal line has become active. When either of these terminals become active, the SDAR will respond with a password request. If the correct password is not received by the lobby terminal or modem terminal within 30 seconds, the SDAR resumes its normal mode of scanning channels, performs calculations, etc.

There are two possibilities with this access procedure that can cause difficulties with the SDAR operation. The first possibility is that the switch on the lobby terminal is turned to "on line" position accidently or remains in the "on line" position for an extended period. If this occurs, the SDAR will continue to display and update information to the terminal, however, the keyboard will be "live," and therefore characters can be typed to the display, thus, scrambling the display. This scrambled display does not affect the SDAR's assigned software operations. However, with the terminal switch in the "on line" position, the modem/remote terminal will be unable to call the unit. The obvious remedy for this problem is to turn the "on line" switch off.

Another system difficulty can occur if the SDAR is called by the remote/
terminal and access is obtained but not returned to the SDAR data collection
program. In this case, the SDAR has essentially become non-functioning in that
the data collection routine is not being performed. As defined below, the method
for correcting this problem is to envoke Task 6 of the System Task List which
allows for return of the program to data collection.

As indicated above, when an active terminal is detected by the SDAR a password request is issued to the terminal user. A valid password must be keyed in by the terminal user within 30 seconds. If the password is not received by

the SDAR it will return to its normal data acquisition mode and will not acknowledge the terminal again until it has been off line for at least one minute. The user should recall the system by telephone modem after one minute or reset the "on line" switch in order to obtain a new opportunity to enter a password.

The system password which allows access to the system task list is

SDARMANGR

which stands for Solar Data Acquisition and Reduction Manager.

After the above password has been received the SDAR will print the SYSTEM TASK LIST at the terminal and wait for the operator's response. Examples of the implementation of each task are provided on the following pages. The examples illustrate the messages which an operator will see displayed when implementating each task. The symbol ">" on the display indicates that the SDAR is waiting for an acceptable response from the operator before it proceeds.

## NOTE:

While the SDAR is performing operations in the system task list, none of the programmed system data acquisition and computation functions will be performed. For this reason, the historical computations will be inaccurate, if the use of the system task lists are utilized for large periods of time. To minimize these inaccuracies it is recommended that access to the Task List be made during periods when there is minimum solar and/or total HVAC system activity.

# TASK 1 - DATA TAPE CHANGE

ENTER PASSWORU >SDARMANGR(Note - the password will not be printed) VALTD PASSWORU RECEIVED - WATT

2 AUG 79 22:25

#### SDAR SYSTEM TASK LIST

- 1 Data Tare Change
- 2 Real Time Data List
- 3 List Recorded Data
- 4 Chanse Constants
- 5 Reset System Clock
- 6 Return to Wata Collection Program

OF FOOR GUALTER OF PAGE IN

Enter the task number to be executed >1 DAIN TAPE CHANGE-DAIN TAPE CHANGE-Drive \$1 Tape Change - Are you sure?(Y/N) >Y Ready for tape change - Type \*F\* when done.>F

# NOTES: Task 1

- 1. Drive #1 is the right hand drive unit when facing the SDAR.
- 2. Only the data tape in Drive #1 should be replaced.
- 3. The system program tape in Drive #0 should not be removed unless authorized by cognizant personnel.
- 4. See Section 5.1 for further explanation.

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## TASK 2 - REAL TIME DATA LIST

#### 2 AUG 79 22128

#### SUAR SYSTEM TASK LIST

- 1 Data Tare Change
- 2 Real Time Data List
- 3 List Recorded Data
- 4 Change Constants
- 5 Reset System Clock
- 6 Peturn To Nata Collection Program

nter the task number to be executed >2 EAL TIME DATA LISTnter the number of scans to be listed >2

2 AUG 79 22:28:36 Scan number- 1

001/CH01 T001/CH02 T100/CH03 T101/CH04 T102/CH05 S100/CH06 T200/CH07 296.58tu/sqFt/Hr 59.6 F 97.8 F 155.3 F 123.7 F 1.0 S 100.2 F

400/CH08 T401/CH09 T402/CH10 T403/CH11 S400/CH12 S401/CH13 W400/CH14 54.2 F 93.1 F 122.9 F 122.9 F 0.0 S 0.0 S 0.0 GPM

500/CH15 T501/CH16 T502/CH17 T503/CH18 T504/CH19 T506/CH20 S500/CH21 S505/CH22 1 0 F 94.2 F 94.1 F 68.2 F 96.1 F 81.6 F 1.0 S 0.0 S

506/CH23

2 AUG 79 22:28:54 Scan number- 2

001/CH01 T001/CH02 T100/CH03 T101/CH04 T102/CH05 S100/CH06 T200/CH07 296.48tu/sqFt/Hr 59.6 F 97.8 F 155.3 F 123.7 F 1.0 S 100.2 F

400/CH08 T401/CH09 T402/CH10 T403/CH11 S400/CH12 S401/CH13 W400/CH14 74.1 F 93.2 F 122.9 F 123.0 F 0.0 S 0.0 S 0.0 GPM

500/CH15 T501/CH16 T502/CH17 T503/CH18 T504/CH19 T506/CH20 S500/CH21 S505/CH22 22.0 F 94.0 F 94.1 F 68.2 F 96.1 F 81.6 F 1.0 S 0.0 S

506/CH23 1.0 S

# NOTES: Task 2:

 Be careful in selecting the number of real time data scans desired. Since the SDAR data exchange rate is at 300 Baud, the exchange and printout of data can take longer than expected. Once the display of requested data has started it can not be stopped until completed.

# TASK 3 - LIST RECORDED DATA

# 2 AUG 79 22129

#### SDAR SYSTEM TASK LIST

- 1 Data Tame Change
- 2 Real Time Data List
- 3 List Recorded Data
- 4 Change Constants
- 5 Reset System Clock
- 6 Return To Nata Collection Program

nter the task number to be executed >3
ECURDED DATA LISTape starting Date/Time 2 AUG 79 18:05:00
ape ending Date/Time 2 AUG 79 19:10:00
ist data from this tape?(Y/N) >Y
nter starting Date(DD-MMM-YY) >02-AUG-79
AIT
nter ending Date(DD-MMM-YY) >02-AUG-79
AIT

2 AUG 79 18:05:00 Scan number 1

0/1/CH01 T001/CH02 T100/CH03 T101/CH04 T102/CH05 S100/CH06 T200/CH07 J.OBtu/sqFt/Hr 59.3 F 97.5 F 123.3 F 123.5 F 0.0 S 99.5 F

400/CH08 T401/CH09 T402/CH10 T403/CH11 S400/CH12 S401/CH13 W400/CH14 93.9 F 92.9 F 122.7 F 122.5 F 0.0 S 0.0 S 0.0 SPM

500/CH15 T501/CH16 T502/CH17 T503/CH18 T504/CH19 T506/CH20 S500/CH21 S505/CH22 2x.8 F 93.9 F 94.0 F 67.9 F 95.8 F 81.4 F 0.0 S 0.0 S

504/CH23

001-Btu 0100-Btu 0101-Btu 0102-Btu 0100-% 0200-Btu - 0.00E-01 0.00E-01 -3.35E+02 0.00E-01 00.0 3.35E+02

400-Btu 0401-Btu 0402-Btu 0403-Btu 0.00E-01 0.00E-01 0.00E-01

500-Btu Q502-Btu Q503-Btu Q505-Btu Q506-Btu N500-% 0.00E-01 0.00E-01 0.00E-01 0.00E-01 0.00E-01

506-Btu D606-\$ H001-Hr 0.00E-01 0.00 0.00

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#### 2 AUG 79 22:30

#### SDAR SYSTEM TASK LIST

- 1 Data Tare Change
- 2 Real Time Data List
- 3 List Recorded Nata
- 4 Change Constants
- 5 Reset System Clock
- 6 Return To Data Collection Program

nter the task number to be executed >3 ECORDED DATA LISTare starting Date/Time 2 AUG 79 18:05:00 are ending Date/fime 2 AUG 79 19:10:00 ist data from this tape?(Y/N) >N ATA TAPE CHANGErive #1 Take Change - Are you sure?(Y/N) >Y eady for tape chasse - Type "f" when done.>f AIT are starting Data/(ime 1 AUG 79 18:05:00 are ending Nate/Time 1 AUG 79 19:10:00 ist wata from this tape?(Y/N) >Y nter starting Date(DD-MMH-YY) >1-AUG-29 id Date - Example: 21-JUN-79 mter starting Date(DD-MNH-YY) >01-AUG-79 AIT nter ending Date(DD-MMM-YY) >01-AUS-79 AIT

NOTE: This sequence illustrates the insertion of a previously recorded data tape for extraction of data for system analysis.

1 AUG 79 18:05:00 Gean number- 1

400/CH08 T401/CH09 T402/CH10 T403/CH11 S400/CH12 S401/CH13 W40G/CH14 93.9 F 92.9 F 122.7 F 122.5 F 0.0 S 0.0 S 0.0 GPM

500/CH15 T501/CH16 T502/CH17 T503/CH18 T504/CH19 T506/CH20 S500/CH21 S505/CH22 21.8 F 93.9 F 94.0 F 67.9 F 95.8 F 81.4 F 0.0 S 0.0 S

506/CH23

001-Btu Q100-Btu Q101-Btu Q102-Btu N100-% Q200-Btu 0.00E-01 0.00E-01 -3.35E402 0.00E-01 00.0 3.35E402

400-Btu Q401-Btu Q402-Btu Q403-Btu 0 'E-01 0.00E-01 0.00E-01 0.00E-01

300-Btu U502-Btu 0503-Btu 0505-Btu 0506-Btu N500-% 0.00E-01 0.00E-01 0.00E-01 0.00E-01 0.00E-01 00.0

# TASK 3 - CONT.

0.00E-01 0.00 0.00

Do not forset to reinstall the current data tame

# NOTES: Task 3

- Be careful in selecting the number of real time data scans desired. Since the SDAR data exchange rate is at 300 Baud, the exchange and printout of data can take longer than expected. Once the display of requested data has started it can not be stopped until completed.
- 2. Descriptions of the parameters and channels are provided in Tables 1-3.

# TASK 4 - CHANGE CONSTANTS

## 2 AUG 79 22136

#### SDAR SYSTEM TASK LIST

- 1 Data Tape Change
- 2 Real Time Data List
- 3 List Recorded Data
- 4 Chanse Constants
- 5 Reset System Clock
- 6 Return To Data Collection Program

Enter the task number to be executed >4 W100(Gpm)= 60.00> EP101(Ku)= 11.50> EP400(Ku)= 31.00> W500(Gpm)= 300.00> EP500(Ku)= 15.50> EF504(Ku)= 3.46> EP505(Ku)= 3.80> W505 (Gpm) = 160.00> W506(Gpm)= 300.00> HTCUST(\$/MBtu)= 7.49> CLCOST(\$/MBtu)= 2.00> MININ(Btu/soft) = 20.0Record Intvl(Min)= 59>30

# NOTES: Task 4

- Tables 2 and 3 provide descriptions of how the engineering constants are used in the system performance calculations.
- 2. The recording interval constant may be selected to be from 1 to 59 minutes in <a href="whole minute increments">whole minute increments</a>. See Section 5.1.1 on how the recording interval affects the frequency of tape changes.

# TASK 5 - RESET SYSTEM CLOCK

## 2 AUG 79 22137

#### SDAR GYSTEM TASK LIST

- 1 Data Tape Change
- 2 Real Time Data List
- 3 List Recorded Data
- 4 Change Constants
- 5 Reset System Clock
- 6 Return To Data Collection Program

Enter the task number to be executed >5 CLOCK CHANGE - Enter the new date(DD-MMM-YY) >2-AUG-79 Invalid Date or Time entered - Example: 21-JUN-79 14:31

CLOCK CHANGE - Enter the new date(DD-MMM-YY) >02-AUG-79 Enter the new time in 24Hr clock(HH:MM) >22:45 Clock now reads - 2 AUG 79 22:45:00

# TASK 6 - RETURN TO DATA COLLECTION PROGRAM

## 2 AUG 79 22:45

#### SDAR SYSTEM TASK LIST

- 1 Data Tape Change
- 2 Real Time Data List
- 3 List Recorded Data
- 4 Change Constants
- 5 Reset System Clock
- 6 Return To Data Collection Program

Enter the task number to be executed >6
Returning to data collection program.
Please hang up the modem or place the ON-LINE/OFF-LINE switch in the OFF-LINE position.

## NOTES: Task 6

1. Section 4.2 has further explanation of system problems that can be caused by not hanging up the modem or resetting the lobby display switch.

#### Section 5.0

#### OPERATIONAL INFORMATION

This section provides information considered necessary to achieve continued successful operation of the unit.

# 5.1 Cassette Tape Drive

The tape drive utilized in the SDAR is manufactured by Digital Equipment Corp. as their model TU-58 dual drive cassette unit. This unit is mounted in the SDAR enclosure and requires the use of two tape cassettes. The two tape drive slots are shown in Fig. 4 and are labeled as Drive Unit "O" and Drive Unit "1." Indicator lights are provided to indicate when the tape drive is in an active status, i.e., either reading or recording from tape.

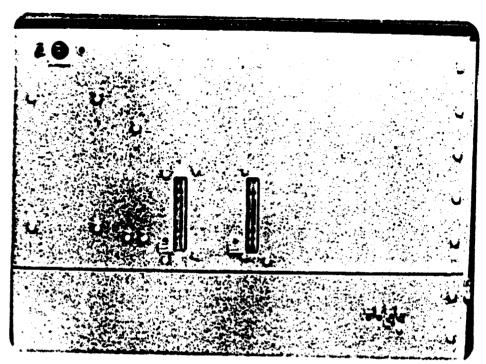
#### NOTE:

DO NOT remove the cassettes while the active indicator lights are illuminated. This may cause data to be lost. However, if removal does occur while the unit is active no physical damage will occur to the unit other than the possible data loss.

The cassette used at Drive Unit O contains the SDAR operating system and the cumulative solar system operating parameters that are periodically updated, averaged, and displayed to the lobby terminal. The cassette used at Drive Unit 1 contains the actual engineering data computed for each recorded scan.

#### NOTE:

The tape cartridge in Drive Unit O should never be removed unless some change in the operating system is considered necessary. If such changes in the operating system are required, contact REMTECH for technical assistance.



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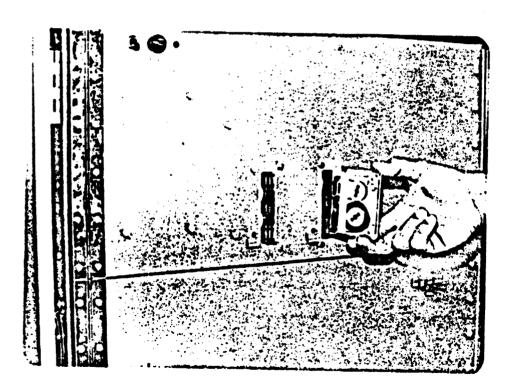


Fig. 4 Illustration of SDAR Tape Insertion and Controls

## 5.1.1 Tape Change Procedure

Periodically, the cassette in Drive Unit 1 must be changed if the engineering data recorded on that tape are to be retained for historical and/or system analysis purposes. The time interval between tape changes is a function of the amount of information that may be recorded on the tape and the frequency with which a recording is made. The cassette cartridges will allow 1880 recordings before becoming full of data.

As described in Section 4.2, the SDAR scans the 23 data channels (Table 1) at one minute intervals and converts these readings to engineering units. In addition, the program performs the 19 system performance calculations given in Table 3, so every minute 42 data records are available for recording. The interval at which data is recorded may be selected to be from 1 to 59 minutes in whole-minute increments.

Then depending on the recording interval selected, the requirements for tape changes will likewise vary. Guidelines for this variation are provided below.

Selected Recording Interval (Minutes)	Time to Fill Cassette Tapes (hours) (days)		
1	31.3	1.3	
5	156.7	6.5	
10	313.3	13.1	
15	470.0	19.6	
20	626.7	26.1	
30	940.0	39.2	
59	1848.7	77.0	

It should be noted that if the recording interval is set at 10 minutes, the data read on the input channel assignments shown in Table 1 will not be recorded but once every 10 minutes even though the SDAR is performing that reading and calculation at one minute intervals. Likewise, the performance calculations of

Table 3 are only recorded every 10 minutes even though the calculation is made each minute. Thus, the selection of the recording interval must allow for both the requirements of the system performance analysis and the requirements for the frequency at which a tape change can be routinely made.

For example, if the recording interval is selected to be every 15 minutes, then replacement of the tape must be made every 470 operating hours or 19.6 days. The SDAR is also programmed to provide visual and audible alarm at the lobby display terminal when the tape is close to becoming full. When the tape becomes 80% full, a warning will appear on the lobby display alerting cognizant personnel of the need to change the tape. An audible beeping alarm will also be made each time the lobby display is updated.

#### NOTE:

If the full tape is not replaced with a new one the SDAR will continue to read the data channels as programmed and perform the indicated calculations, however, the calculations will not be recorded to tape in proper sequence. The replacement tape for the SDAR is the Digital Equipment Corporation, DEC tape II which is a preformated version of the 3M Corp. DC100A tape cartridge.

# 5.1.2 Tape Head and Drive Cleaning

The tape head and drive require periodic cleaning to prevent data errors caused by contamination and oxide build-up. After 250 hours of tape running time or semi-annually, the tape head and drive wheel should be cleaned with a long handled cotton applicator moistened with 95 percent isopropyl-alcohol, fluorocarbon TF, 113 or equivalent. The drive wheel should be rotated to assure cleaning all around the surface.

# 5.1.3 Cassette Cartridge Wear

The tape cartridge is expected to last for 5,000 end-to-end-and back passes. Useful life may vary from tape to tape, however, if errors in the tape data begin

to occur it is recommended that the tape be discarded and a new one utilized.

### 5.1.4 Tape Drive Specifications

- Capacity per cartridge 26/1,144 bytes, formatted in 512 blocks of 512 bytes each
- Read/write 41.7 µs/data bit, 24k bytes/s
- Cartridge life 5,000 minimum end-to-end tape passes
- Average access time 9.3 seconds
- Maximum access time 28 seconds
- Read/write tape speed 76 cm/s(30in/s)
- Search tape speed 152 cm/s (60 in/s)
- Read/write tape speed 76 cm/s (30in/s)
- Recording method Ratio encoding
- Medium DECtape II cartridge with 42.7 m(140 ft) of 3.81 mm (0.150 in) tape
- Track format Two tracks, each containing 1024 individually numbered, firmware-interleaved "records." Firmware manipulates 4 records at each operation to form 512-byte blocks.

### 5.2 SDAR Controls

As shown in Fig. 4, the SDAR enclosure contains several controls and indicator lights in addition to the slots for the tape cartridges. In the upper left corner an on-off switch, fuse and "on" indicator light is provided. On the lower right side of the unit two switches and indicator lights are provided. The "run" indicator light will be illuminated when the "run-halt" switch is in the run position. This indicates that the unit is in a run status and performing programmed functions. If the run-halt switch is moved to the halt position, the program will stop the performance of the programmed functions. The "DC ok"

indicator light indicates that the DC power supply is providing power to the computer circuits.

The "reset" switch allows for the operator to manually "boot" the system. Pushing this switch upward causes the unit to read the operating system tape in Drive Unit O and load the programmed information on that tape to its memory. The reset switch should only be used when it is necessary to replace and/or reload a new operating system to the SDAR. In the event of a power failure, it is not necessary to "reset" the unit, since the SDAR is programmed to "reboot" itself when power is restored.

#### NOTE

It is recommended that only authorized and knowledgeable personnel have access to the interior of the SDAR enclosure. Once installed, none of the control switches should be moved since the changing of these switches can halt the unit in the performance of its programmed instructions.

## 5.3 Terminal/Signal Conditioning Controls

The only controls provided in the terminal/signal conditioning enclosure is the on/off switch for the unit and several voltage indicator lights. When properly operating, all the voltage and power indicator lights should be illuminated. Again, it is recommended that only authorized personnel have access to this unit since if the power is switched off, the system will not perform its prescribed functions.

## 5.4 System Power Requirements

The power requirements of three units to the SDAR system are:

	<u>Voltage</u>	Current Draw (amps)
SDAR Enclosure	110-115	3
Terminal/Signal Enclosure	110-115	3
Video Display	110-115	3

It is recommended that these units be placed on a separate 20 amp circuit which will not be interupted by normal electrical building maintenance. Power interuption will only cause the loss of data for the time interval over which the power is lost. When power is restored, the system will continue to perform its programmed function.

### NOTE

The loss of power for a period of longer than 30 days will require that an operator reset the system clock with the correct time since the internal battery back-up power supply will only maintain the system clock for 30 days.

## 5.5 SDAR Air Filter Cleaning

The SDAR unit contains two fans which provide cooling air to the enclosure circuits by drawing exterior air through it. A porous foam filter is located on the right hand side of SDAR enclosure. Periodic inspection and cleaning of this filter is recommended to maintain an adequate air flow through the system.

#### NOTE

Periodic inspection and cleaning of the SDAR air filter is recommended to maintain an airflow through the system. Inspection of the filter should be made monthly for excessive lint build-up. If excessive lint build-up is noted, filter should be removed and cleaned. Every 3 months filter should be be removed and cleaned.

The filter may be removed by removal of the eleven screws holding the SDAR swing out panels in place. These screws are located along the right hand side of the SDAR panels. Five screws hold the top panel in place and six hold the bottom panel in place. Upon removal of these screws, the two panels can be swung out, allowing access to the filter. Four additional screws should be removed to allow the foam filter to be removed. Upon removal the filter should be washed in warm soapy water, dried and replaced in the enclosure.

### NOTE

While performing the filter inspection, personnel should also inspect the two fans to assure that each is operating. In the event that one is not operating, arrangements should be made to have REMTECH replace it or local on-site replacement can be made. Two fans were provided to allow for back-up in the event that one failed. Specified fan life is 10,000 hrs.

## 5.6 Warranty

All hardware components are warranted against defects in material and workmanship under normal and proper use and in their original, as delivered, unmodified condition for a period of 90 days from the initial delivery date. If found defective by REMTECH within the terms of this warranty REMTECH's sole obligation shall be to repair or replace (at its option) the defective components. If REMTECH determines that the component is not defective within the terms of this warranty, the customer shall pay all costs of handling and return transportation. All replaced components become the property of REMTECH.

All software supplied in compliance with the customer requirements is warranted for a period of 90 days against defects in performing the functions

specified. If found defective, REMTECH's sole obligation shall be to correct the defects to meet the customer requirements.

All work performed outside the scope of the above warranty periods will be at REMTECH's then current labor and materials rates.

# APPENDIX E ACCEPTANCE TEST PLAN, UDRI

## COLUMBUS TECHNICAL INSTITUTE SOLAR ENERGY DEMONSTRATION PROGRAM

FINAL

Acceptance Test Plan

University of Dayton Research Institute

March 5, 1979

Reference Purchase Order No. 18679

Prepared for:

Columbus Technical Institute
550 East Spring Street
P.O. Box 1609
Columbus, Ohio 43216

#### FINAL ACCEPTANCE TEST PLAN

The equipment, inspection, and acceptance testing requirements for the solar system has been specified in the "Specification for Phase V Building" dated April 1977 and incorporating the latest revisions, to insure that all components and work are in accordance with all local, State, and Federal laws, ordinances, rules, and regulations relating to the work and to insure that all components, subsystems, and systems operate in conformance with the design specifications. The detailed acceptance test plan presented herein is based on the final approved working drawings and system control logic. This test plan includes eleven test conditions to functionally demonstrate the systems operational modes of solar energy collection and storage, heating and cooling, system leak detection, and system overheat and freeze protection.

### A. ITEM TO BE TESTED

The item to be tested will include all parts of the operating and control systems. Specifically, the piping system, the pumps, the control transducers, the control actuators, and the system safety and warning components will be tested.

### B. TEST OBJECTIVES

The objectives of the test program are to determine and demonstrate that the system is functionally operable, that it meets the design specifications, and that it is ready for use.

### C. TEST REQUIREMENTS

- 1. All controls and operational components shall be exercised by inducing transducer signals or detector actuation. Functional operability to the design specifications shall be shown in each of the system's operational modes.
- All solar system components, including piping and fittings, solar collectors, storage tank, and heat exchangers, shall be tested in the system at 45 psi,

30 psi for collectors. Leaks, if any, shall be made tight and retests performed until no discernible leaks are found.

2. Approximate flow rates shall be determined by measuring pressure drop through the various components, collectors, absorption machine, purge heat exchanger, etc., throughout the system under all modes of operation to determine that pumps are delivering design fluid flows and that obstructions are not present in the system and to verify that the system control valves are not leaking and are positioned for proper flow.

### D. TEST PROCEDURES

1. The operation of the solar system in each of the operating modes shown in Table 1 shall be demonstrated by falsifying the various temperature transducer signals and actuating the leak detector switch as indicated in Table 2. A description of the solar control system and a schematic for locating components and directions of flow is presented in Attachment 1. The test sequence for the system in the drained and folled configuration is presented below. The test condition comments presented in Table 3 are summary in nature and are not intended to be all inclusive.

## Test Sequence - System Drained (see Tables 2 and 3)

- Set all equipment controls to "OFF."
- Set simulated test temperatures.
- Set building HVAC interface controls.
- Activate the flow alarm switch
- e Check valve status This should be accomplished by visual inspection to insure that the direction of flow is as indicated for the given test condition.

- Check equipment status by:
  - Momentarily switching the equipment controls to "AUTO" mode,
  - Measuring the availability of power to each equipment item.

# Test Sequence - System Filled (see Tables 2 and 3)

- Set all equipment controls to "OFF".
- Set simulated test temperatures.
- Set building HVAC interface controls.
- Activate the flow alarm switch.
- Check valve status This should be accomplished
   by visual inspection to insure that the direction
   of flow is as indicated for the given test condition.
- Set all equipment controls to the "AUTO" mode
- Measure the flow rates and pressures in appropriate segments of the system as a final verification of the operation of the pumps and control system in accordance with the design specifications and that the system is free of obstrucations and that the system control valves are not leaking and are positioned for proper flow.
- Re-set all equipment controls to the "OFF" mode.
- 2. Pressure tests will be performed on all segments of the fluid system after installation is completed to demonstrate the integrity and safety of the system. Pressure relief valves will be replaced with plugs as necessary and each segment of the system will be pressurized to 150 percent of its design working pressure with the exception of the collectors, which will be tested at 100%, or 30 psig. The lack of necessity for makeup of the pressurizing fluid for ten minutes at this pressure shall demonstrate the integrity of the fluid system.

Satisfactory completion of these procedures will be deemed sufficient to demonstrate the adequacy of the system to meet its performance requirements.

SYSTEMS FUNCTIONS DEMONSTRATED VERSUS TEST CONDITION NUMBER TABLE 1

	11				×			×	×	×	×	
	10				×			×	×	×		
Test Condition Number	6				×			×	×			
	8				×	X		×				
	7			×		×		×				
	9	×	×			X						
	5	×	×	×						-		·
	4	×	×			×	×					·
	3	×	×									
	2		·					×				×
	1							×				
100	Demonstrated	Solar Heat Collected	Head Added to Storage Tank	Building Heat- No Boiler Contribution	Building Heat- Boiler Contribution	Building Cooling	Heat Purged	T1 < T2	TO < 40°F	T1 < 40°F	Low Collector Temperature T2 < 38°F	Solar System Leak

TABLE 2 SINULATED TEST CONDITIONS AND COMPONENT STATUS VERSUS TEST CONDITION NUMBER

						Test Con	Condition	Number			
	1	7	3	4	5		1	80	6	10	
Temperature Time Settings											
TO Outdoor Air Temp °F	70	70	75	7.5	o's	75	9	40	3.5	<u>.</u>	-
	65	65	100	230	000	210	, <b>4</b>	2	9	2 6	32
	70	70	08	200	06	190	06		2	3	
stem	70	20	75	7.5	8	08	2	70	20,2	75	75
Return											
14 Heating System	10	70	75	75	28	08	78	78	63	109	109
	7	7	9		-		,	(	•		;
Collector Return	20	20,	2 2	200	3 8	100	Ç 6	2 4	9 4	35	37
Valve Status	,				:		2	3	3	3	5
V. Absorption Machine	ø	a	6	3	6	:			1	1	
				E #		E f	. Y.			. A.	e. 1
	В.Р.	3.5	. 6	0		- a					
V4 Tank (Collector	B. P.	9.0	H	6	F	-			. 4	C &	
			'	)		•			:	•	4
V5 Purge	B.P.	<b>8</b> . P.	B.P.	I	B.P.	B.P.	B.P.	B.P.	B.P.	B.P.	B. P.
		-									
Equipment Status						,					
Tower Pump "E"	OFF	OFF	OFF	NO O	OFF	Z C	08.5	340	30	0	3
Tower Fan	OFF	OFF	OFF	NO O	OFF	Š	9.5	9.00	OFF	OFF	0
Absorption Machine	OFF	OFF	OFF	NO O	OFF	Z O	OFF	OFF	OFF	OFF	OFF
Solar Fumps "A" & "B"	OFF	OFF	S i	NO (	- 6	8	0FF	OFF	ON/OFF	8	8
HOL Water Fumbs 1.6.7.	5	5	5	i.	<u> </u>	er P	<u>z</u>	<u>z</u>	₹	8	ૄ
Alarm Setting/Status		-									
Alarm-Low Collector	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	8
Temperature											
Alarm-Solar System Leak	OFF	<u>z</u>	140	0FF	OFF	OFF	<b>4</b>	140	OFF	0FF	OFF
Building							-		-		
Thermostat Settings-*F	20	70	75	75	75	70	75	75	75	75	75
	<b>4</b> 5	\$	45	45	W/W	. 45	45	41	K/N	N/N	K/N
Building Cold Water	Z Ö	- N	NO O	20	OFF	Ž	ē	ā	140	440	440
Pump		•	:	;		5	5	5	;	;	;
		_		-	-						

CAUTION - review collector manufacturer filling and safety precaution prior to filling and testing. NOTES:

See Table 3 for applicable test condition comments prior to initiating the test. T  $\sim$  through; B.P.  $\sim$  Bypass; M  $\sim$  Modulate.

# TABLE 3 TEST CONDITON COMMENTS

### Test Condition 1

This is a static condition which can also be used to conduct the system pressure tests, after filling, to demonstrate the integrity and safety of the system.

### Test Condition 2

This condition is only used to demonstrate the leak detection system. In the drained configuration the flow alarm switch must be manually activated. In the filled configuration a manual drain valve must be opened, simulating a system leak, to activate the flow alarm switch.

Note: System leaks in actual operation should be isolated and repaired, with caution, as soon as possible.

Review maintenance and safety precautions recommended by the collector manufacturer.

### Test Condition 3

In this test the adjustable control timer must be set to run the Solar Pumps "A" and "B" a minimum of one-half hour. The following must be performed to complete this test condition.

- Adjust timer beyond the minimum setting.
   Note: Solar Pumps "A" and "B" should be "ON".
- Reset Tl to 80°F and T2 to 100°F

  Note: Solar Pumps "A" and "B" should turn "OFF".

## Test Condition 4

The following must be performed to complete this test condition.

Reset T1 to 220°F

Note: Valve V5 should position for full bypass of the Purge Heat Exchanger.

### Test Condition 5

This is a standard solar energy collecting, storing, and building heating mode. There is no requirement for boosting the temperature of the hot water supply to the heating system.

### Test Condition 6

This is a standard solar energy collecting, storing, and building cooling mode using the absorption machine. The following must be performed to complete this test condition.

- Reset Tl to 170°F, T2 to 160°F, and T5 to 170°F.
  - Notes: a. Absorption machine should turn "OFF".
    - b. Tower Pump "E" should turn "OFF".
    - c. Tower Fan should turn "OFF".
    - d. Valve Vl should position for full bypass of the absorption machine.

### Test Condition 7

This is a standard building heating mode with no requirement for boosting the temperature of the hot water supply to the heating system.

## Test Condition 8

This is a standard building heating mode in which the return hot water from the heating system bypasses the storage tank. The temperature of the hot water supply to the heating system is boosted in the boiler to achieve the desired supply temperature, T4.

### Test Condition 9

This is a standard building heating mode as indicated in Test Condition 8. In addition, because of the low outside air temperature, TO, the Solar Pumps "A" and "B" should cycle "ON" for one-half hour every four hours. This operation should be checked by manually advancing the timer through at least two complete cycles.

### Test Condition 10

This is a standard building heating mode as indicated in Test Condition 8. In addition, because of the low outside air temperature, TO, and low collector discharge temperature, T1, the water is continuously circulated through the storage tank until T1 exceeds 60°F. Therefore, the following must be performed to complete this test condition.

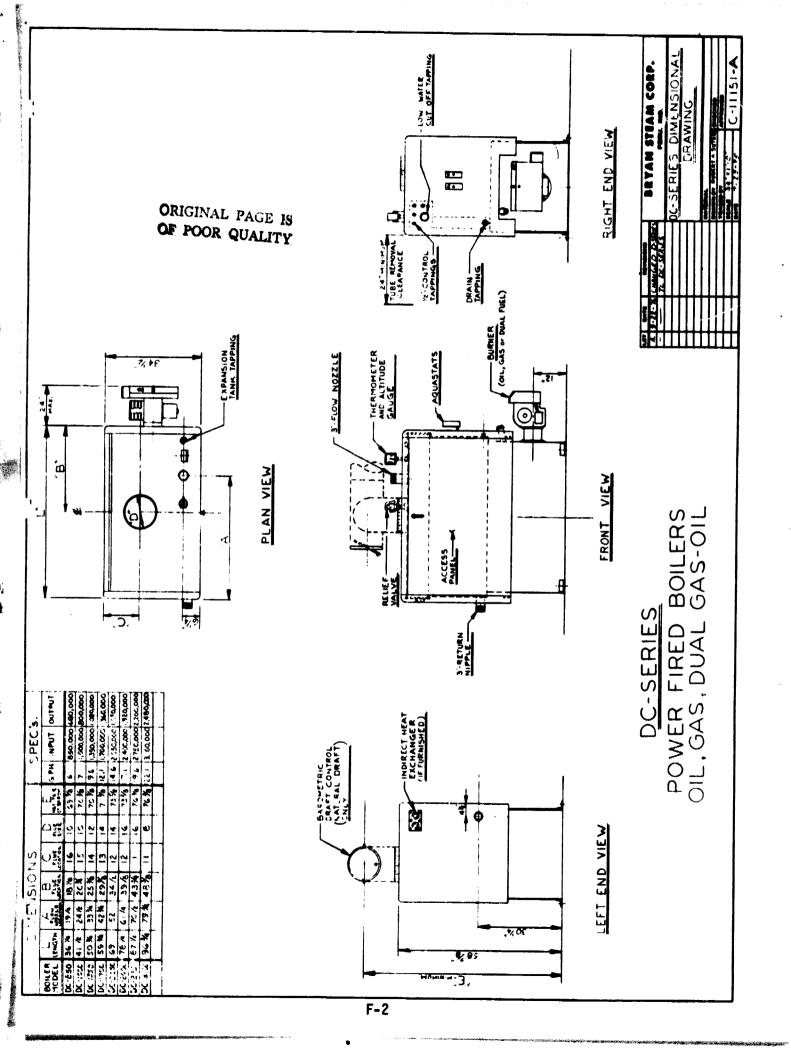
- Reset Tl to 63°F.
  - Notes: a. Solar Pumps "A" and "B" should turn "OFF".
    - b. Valve V4 should position for full bypass of the storage tank.

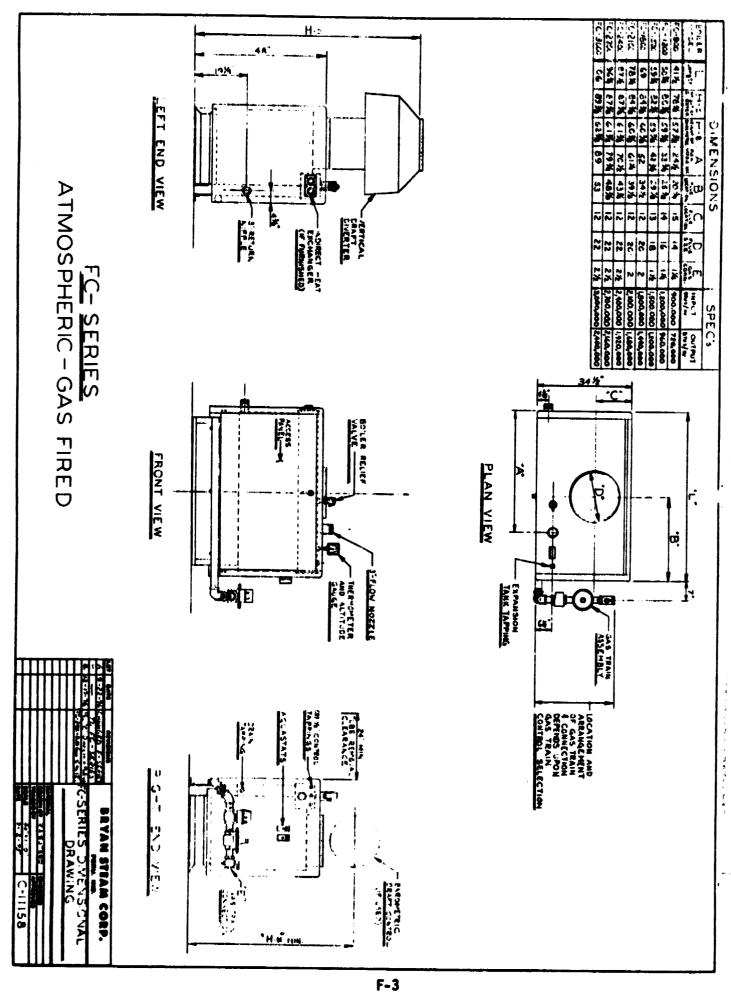
## Test Condition 11

This is a standard building heating mode as indicated in Test Condition 8. In addition, because of the low outside air temperature, T0, low collector discharge temperature, T1, and low storage tank temperature, T2, the Low Collector Temperature Alarm should be activated.

Note: If this latter condition occurs in actual operation a manual drain valve must be opened to allow the automatic fill valve to operate and supply city water to the system until this condition is relieved. It should be noted that this action will also activate the Solar System Leak Alarm.

# APPENDIX F VENDOR ITEMS





	The s			ION CO	LD GENE	RATOR			API	PROVAL STAMP			
gagrottegest Hrid	MC DO	NALÓ, CAS	SELL	. & BAS	SSETT								
100	HEAP	Y & ASSOC		DAY	TON		7 1	TOP	APF	ROVE	ROVED BY		
*		HO LOCATION CC			• • • • • • • • • • • • • • • • • • • •		7	HEAPY & ASSOCIATES					
	ORDER	DATE GUOTE	MEN ORS		GUOTOSION A	SCOUNT NO.	┪ ,	By 1	GARUS	Smith !	Smith 120		
	7-15	-77   (	CT-93	39		······································		DATE 8-3/-7/					
		UCKWORTH 617 DILEY			co.								
		ANAL WING			HIO 43	110	1.						
: :	TAG				A98 🗍	21P COB	SHIP WIT	No.					
	ITEM QTY	TEM QTY MODEL CAPACITY FURNE M							119/00/1	TRANE AB	NE ABSORPTION COLD		
<b>A</b>	A 1 ABSC-01A4-WA-8BCE 35								na 46		RS INCORPORATE		
•	<b>7</b>			i eru	OPERATING	LWF		PD. FT.	PASSES	THESE ADV	Anced Features:		
W		SECTION EVAPORATOR	1	85	55	45	.0005	.0005 20 8					
+		ABSORBER	I	300	85		.0005	22	4	]			
•		CONDENSER	1	70	192	180	.0005	-	2	4	TO START AND E WITH COOLING		
A		CONC (H.W.)		<u> </u>	WATER TEMP	<del></del>	PRESSURE	SHUT-0 FF	<del> </del>	WATER T	EMP ERATURE		
<b>A</b>						DVALVE			MACHINE	AS LOW AS 55° F			
Ñ.		CONC (STM)	-	e/HR					MEAT				
<b>&gt; &lt;</b>	LA CROSSE USE ONLY STROKE							DEGREES ROTATION 2 UNMATCHED PUMP A					
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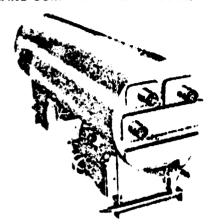
FILE: TRANE REFRIGERATION PRODUCTS LIQUID CHILLERS-ABSORPTION Cold Generator Model C Submittal

ABSC-S-45

FEBRUARY, 1976

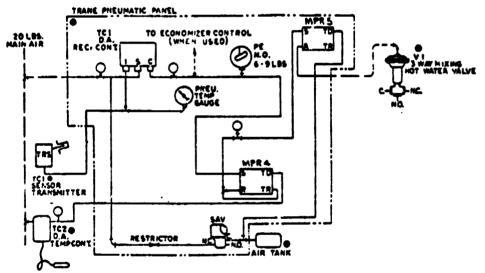
THE TRANE COMPANY - LA CROSSE, WISCONSIN 54501

COMMERCIAL AIR CONDITIONING DIVISION



## ABSORPTION COLD GENERATORS" MEDIUM TEMPERATURE HOT WATER MODEL ABSC

PIPING AND PNEUMATIC CONTROL

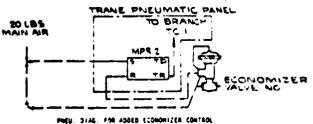


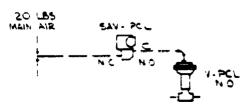
### PNEUMATIC DIAGRAM FOR STANDARD CONTROL INCLUDING DEMAND LIMITER

TOT - DIRECT ACTING PECS: VER/CONTROLLER TOO - GLARCT ACTING TERPERATURE COMPROLLER TRO - TEMPERATURE CENSUR - TRANSPITTER SAVI - SQUENOIO AIR VALVE

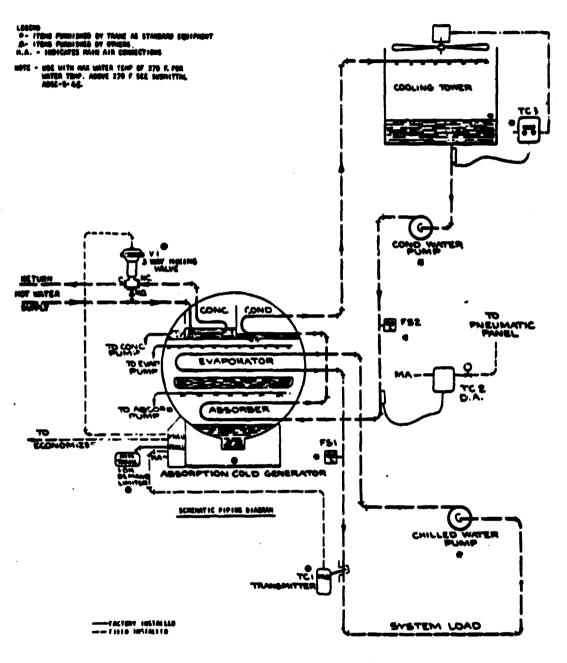
SHAT - SOCRATIO AFRIVACE
PE - PREUMATIC ELECTRIC SHITCH
HARS - MULTI-PURPOSE RELAY COM PRESSURE DELECTORY
HARR - ROLERSING MULTI-PURPOSE RELAY
HARR - MULTI-PURPOSE RELAY CHARACTERIZED MINIMUM PRESSURE LOW PRESSURE SELECTORY

--- FACTORY INSTALLED

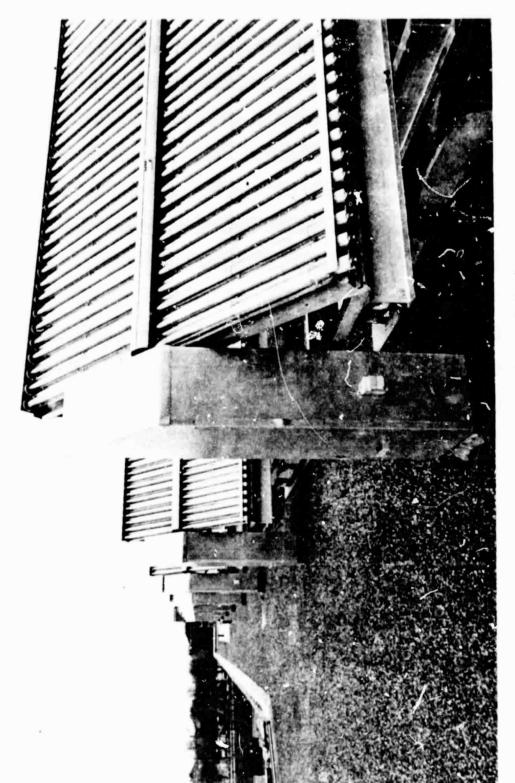




THELL SIAS, FOR ABOUT V-PCL CONTROL

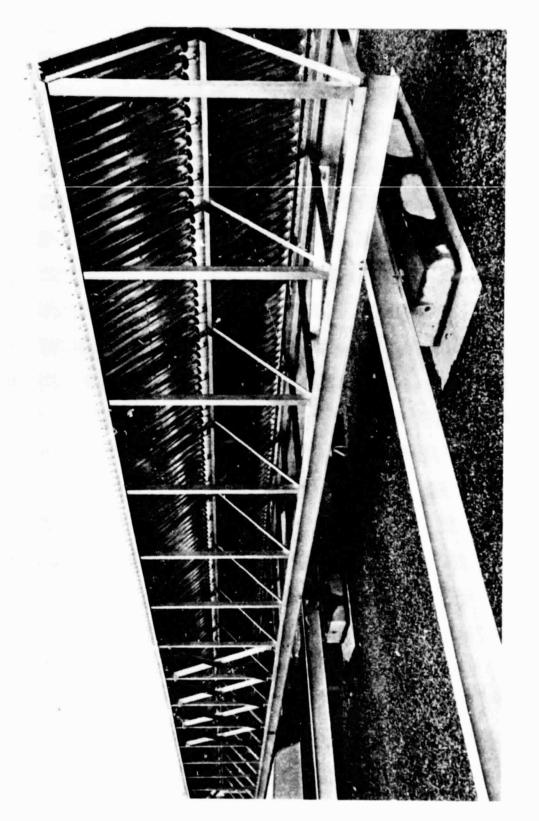


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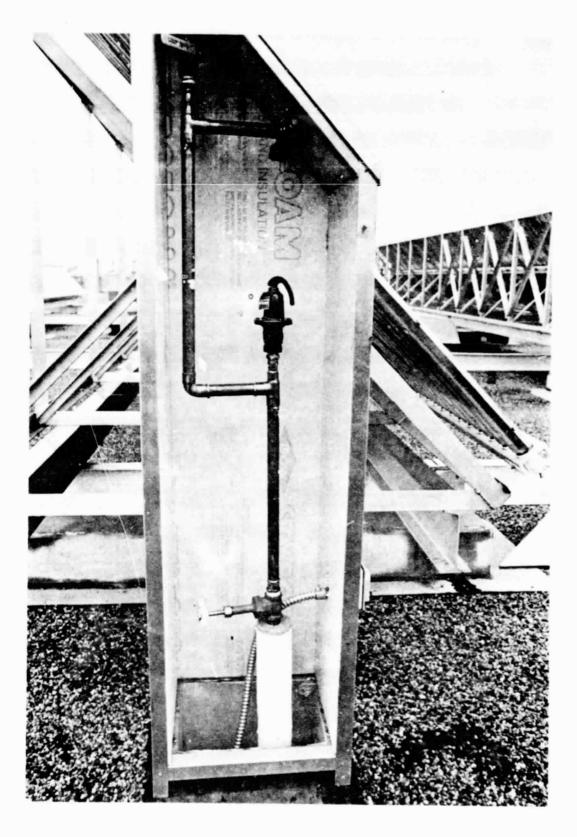
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Solar Collectors with Roof Curbs.

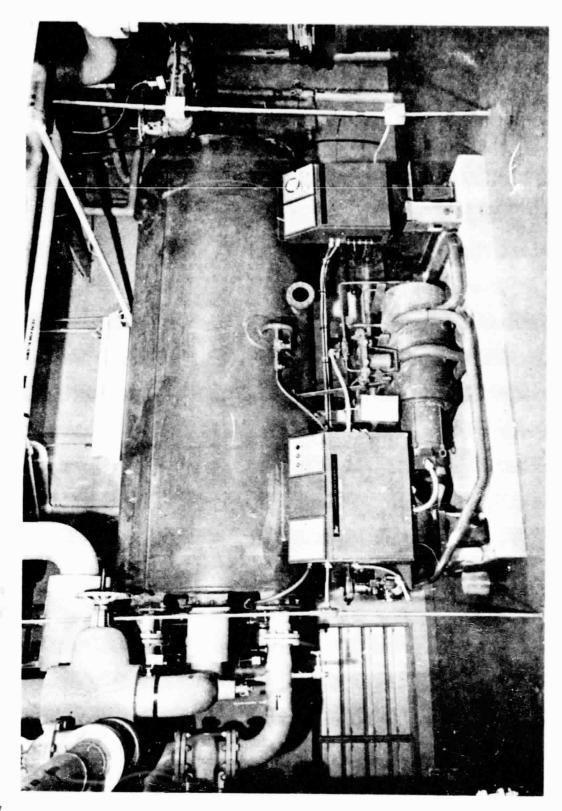


Solar Collector Structural Framework.

Absorption Chiller.

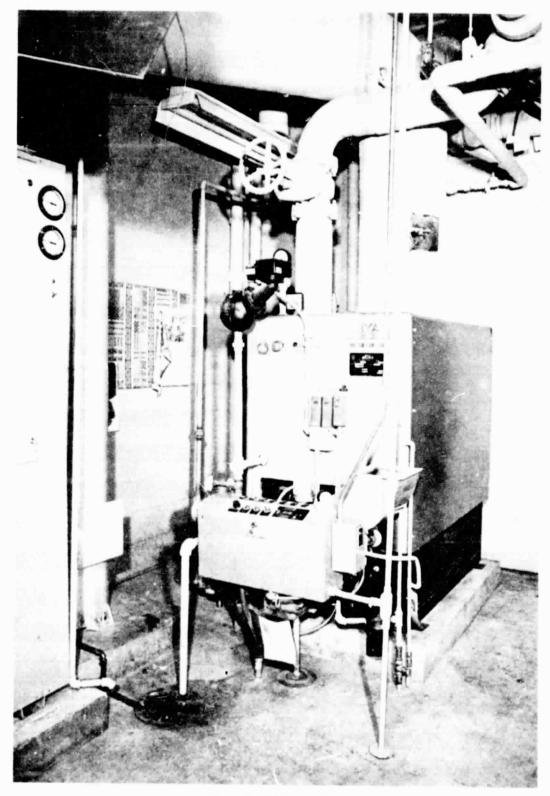


Details of Roof Curb.

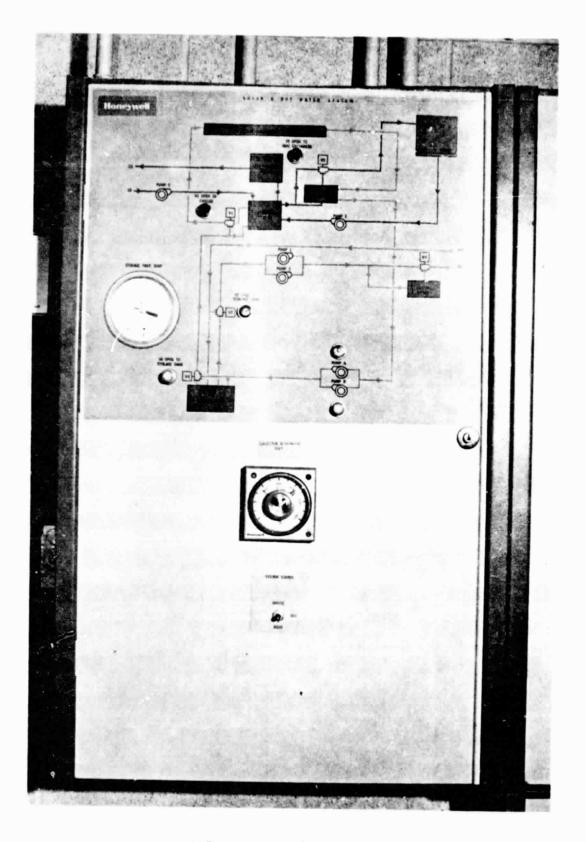


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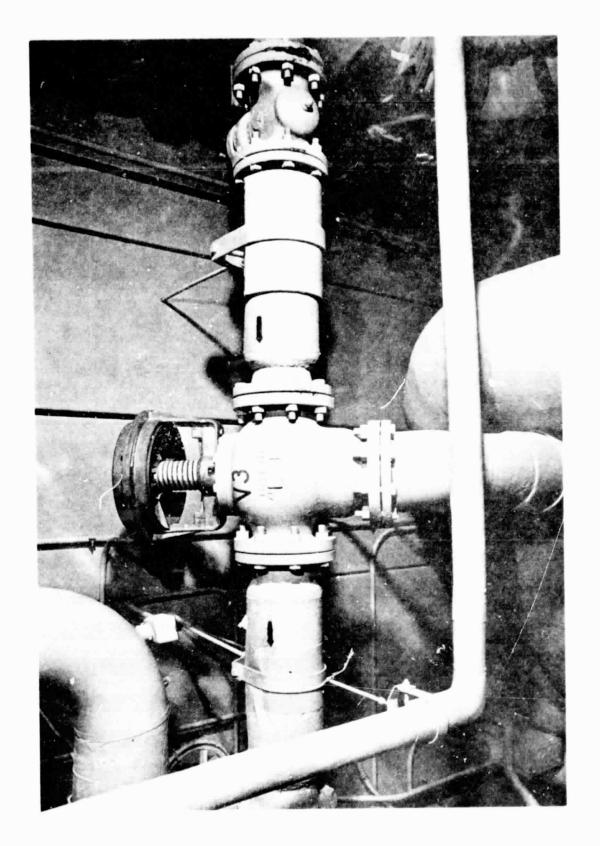
Cooling Tower.



Gas/Fuel Oil Boiler.



Solar Control Panel.



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